

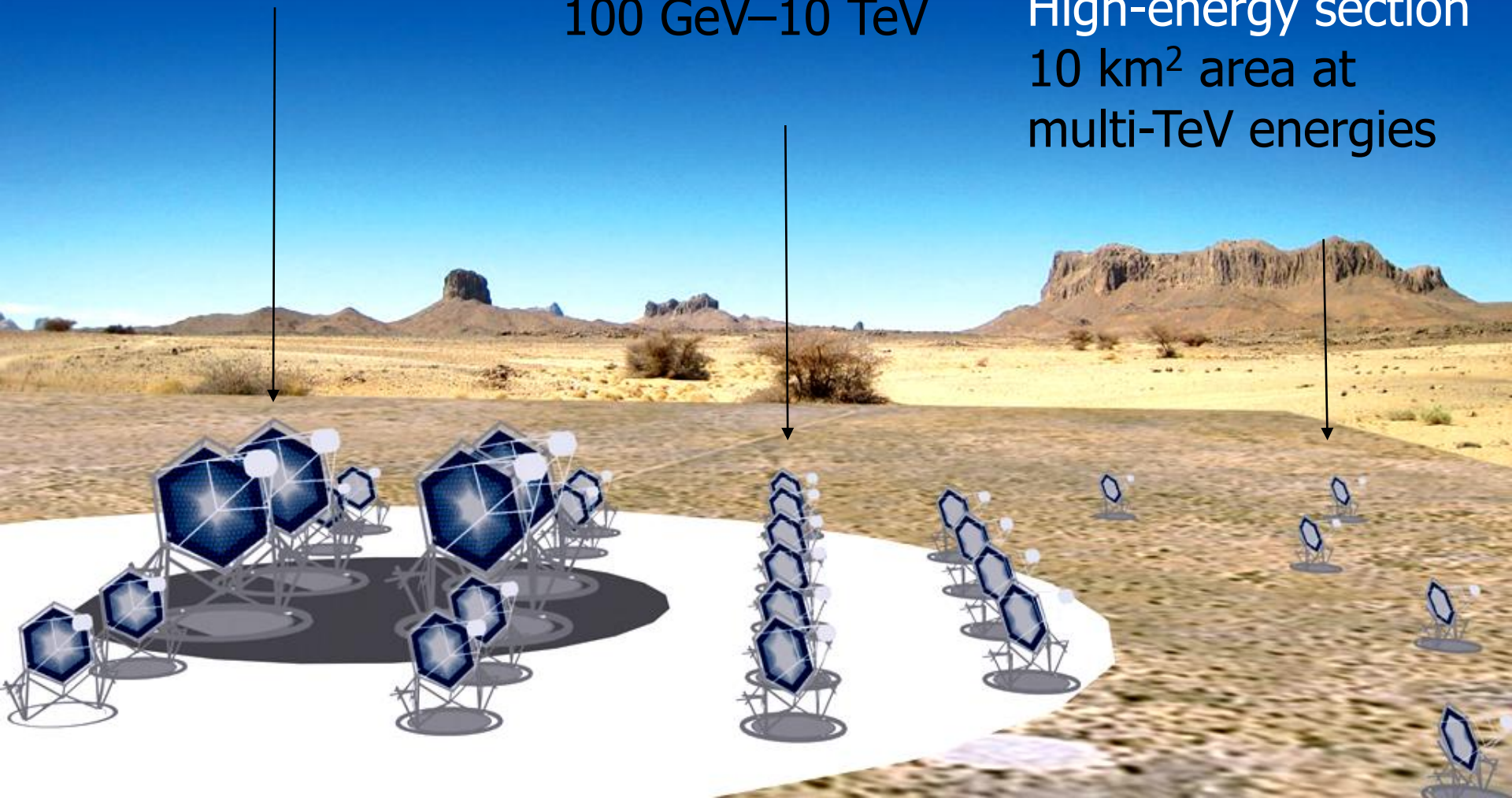
Requirements and Optimisation for the CTA SST sub-system

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Leicester

Low-energy section
energy threshold
of 20-30 GeV

Medium Energies:
mCrab sensitivity
100 GeV–10 TeV

High-energy section
10 km² area at
multi-TeV energies



~23m telescopes

4 - 6° FoV

0.08 - 0.12° pixels

Parabolic/Hybrid f/D~1.2

12m telescopes

7 - 8° FoV

0.16 - 0.18° pixels

Hybrid f/D = 1.35

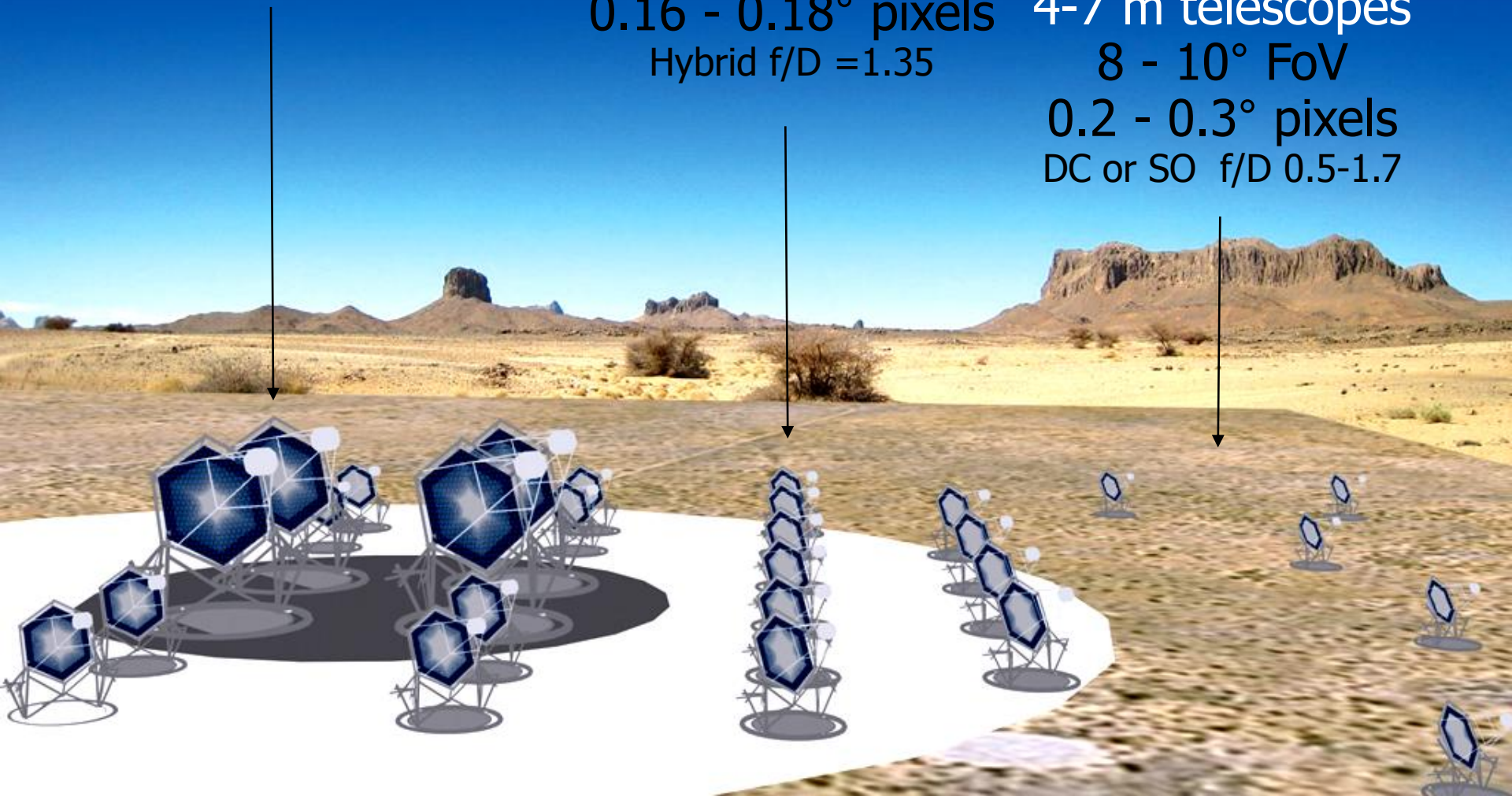
SST

4-7 m telescopes

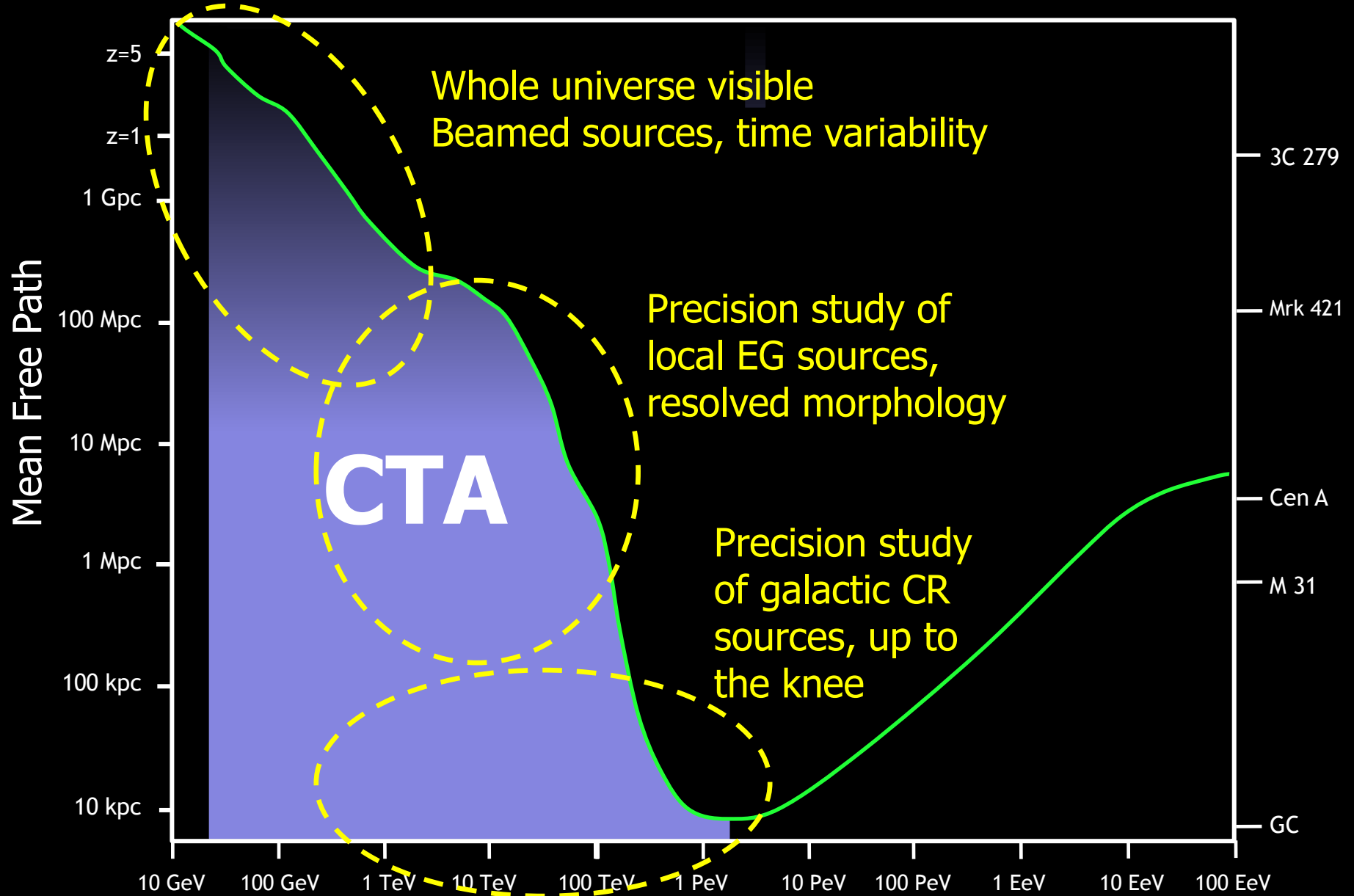
8 - 10° FoV

0.2 - 0.3° pixels

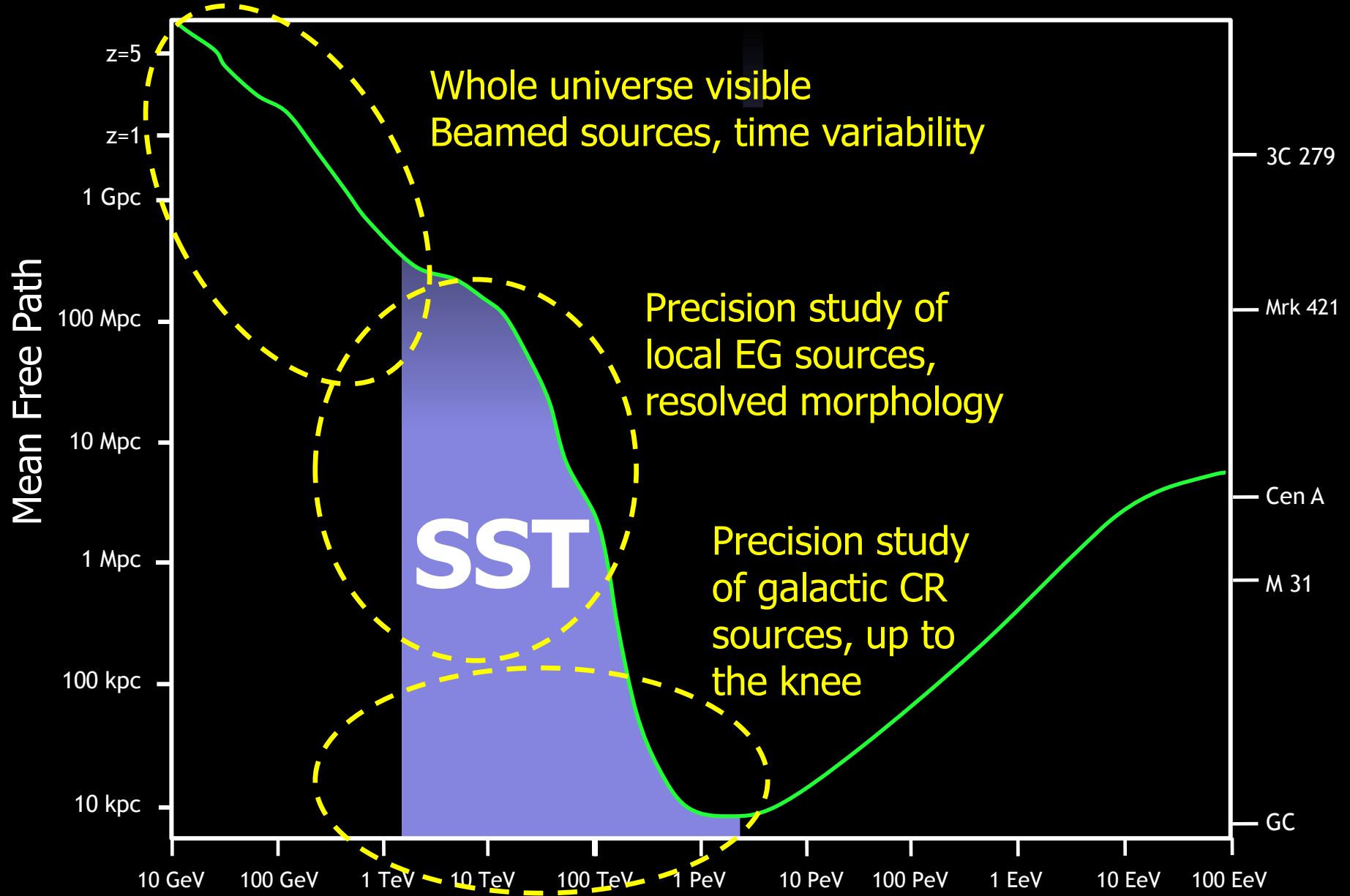
DC or SO f/D 0.5-1.7



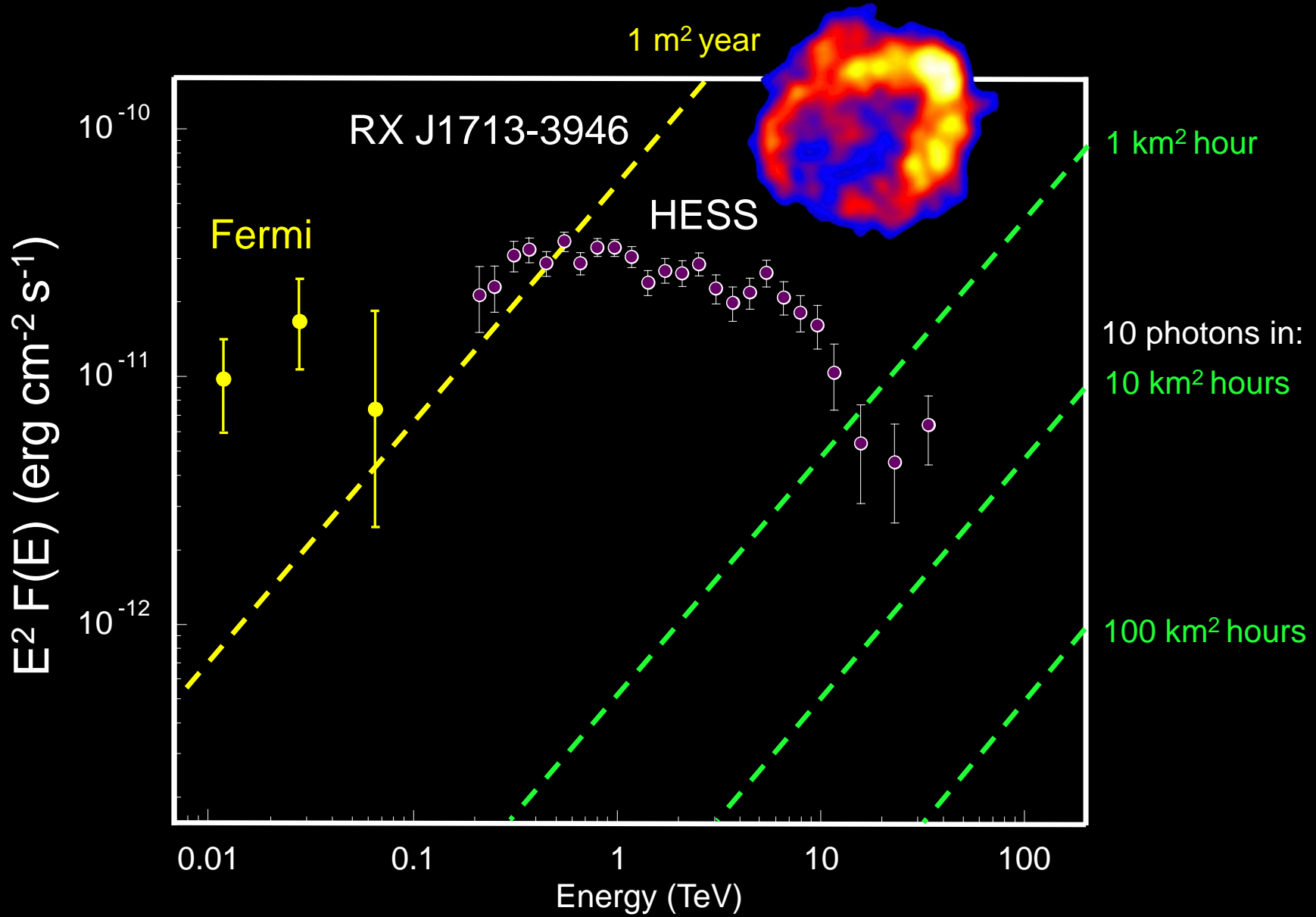
4 The Gamma-ray Horizon



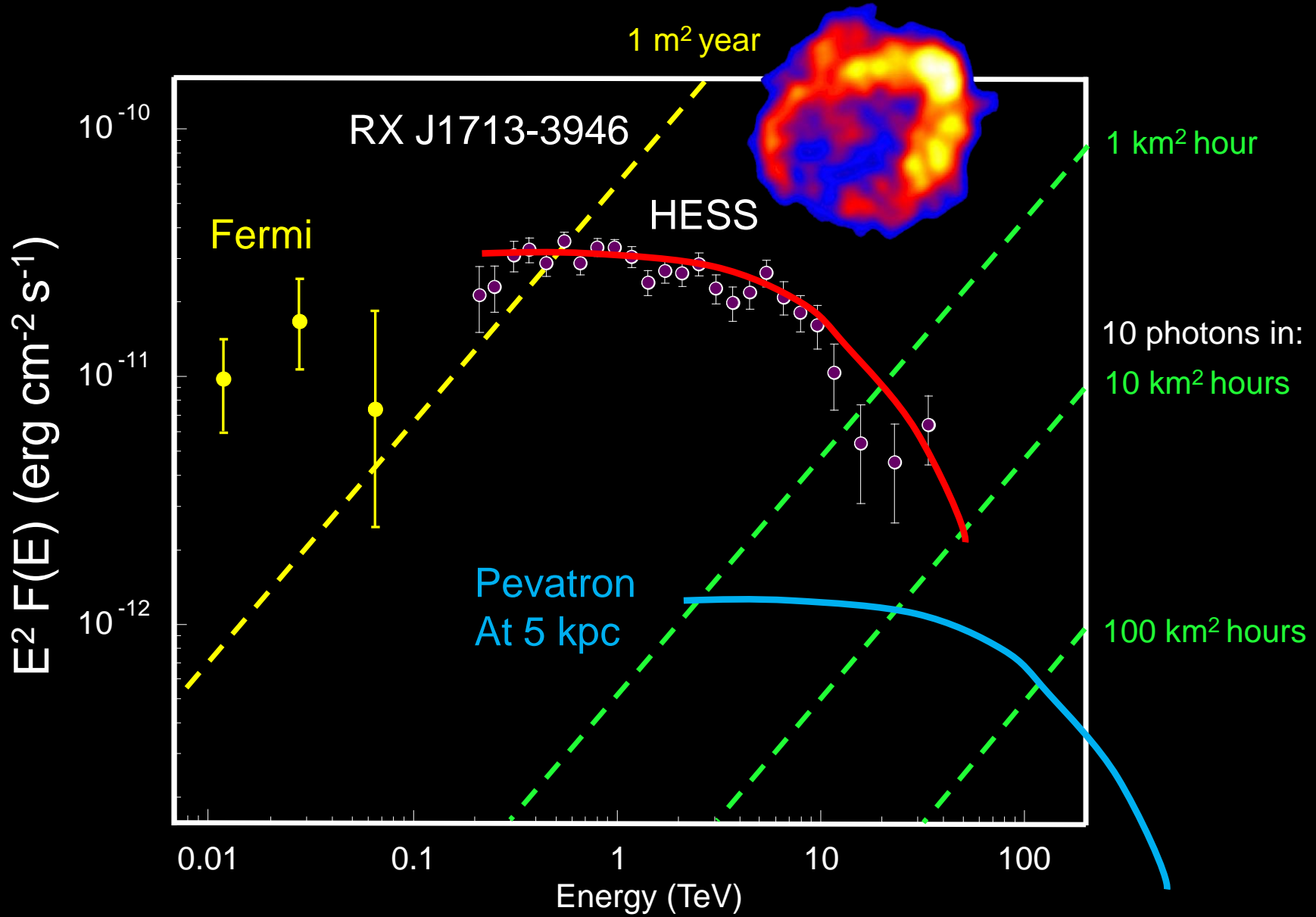
5 The Gamma-ray Horizon



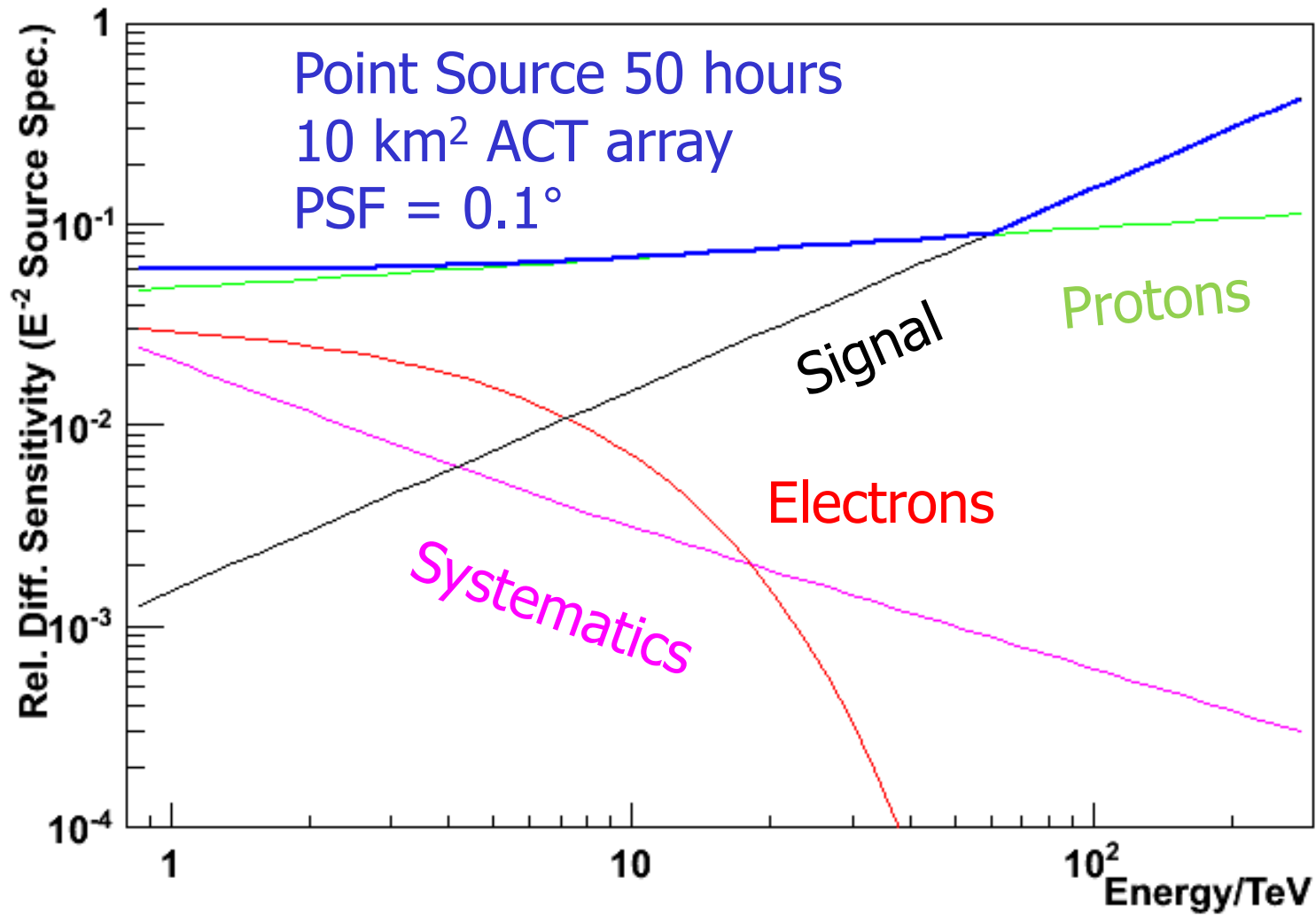
6 Photon Statistics



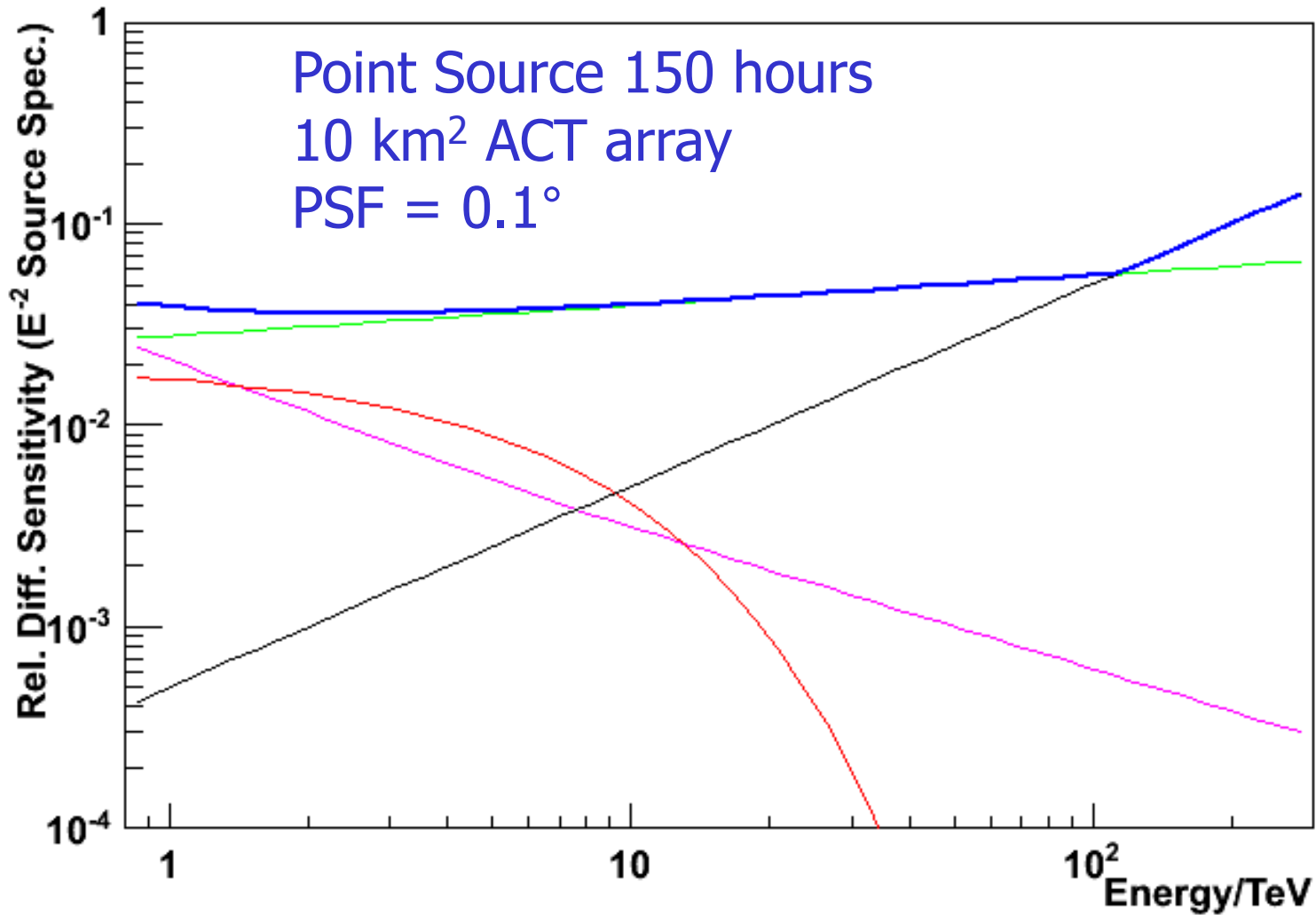
7 Photon Statistics



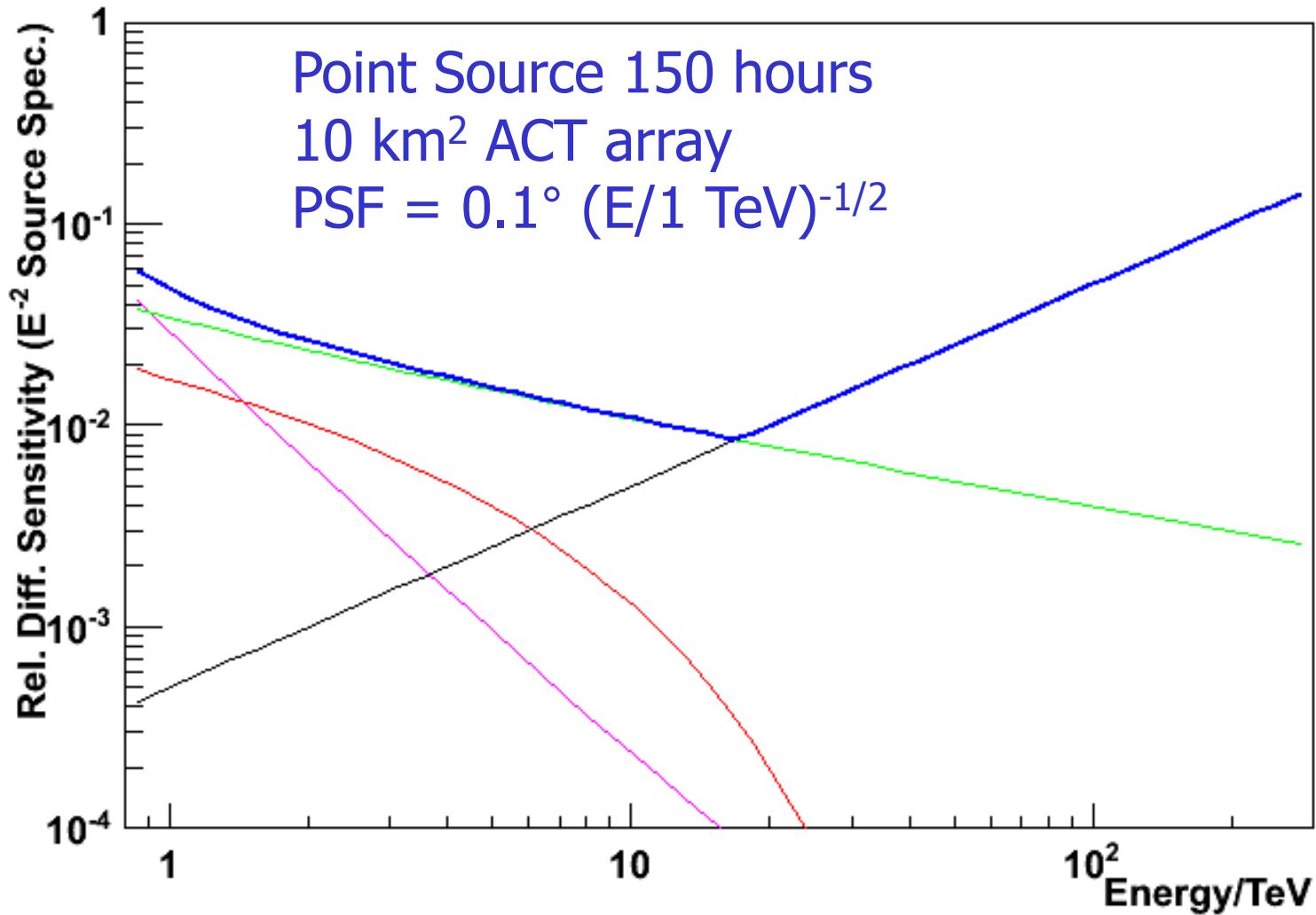
8 Limitations



9 Limitations

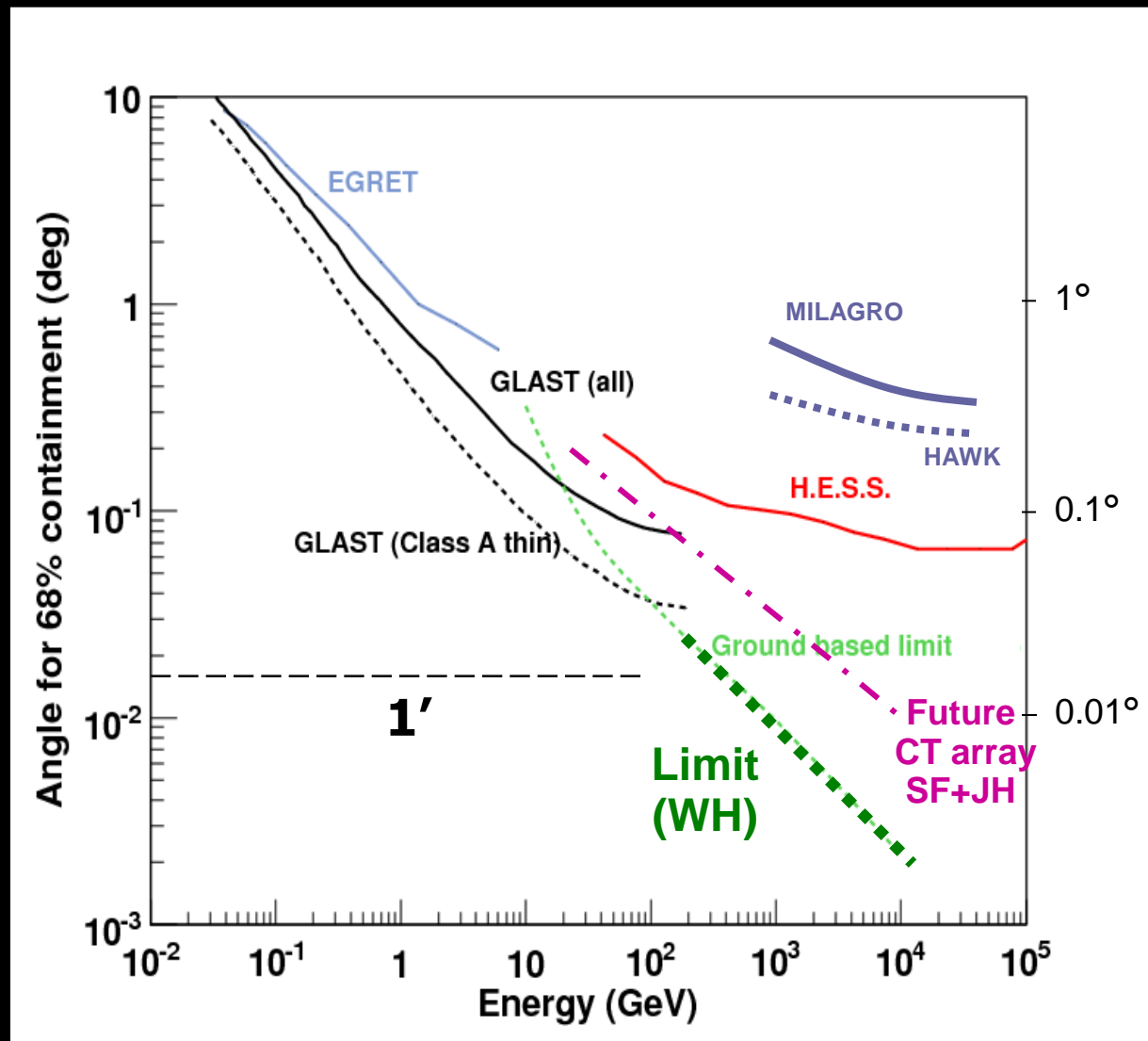


10 Limitations



11 Angular resolution

- $\sim 1'$ resolution achievable with next generation IACT arrays
- Fundamental limit is $\sim 10''$ above a few TeV



12 Resolution

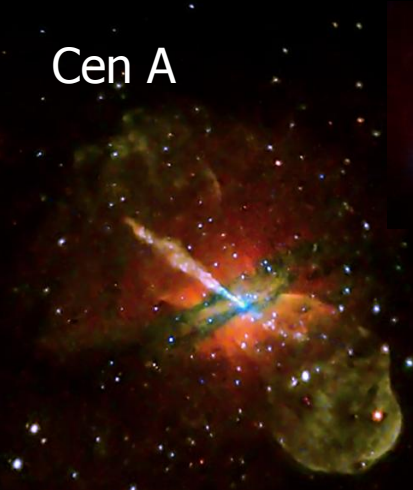
Hydra A



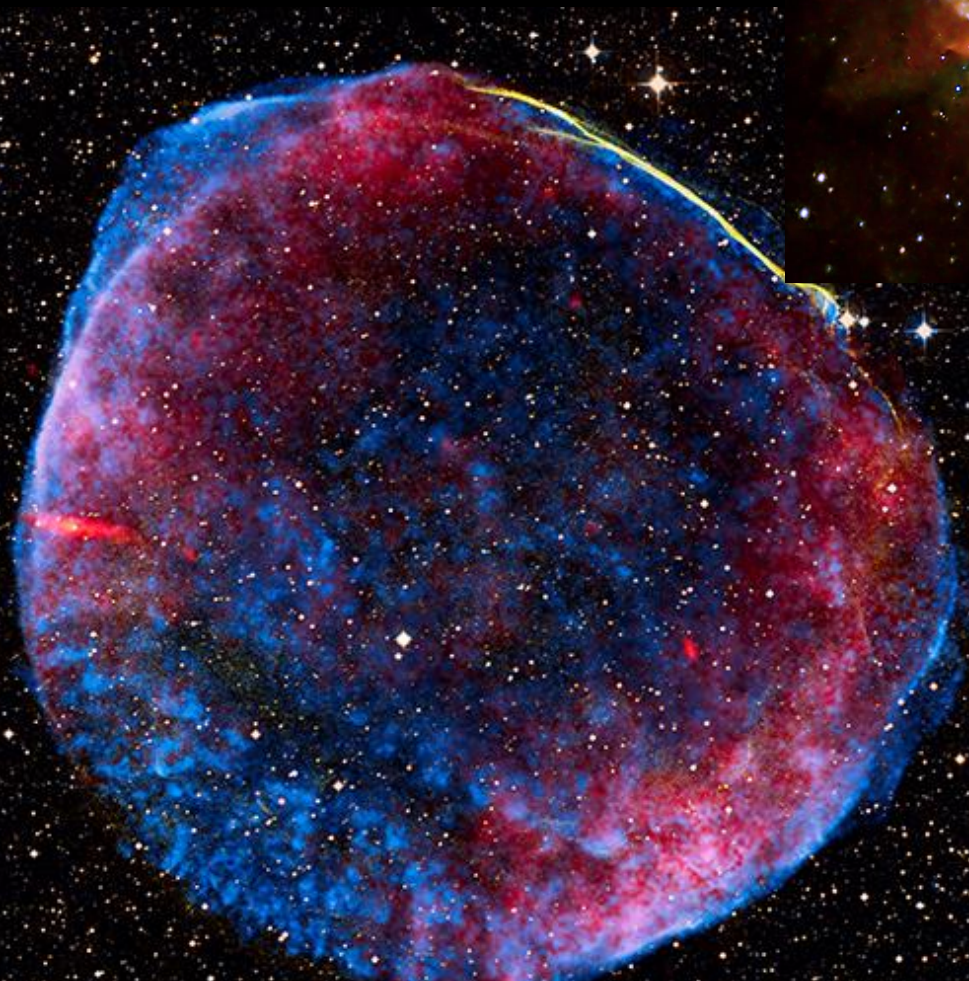
M 82



Cen A



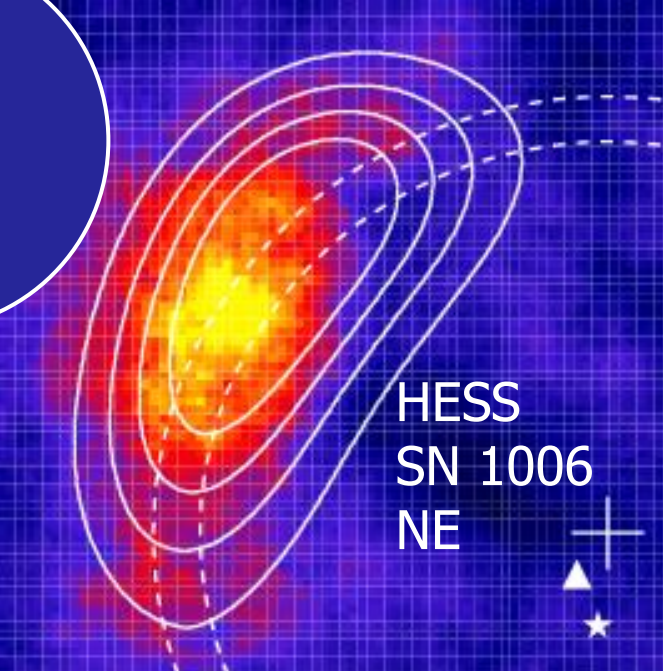
SN 1006



1'

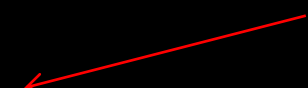
2'

5'

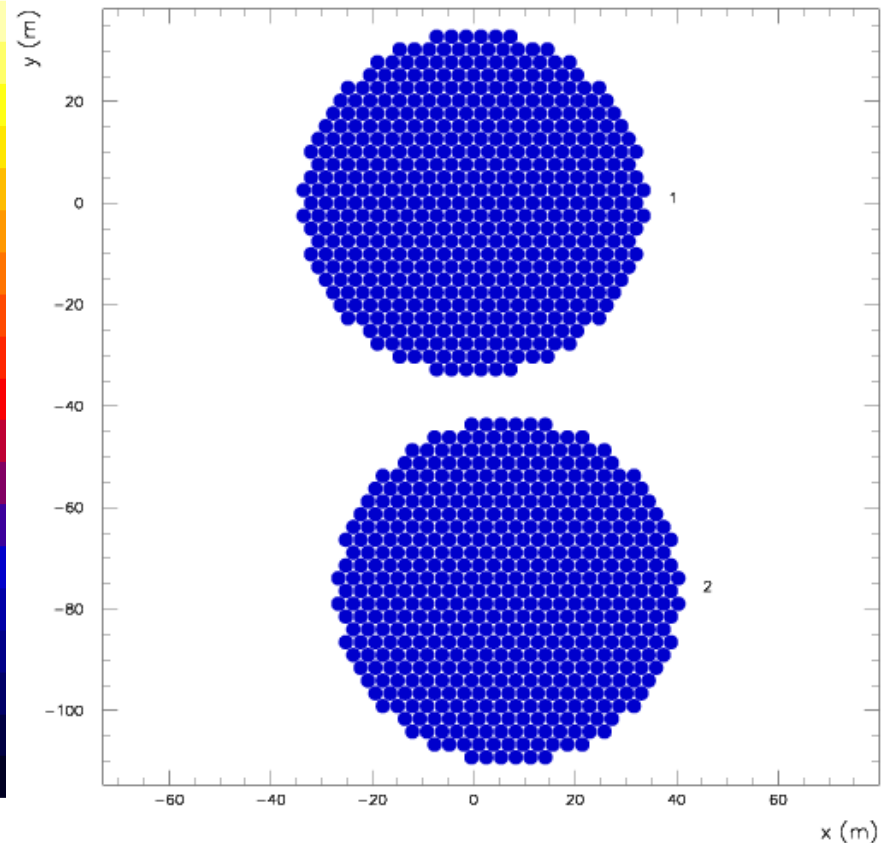
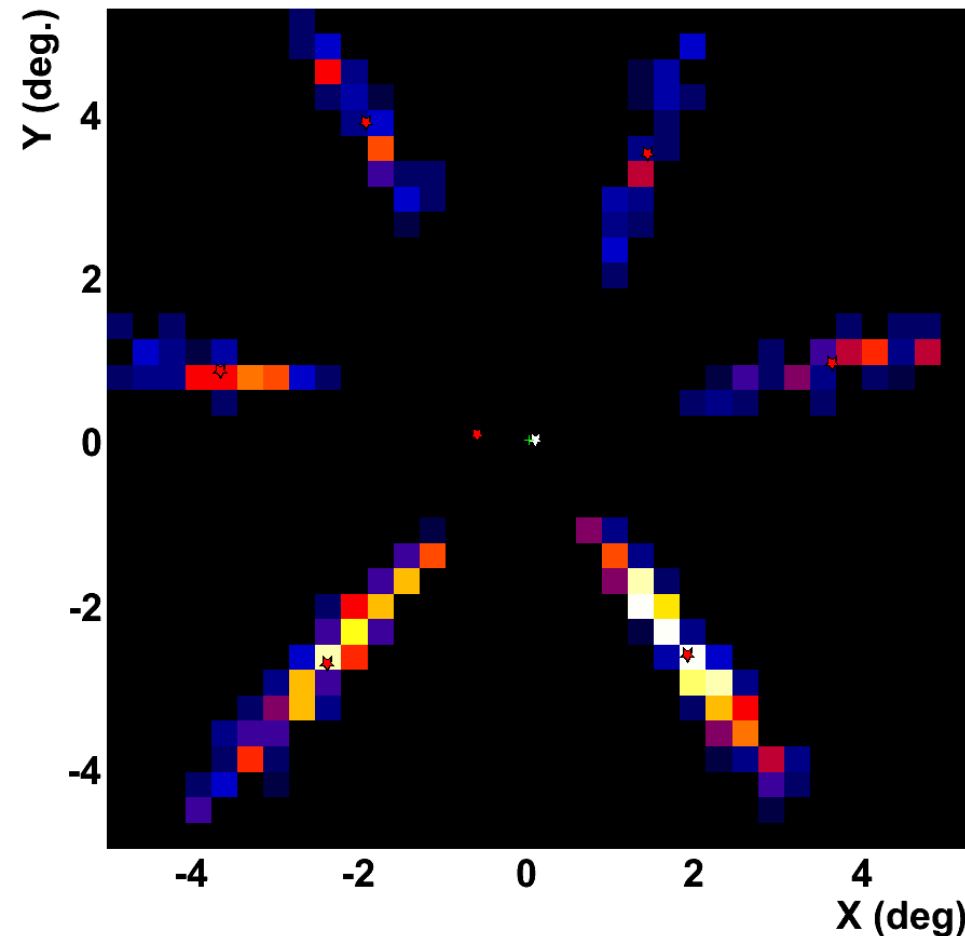


HESS
SN 1006
NE



- Area
 - $O(10 \text{ km}^2)$ at 100 TeV
- Energy Range
 - ~1 TeV to $\gg 100 \text{ TeV}$ 
 - Inefficient for the SST to compete with the MST in the core energy range - aim for SST dominance of sensitivity between 5 and 10 TeV (trigger 1-3 TeV)
 - Maximum energy?
 - ▶ Aim to run out of stats. for ~1 Crab source before saturation
- Implies minimum dish diameter ~3 m (for <150 m spacing)
- Angular resolution / Background rejection
 - As good as possible, BG free at lowest achievable energy (i.e. best sensitivity)

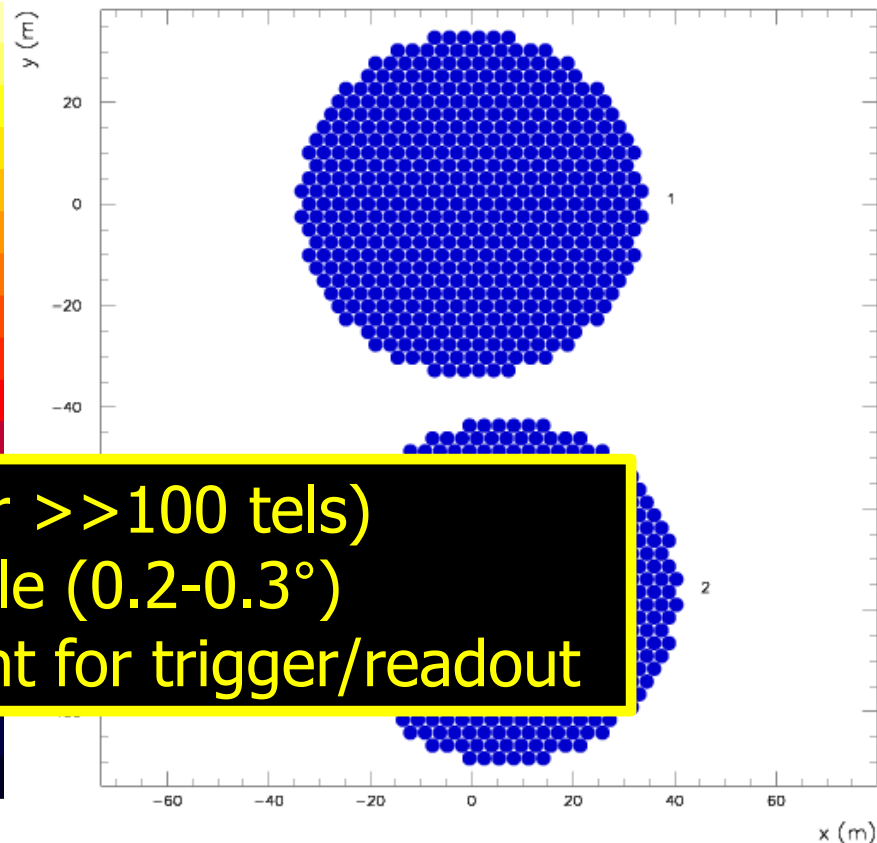
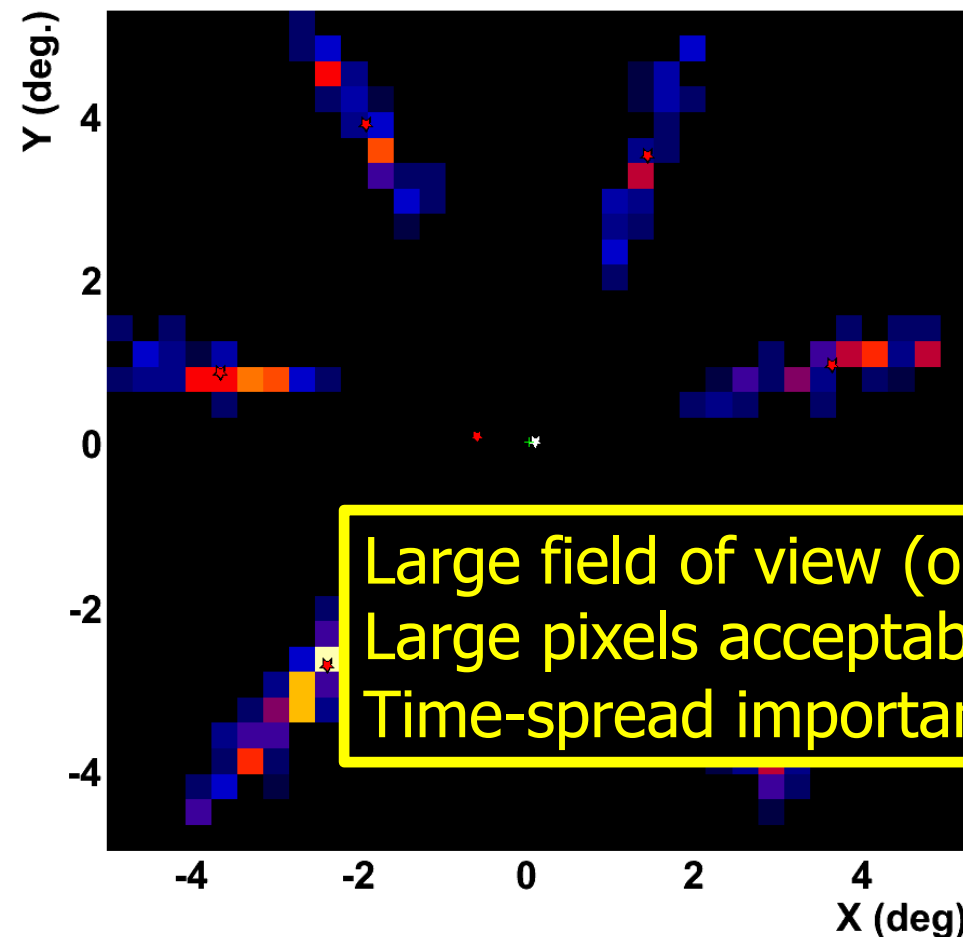
14 Special Considerations



Long, wide, offset, large time-spread images

Examples: Images in six 10° FoV (0.25° pixel) cameras (30 m^2 tels.) $\sim 500 \text{ m}$ from the core of 14 TeV shower + VERITAS movie

15 Special Considerations



Large field of view (or $\gg 100$ tels)
Large pixels acceptable ($0.2-0.3^\circ$)
Time-spread important for trigger/readout

Long, wide, offset, large time-spread images

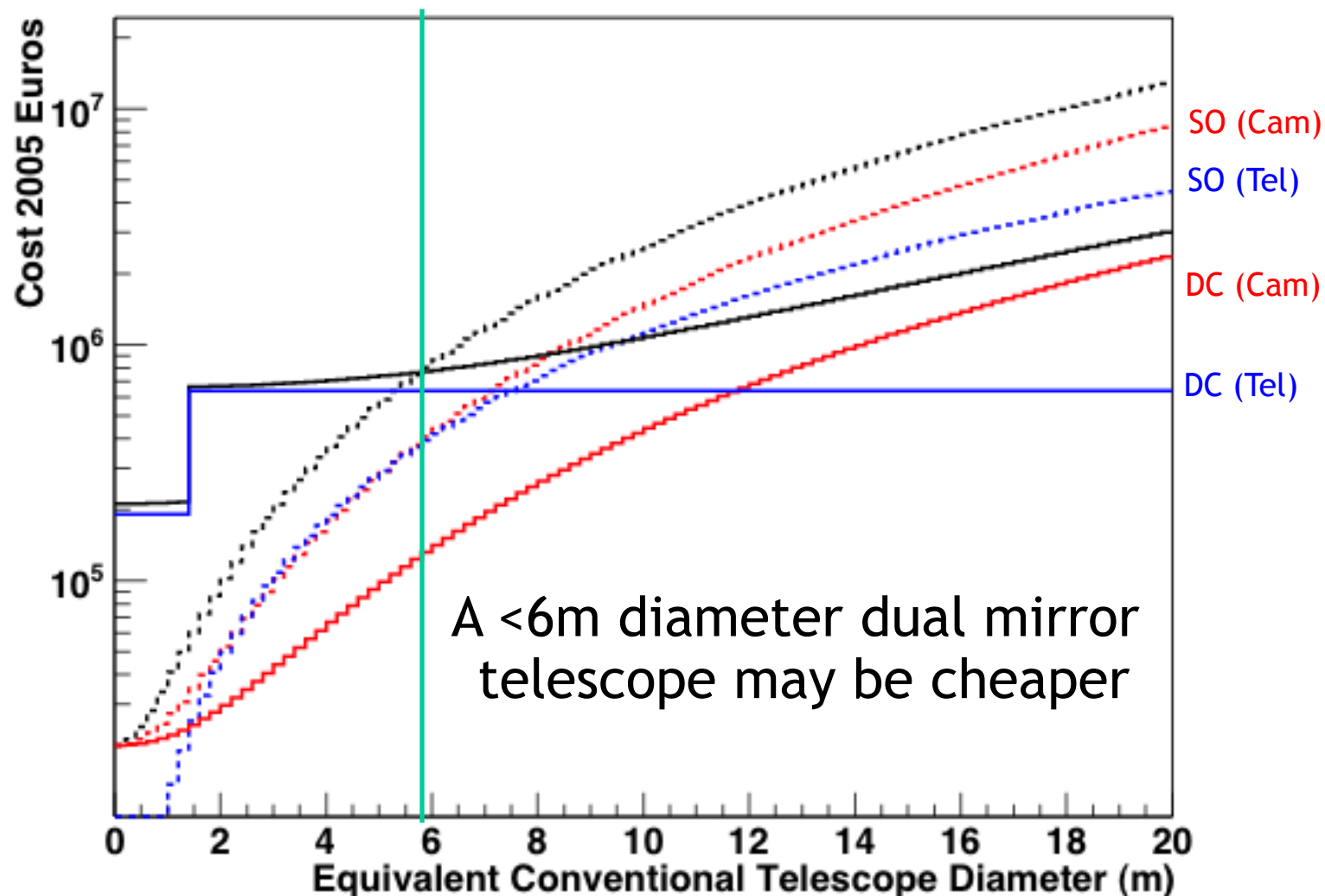
Examples: Images in six 10° FoV (0.25° pixel) cameras (30 m^2 tels.) $\sim 500 \text{ m}$ from the core of 14 TeV shower + VERITAS movie

- Huge phase-space available - start with some attractive solutions:
 - 1) Share MST photosensor/mechanics and (possibly) readout electronics
 - ▶ Scale down primary mirror 12m→7m to get from $0.18^\circ \rightarrow 0.25^\circ$ with reasonable f/D
 - 2) Take plate-scale of cheaper photosensors (5-7mm) and adapt optics to get primary as large as possible (e.g. $f/D \rightarrow 0.5$)
 - ▶ Two-mirror solution or light-cones+SiPMs: ~4m \emptyset

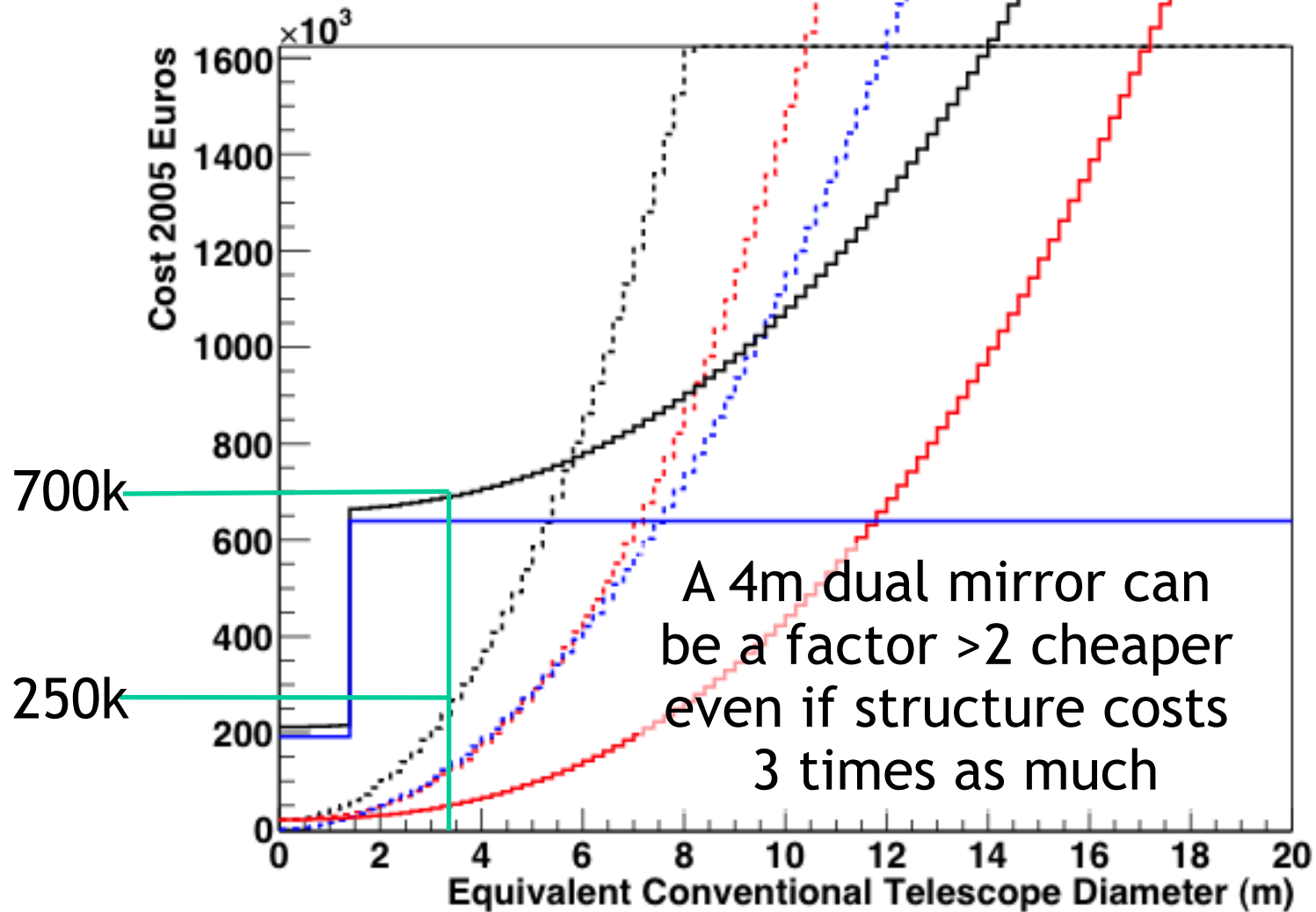
NB: Decision point for 1 versus 2 reflectors – Oct 2011

17 Telescope Cost

Assumes: SO Cam Pixel Cost = $1/3 \times DC$, SO Tel/Mir = $3 \times DC$

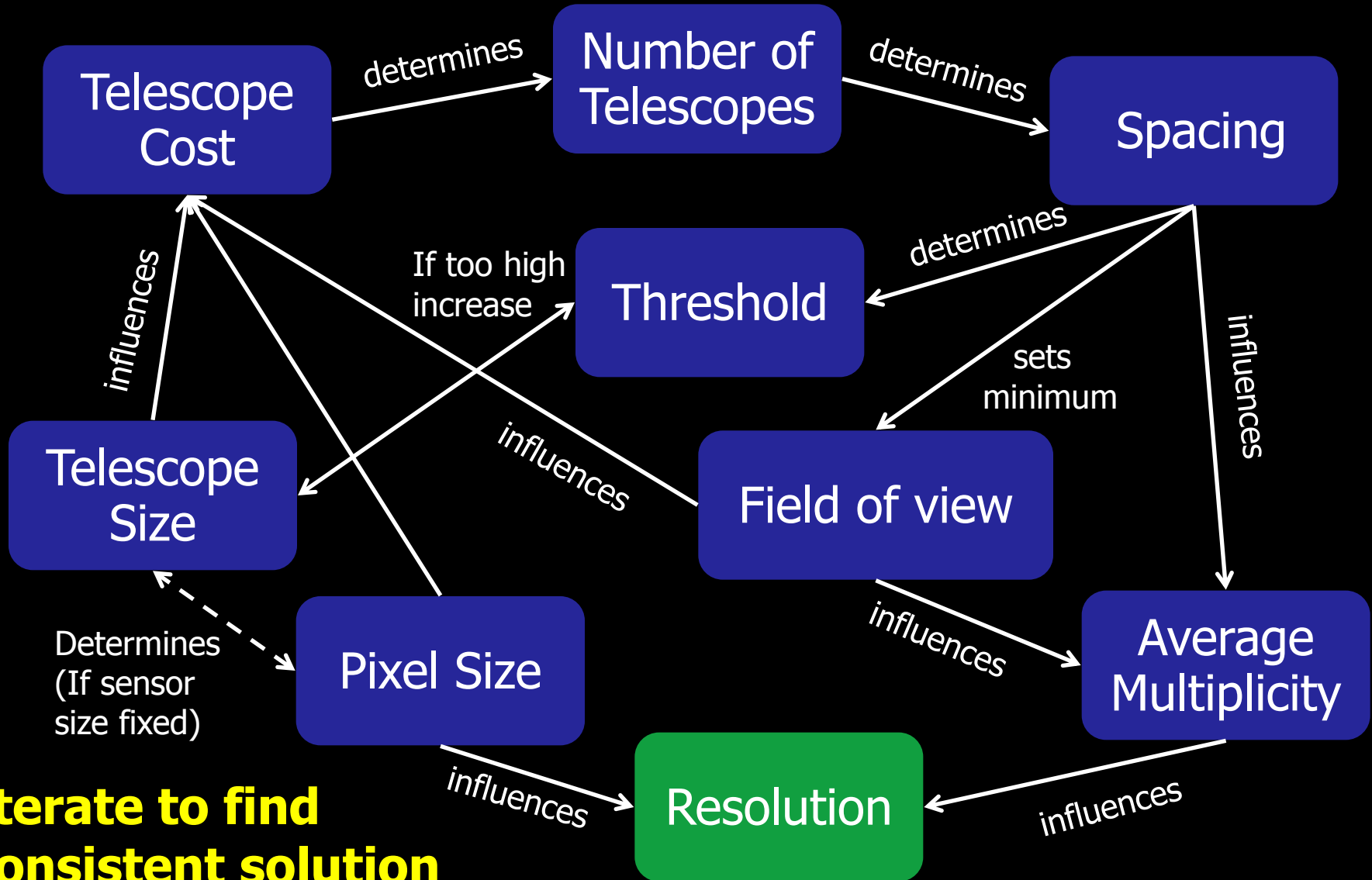


18 Telescope Cost



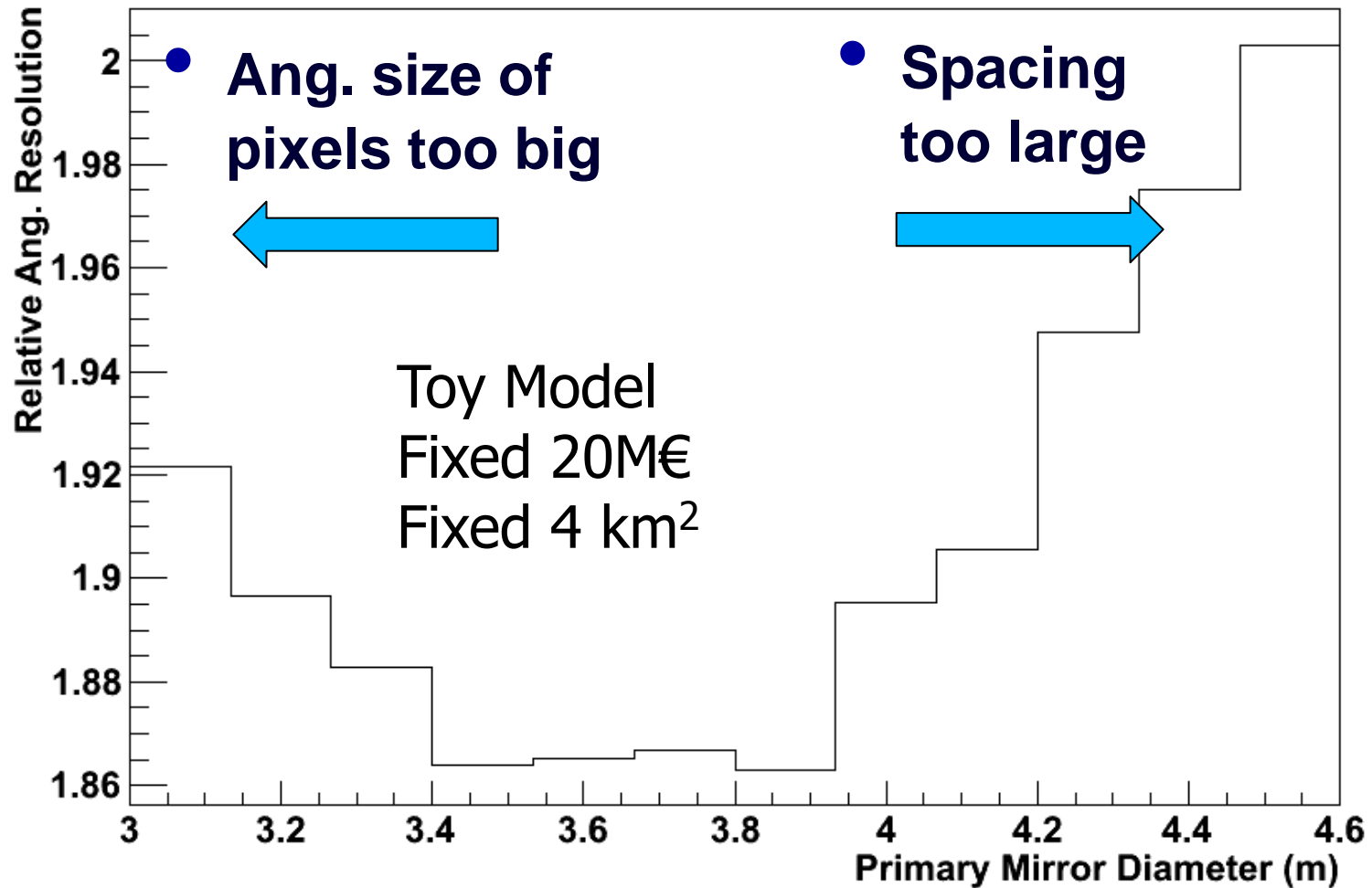
19 Optimisation

For fixed area & array cost

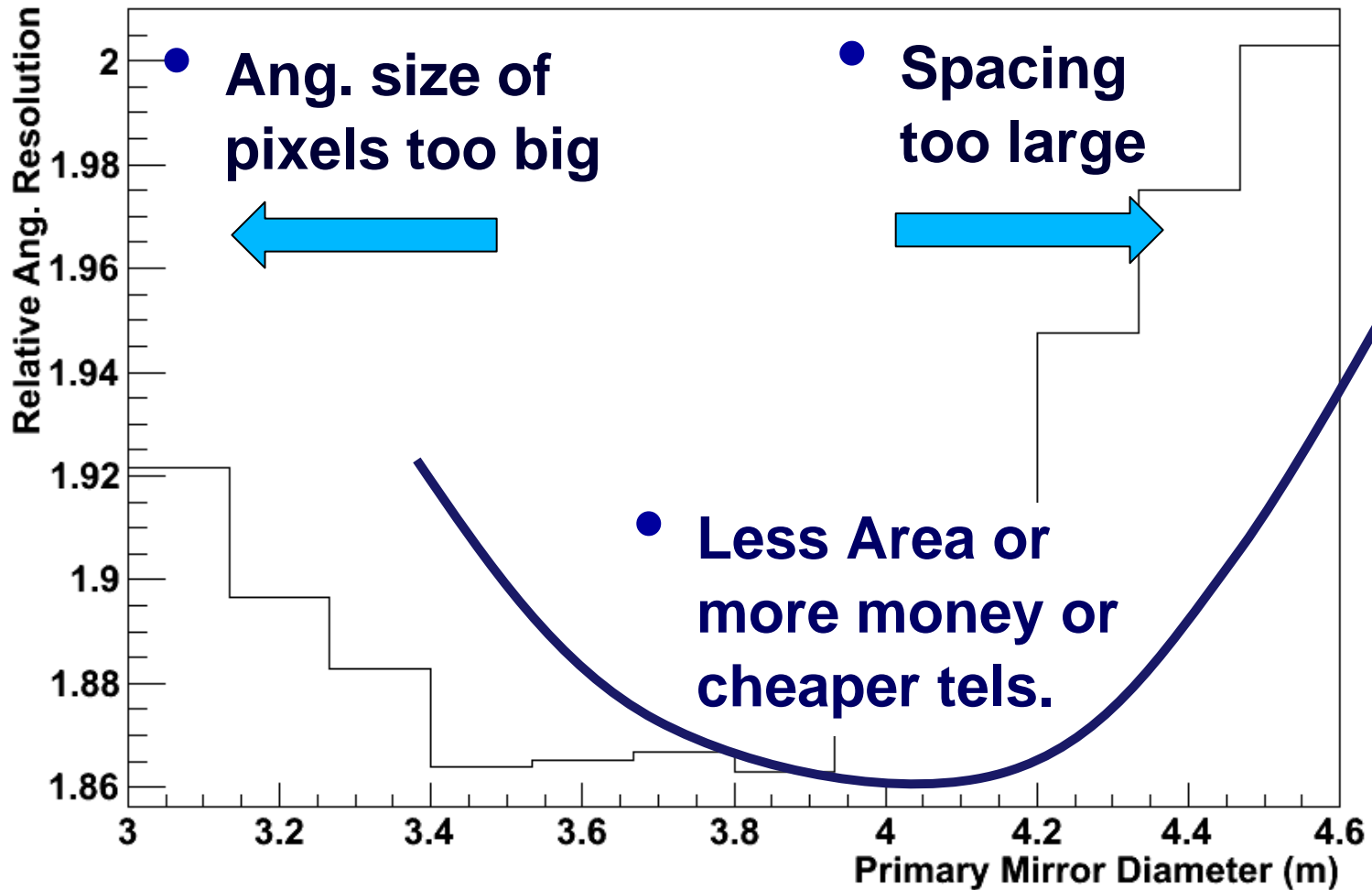


Iterate to find consistent solution

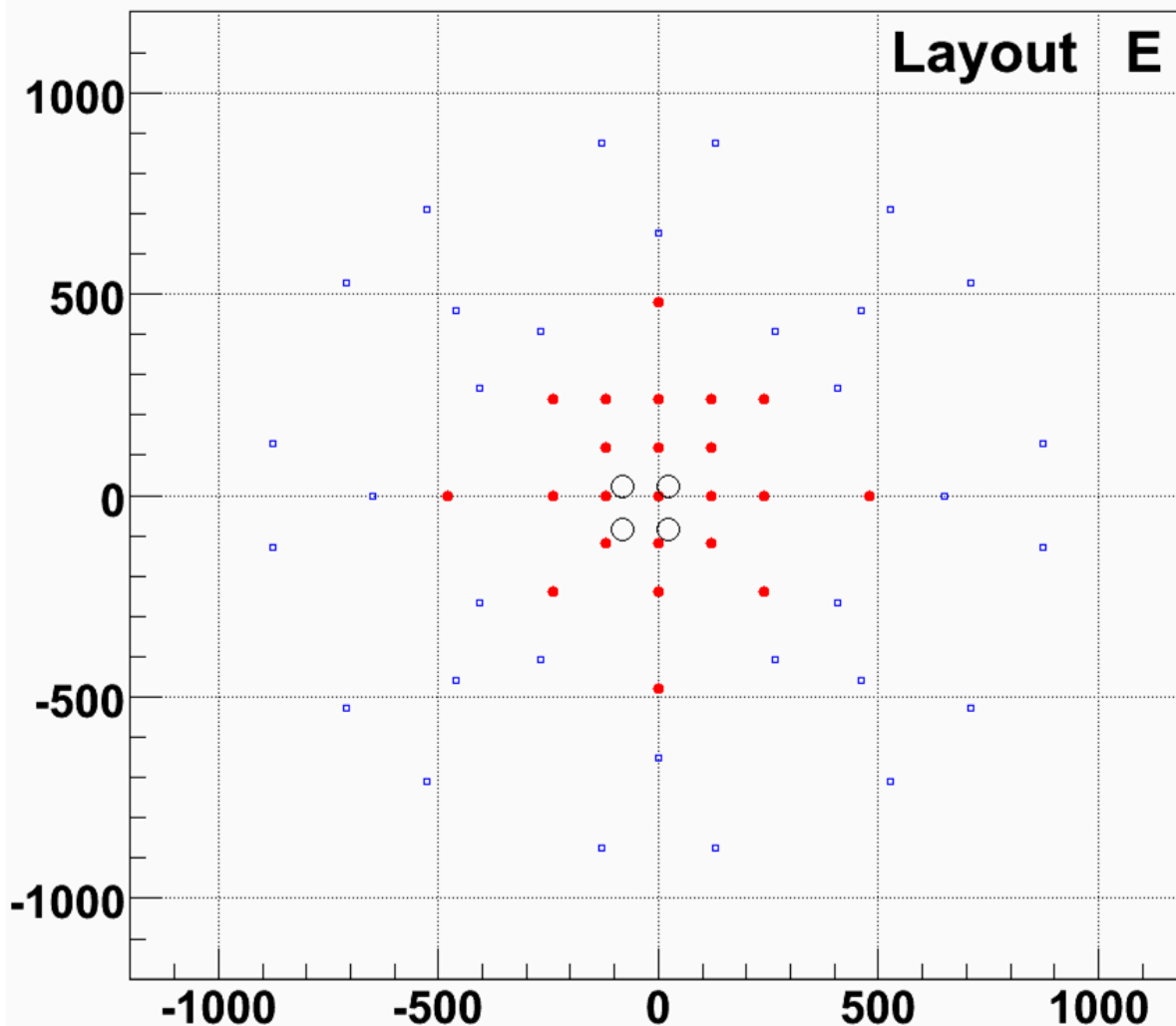
20 Optimisation Attempt



21 Optimisation Attempt



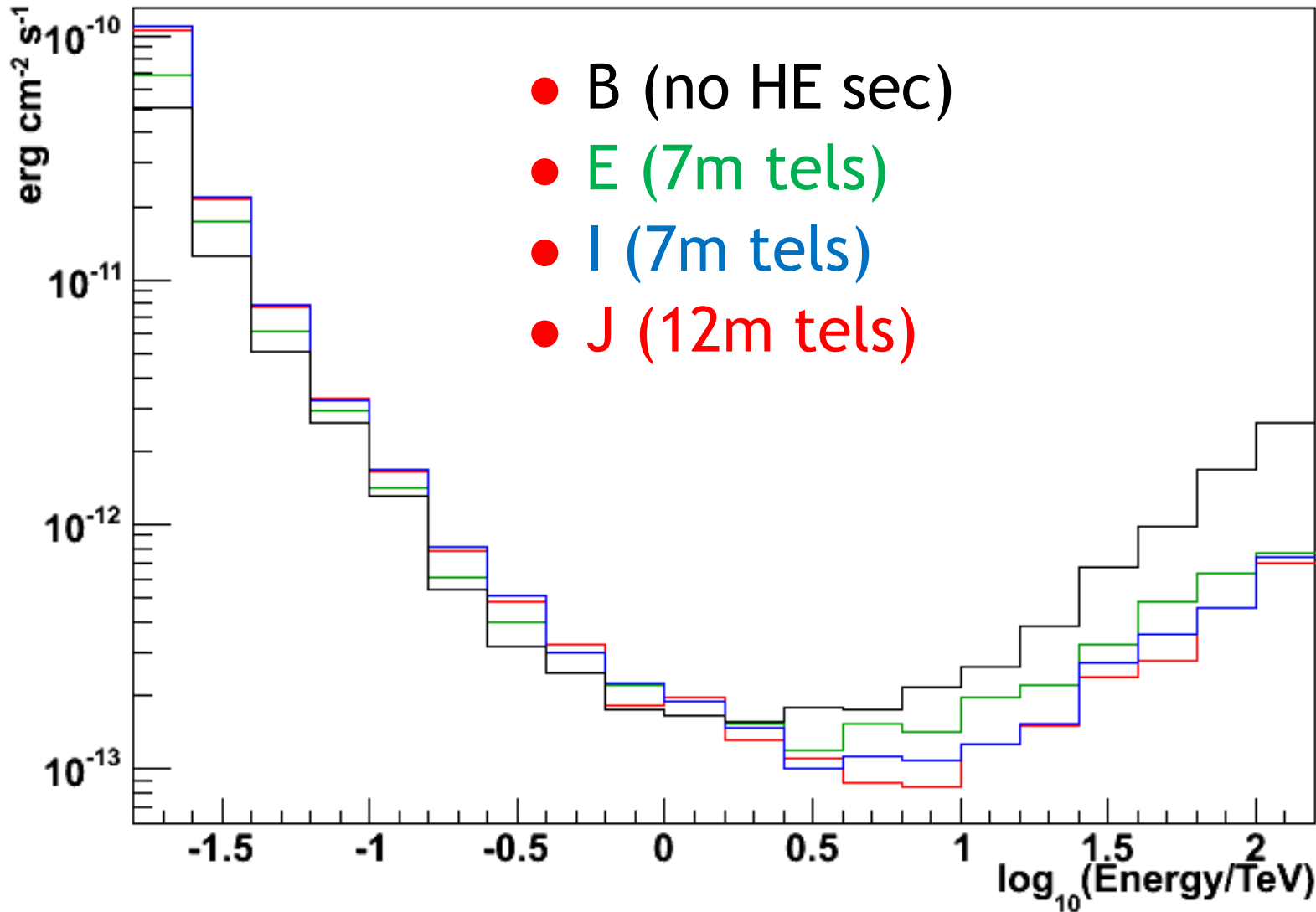
Full MC – Configuration E



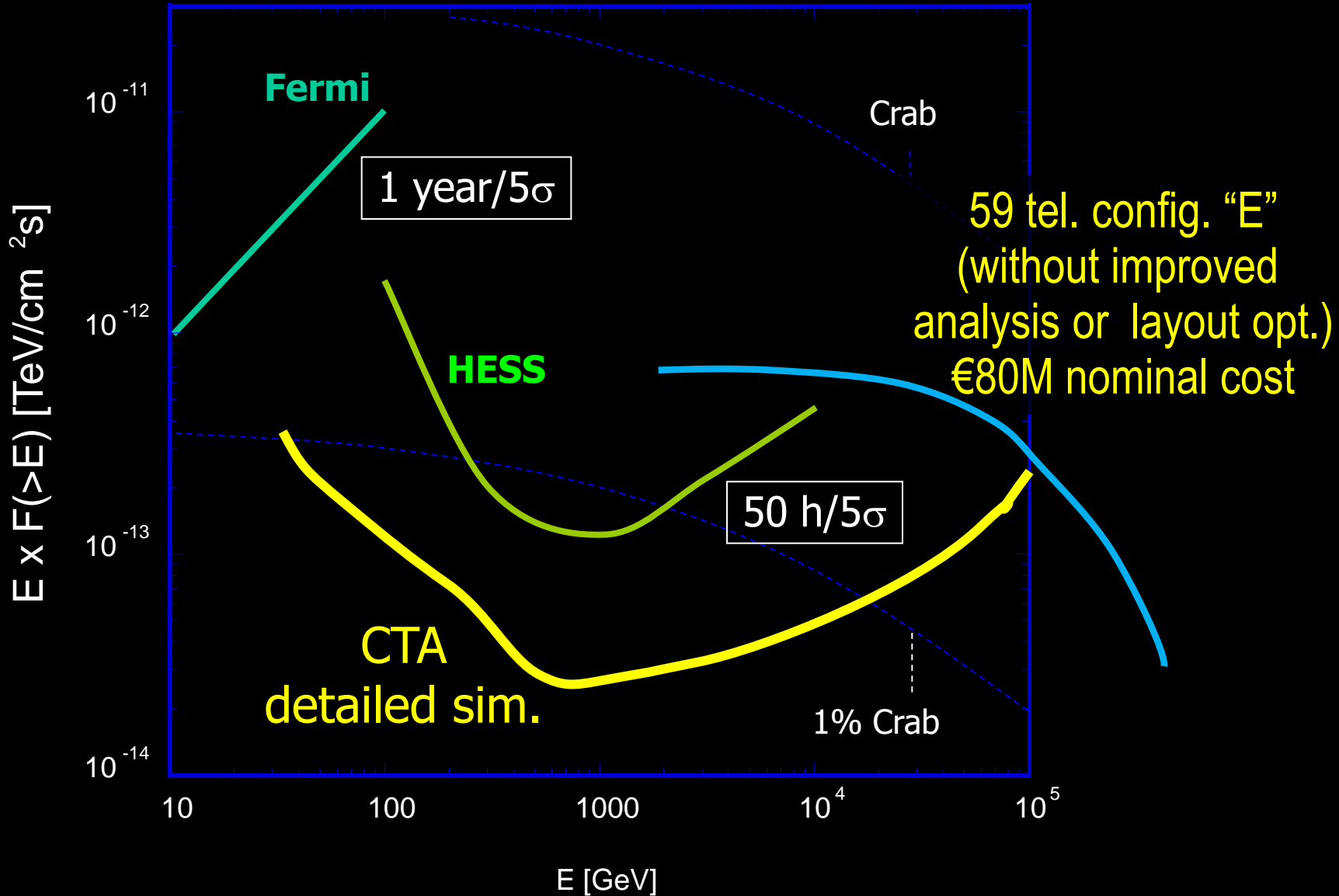
- 23m (x4)
4.6° FoV,
0.09° pixels
- 12m (x23)
8° FoV
0.18° pixels
- 7m (x32)
10° FoV
0.25° pixels

Nominal cost
80Me

23 Production 1 Config Sens.



24 Point-source Sensitivity



- Unavoidable features of the SST
 - ▶ Many telescopes
 - ▶ $>6^\circ$ FoV
 - ▶ Long event/integration times
- Optimisation
 - ▶ Requires performance and cost information for individual components
 - › Detailed design work needed
 - ▶ Can be done iteratively using Toy+Real MC once we have costed designs for different options
- Organisation...