

#### CHEC Camera: Monte Carlo Trigger Studies

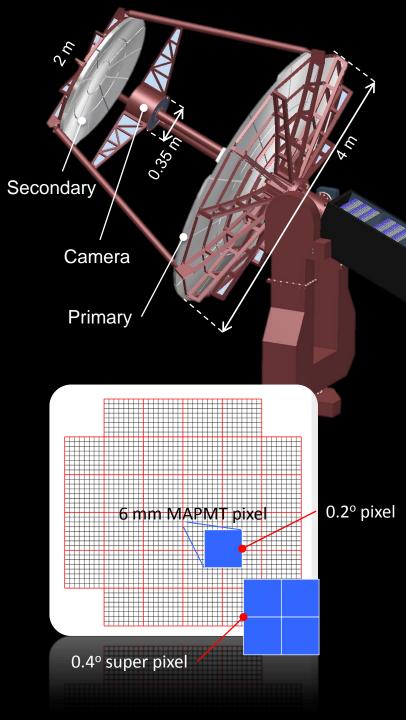
## MAPM-based Camera $(\rightarrow all details on the wiki!)$

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CTA-UK meeting, Liverpool

## Aims and outline

- Preliminary optimisation of the CHEC camera design, based on MAPMs
- Based on Target electronics: 4 x 0.2° pixels are summed on the ASIC (current implementation). Studies also performed with 16 x 0.2° and 1 x 0.2° "super pixels".
- Trigger Studies: Target v5 has majority trigger and analogue sum of 4 pixels implemented. Not so sure about analogue sum of 16, or digital sum...



## **Key Ingredients**

#### MAPM SPE spectrum

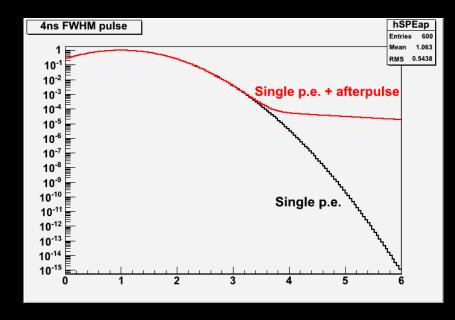
 Simple fit based on lab measurement (one channel H10966 MAPMT)

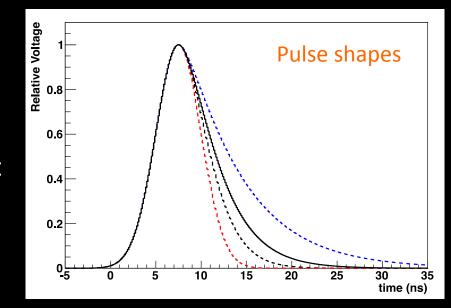
#### • Pulse shape

- Pulse shape used in P. Cogan's thesis (VERITAS)
- Represents preamp output, rather than MAPM
- tested different pulse shapes

#### • NSB

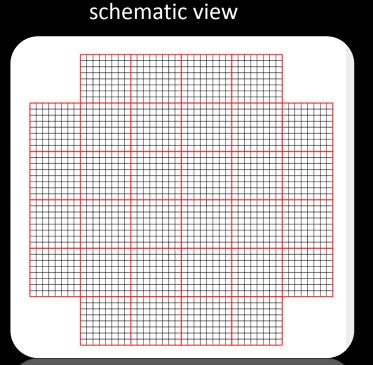
- Scaled from MST rate to the DM SST
- 12 MHz per pixel (corresponds to the "aggressive" trigger definition of the MC group.)
- Jitter/Gain
  - different jitters and gain variances have been tested as well



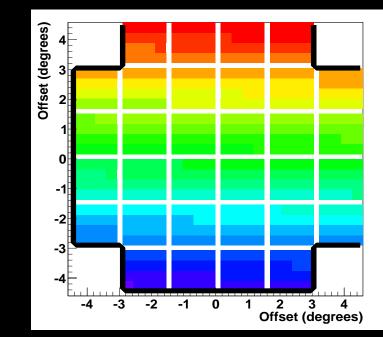


## Simulation

- CORSIKA shower simulations are used to generate lists of photo-electrons
- convert these to a ROOT-based image format assuming perfect PSF
- Use *LTools* simulation package to perform the actual study
- assume 32 x 64 pixel MAPM modules
- gaps between modules taken into account (1 pixel wide)



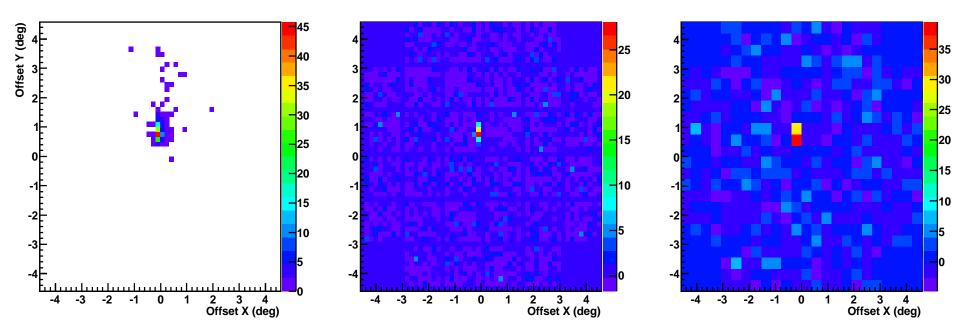
#### simulation



## Simulation

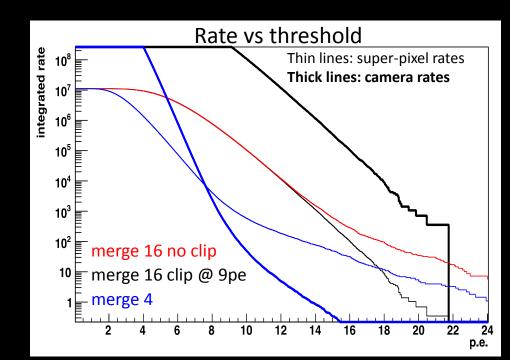
- take raw images
- add electronic noise (0.4 p.e. rms per pixel) and NSB
- make analogue sum of 4 (or 16) pixels  $\rightarrow$  generate trigger image
- apply trigger criterion on minimum pixel intensity in the triggered image

#### simulated shower image $\rightarrow$ + NSB, + electronic noise $\rightarrow$ resulting trigger image (merge 4)



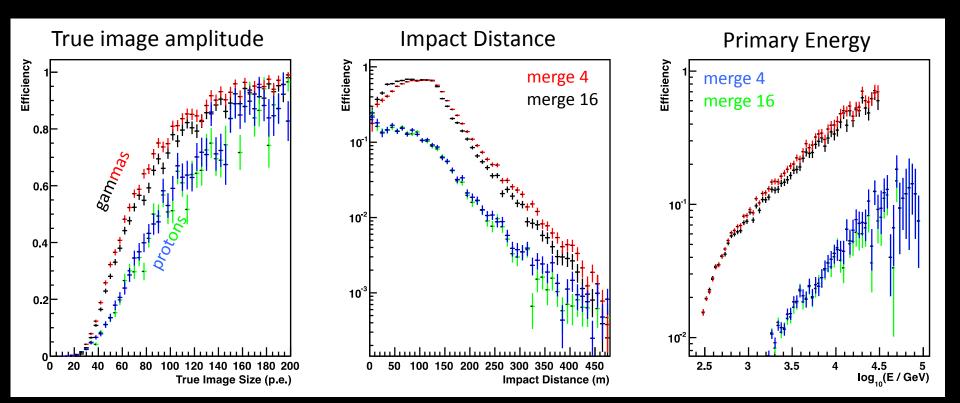
#### How to get the Trigger criteria?

- Get the pixel threshold by requiring 200 Hz camera accidental trigger rate for given NSB level
- A digital pulse based on a pixel (or combination of neighbouring pixels) exceeding this threshold is assumed to be sent to camera-level trigger
- Apply neighbour requirement and test
  - merge 4 with multiplicity of 1 & 2, merge 16, multiplicity of 1
- Check efficiency with which images of certain amplitude trigger



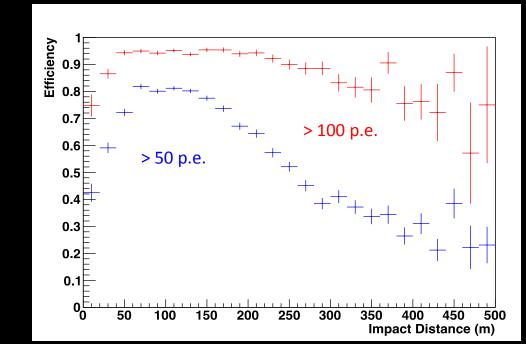
## Trigger efficiency

- CTA level B specifications of 50% trigger efficiency at 100 p.e. can be met
- Reach 50% around 60-70 p.e. (and coincidence window of 9ns & 6.5ns FWHM pulse, see later)
- good trigger efficiency at largish shower impact distances (important for SSTs as many high-energy shower are far away)



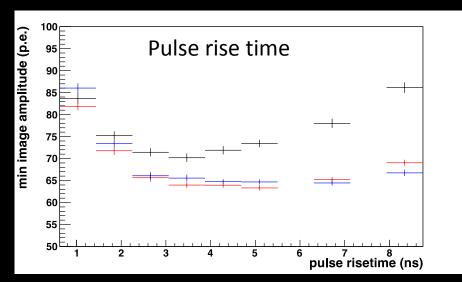
## Trigger efficiency

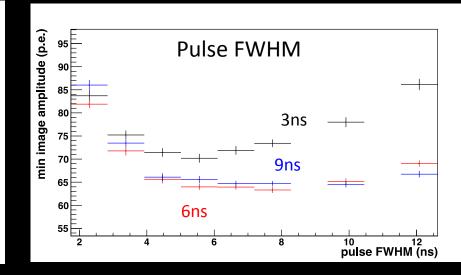
- CTA level B specifications of 50% trigger efficiency at 100 p.e. can be met
- Reach 50% around 60-70 p.e. (and coincidence window of 9ns & 6.5 ns FWHM pulse)
- good trigger efficiency at large shower impact distances (important for SSTs as many high-energy shower are far away)
- Nearly all images with size > 100 p.e. and impact distance between 50m and 300m trigger



#### Trigger efficiency: pulse FWHM, rise time

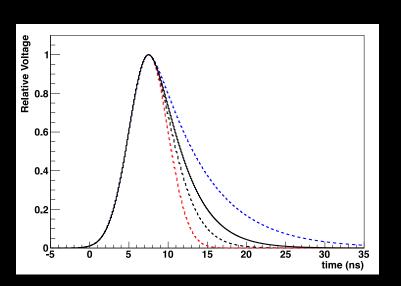
- In the following, show image size at 50% trigger efficiency as a function of pulse shape, coincidence window between pixels, gain variance, ...
- For fixed pulse shape:
  - Very short pulses don't overlap/build up in the merge 4
  - If coincidence window between pixels is too short, long pulses don't overlap (get cropped)
  - optimum rise time between 3.5ns and 6.5 ns

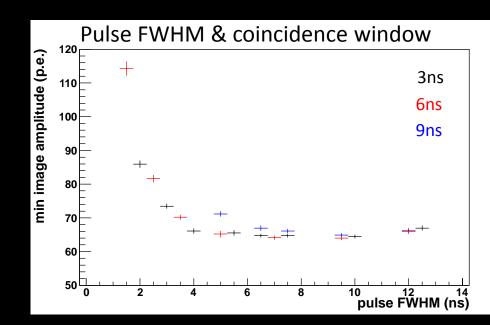




## Trigger efficiency: pulse shape

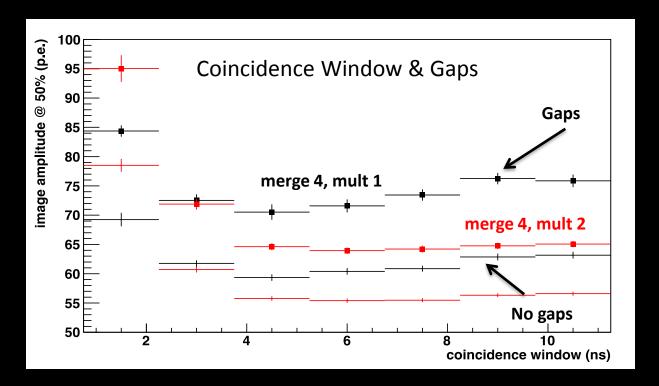
- In the following, show image size at 50% trigger efficiency as a function of pulse shape, coincidence window between pixels, gain variance, ...
- Change pulse shape:
  - again, very short pulses don't overlap
  - optimum around 5.5 10.5 ns





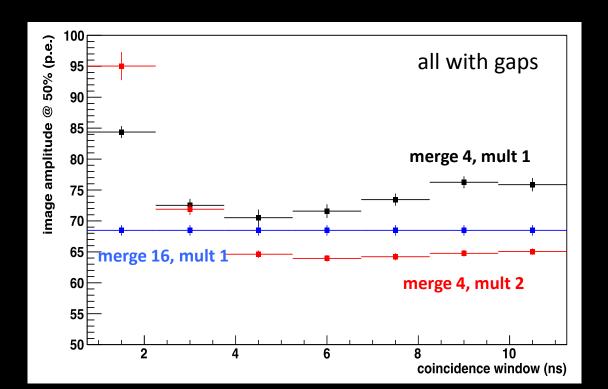
#### Trigger efficiency: Coincidence Window

- Coincidence window of 6ns 10ns desirable
- Gaps increase minimum image size @ 50% trigger efficiency by  $\sim 10\%$  15%
- Merge of 4 pixels and single pixel trigger has inferior performance compared to merge of 4 pixels and a multiplicity of 2



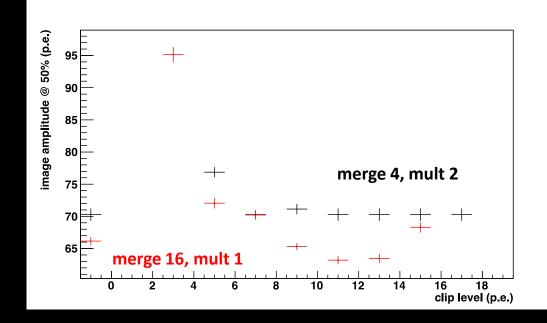
#### Trigger efficiency: Coincidence Window

- Coincidence window of 6ns 10ns desirable
- Gaps increase minimum image size @ 50% trigger efficiency by  $\sim 10\%$  15%
- Merge of 16 pixels looks like a desirable solution
- ightarrow check how clipping improves things



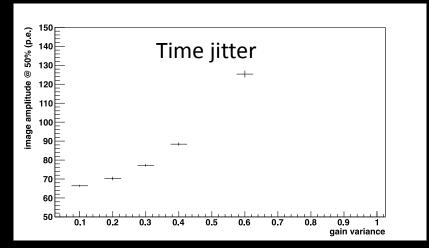
## **Trigger efficiency: Clipping**

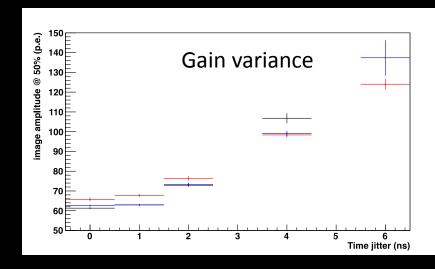
 No significant effect for merge 4, mult 2 config, but 10% improvement for merge 16, mult 1 → could make this trigger very powerful



# Trigger efficiency: Time jitter & gain variance

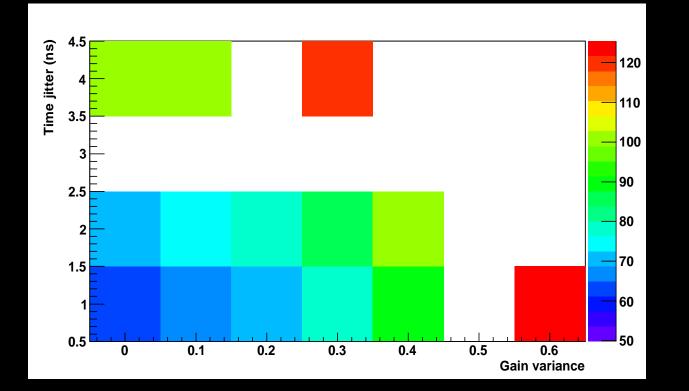
- Time jitter < 2ns for 10ns coincidence window desirable, or < 1ns for 6ns coincidence window
- Gain variance < 25% (35%) rms for 4-pixel (16-pixel) merge





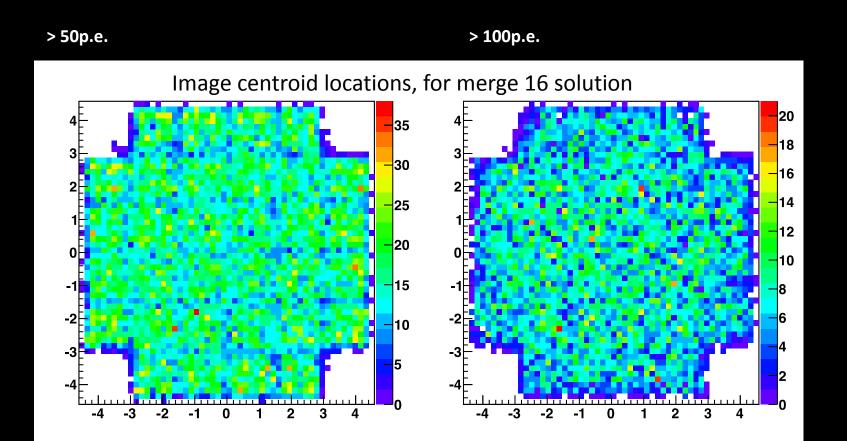
# Trigger efficiency: Time jitter & gain variance

- Combined effect
  - things can turn quite bad if both things get too large, e.g. 2.0ns time jitter and 40% gain variance → threshold increases to ~85 p.e.



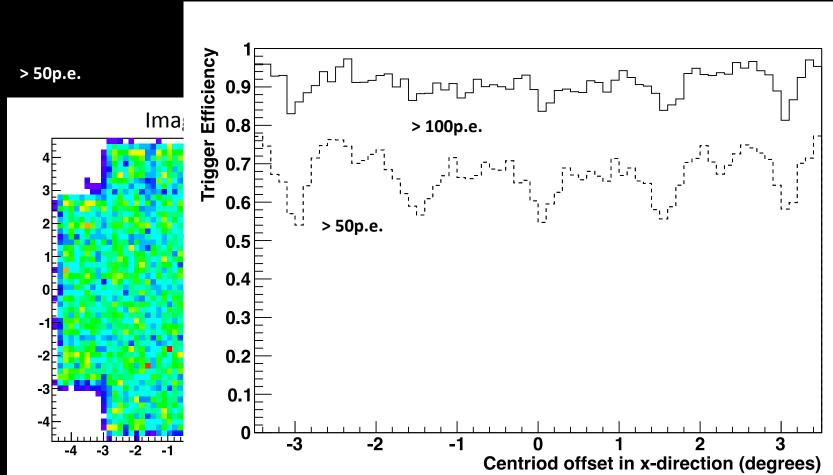
## Trigger efficiency: Camera uniformity

 Use diffuse gamma-ray simulations and check if camera responds uniformly to signals



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#### Summary: Recommendations

#### **Recommendations:**

Pulse Shape (after pre-amplifier/at Target input): 10-90% risetime 3.5-6.0 ns, and FWHM 5.5-10.5 ns

**Trigger logic**: analogue sum of 4 pixels, discriminated and sent to camera-trigger where a neighbour requirement and a minimum multiplicity of 2 is applied within a coincidence window (between digital signals on the backplane).

#### Camera Trigger Coincidence Window: 6-10 ns.

(a simple OR of all discriminated 16-pixel sums is attractive – particularly with clipping, but has inferior performance at larger impact distances – at least when no signal clipping is applied.)

Time jitter on digital inputs to camera trigger: <2ns for a 10 ns coincidence window, <1ns for a 6ns window.

Electronic Noise: <0.5 mV rms per pixel on the trigger path.

Pixel to pixel gain variations: <25% rms (4-pixel sum), <35% (16-pixel sum)

Gaps: <1 pixel=6mm gaps between MAPMs (including glass thickness).