

PSA-Diffusion-Triple

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1 Numerical calculation of PSA levels

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1.2 Notes

Nothing at the moment.

1.3 Introduction

Model a prostate tumour and the resulting production of prostate specific antigen (PSA). Define a “body”, a rectangular 3D grid of “cells”. Make some of them prostate, some tumour, and some blood cells. Surround these with a “border”, an outer layer that could be used to simplify the application of boundary conditions during calculation of the changes in PSA concentration. The

overall size of the body does not change, so make this large enough to encompass some tumour growth! PSA is produced at a low rate in the prostate and at a higher rate in the tumour cells and diffuses through these cells into the blood. The PSA also decays and the rate of decay is higher in the blood than in the prostate and tumour cells.

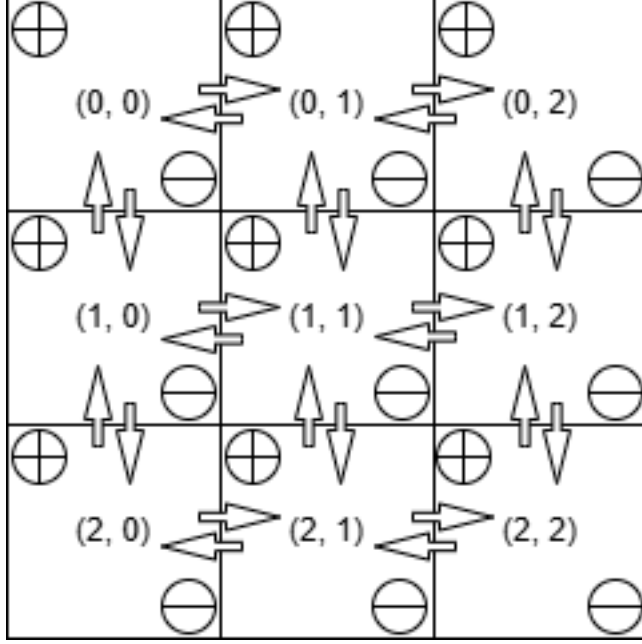


Figure 1 *Illustration in two dimensions of rectangular grid of cells, with flow of PSA from cell to cell and PSA generation and decay.*

Model diffusion as transfer of PSA from one cell $(1, 1)$ to its neighbours $(1, 0)$, $(2, 2)$, $(0, 1)$ and $(2, 1)$ in a time step of length δt . The amount transferred is proportional to the PSA concentration in the cell. the length of the common boundary and of the time step. Similarly, the neighbouring cells transfer PSA into the central cell. Labelling as ρ_{10} the PSA level in cell $(1, 0)$, as ρ_{11} the density in cell $(1, 1)$ and so on, and assuming all the boundaries are of the same length, the change in the quantity of PSA in the central cell in the time interval δt can then be expressed as:

$$\delta_{11} = \delta t \beta (\rho_{01} + \rho_{10} + \rho_{21} + \rho_{12} - 4\rho_{11}).$$

Here, β is a constant of proportionality (which incorporates factors like the length of the cell boundary, its permeability etc.).

Allow for the generation of PSA in the cells; σ_{11} is the amount of PSA produced in cell $(1, 1)$ per unit time:

$$\delta_{11} = \delta t \beta (\rho_{01} + \rho_{10} + \rho_{21} + \rho_{12} - 4\rho_{11}) + \delta t \sigma_{11}.$$

The rate of generation of PSA is different in different cell types.

A further necessary component is PSA decay. Adding this, the above equation becomes:

$$\delta_{11} = \delta t \beta (\rho_{01} + \rho_{10} + \rho_{21} + \rho_{12} - 4\rho_{11}) + \delta t \sigma_{11} - \frac{\delta t}{\tau} \rho_{11}$$

Here, τ is the lifetime of PSA. It is different in tumour or prostate cells and in the blood stream.

The amount of PSA in each of the neighbouring cells changes in the same manner.

This model can be extended to three dimensions. Using an obvious extension of the notation (and assuming the areas connecting the cells are the same), we have:

$$\delta_{111} = \delta t \beta (\rho_{011} + \rho_{101} + \rho_{211} + \rho_{121} + \rho_{110} + \rho_{112} - 6\rho_{111}) + \delta t \sigma_{111} - \frac{\delta t}{\tau} \rho_{111}.$$

As the blood flows past the prostate and tumour, the PSA diffusing into the blood is shared between a large number of cells, resulting in a dilution factor for blood cells. Further, the (effective) diffusion between blood cells is not the same as in “static” cells. Assume that the diffusion in blood cells is essentially instantaneous. (Model this by defining a layer of blood cells adjacent to the prostate/tumour, diffuse PSA into these in the standard way, find the average PSA level in this layer, and assign it to all blood cells.)

The number of cells in the body may change. In particular, the tumour may grow. Initially, assume that cell division happens at the surface of the tumour. The new cell is created next to a tumour cell and the displaced cell moves to another adjacent “neighbour” position. The neighbour moves to the nearest site outside the tumour and prostate. This last cell will extend into the blood so the overall prostate/tumour size will increase.

Cell death has yet to be implemented, but cells, in particular tumour cells, do die. Consider whether to shrink the prostate/tumour when this happens, or to leave a (blood-filled?) void.

1.3.1 Cell type codes

Cell types are coded as follows.

In body:

Description	Code	Notes
Unspecified	0	
Test	-1	
Border	1	Border of body, thickness 1 cell
Blood	2	
Prostate	3	
Tumour	4	

In body_steel:

Description	Code	Notes
Unspecified	0	
Surface	1	Layer of cells immediately outside tumour
Duplicate	2	Cell to be replicated
Exterior	3	Blood layer outside prostate/tumour
End	4	Position to which cell overwritten by duplicate is moved
Neighbour	5	Position to which duplicate written

Description	Code	Notes
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1.3.2 Increase tumour size - making duplications

Find the “surface” cells that lie around the tumour (i.e. cells for which one above is not tumour and/or one below is not tumour and/or one to the left is not tumour and/or one to the right is not tumour).

Choose one surface cell to be the position into which the replicated/duplicated cell goes.

Find the “end” cell, the blood cell closest to the cell to be duplicated.

The codes for these cells are stored in the `body_steer` array.

Find a “neighbour” cell, adjacent to the cell that will accept the duplicate (change cell code in `body_steer` appropriately).

Copy the cell type originally in the duplicate position into the neighbour position and the original neighbour into the end cell position (in `body`).

Create a new tumour cell (in `body`) at the duplicate position.

1.4 Load libraries and initialise random number generator

Return to ToC: »

```
[1]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline
#
import matplotlib.cm as cm
rng = np.random.default_rng()
#
then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))
```

Date and time 2026-01-10 14:33:54.301824

Date and time 2026-01-10 14:33:54.863079

Time since last check is 0:00:00.561255

1.5 Functions

1.5.1 List body data

Return to ToC: »

```

[2]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
def list_body_sums():
    '''
    List numbers of different type of cells in body and body_steer arrays
    '''
    n_border = np.sum(body == c_border)
    n_blood = np.sum(body == c_blood)
    n_prostate = np.sum(body == c_prostate)
    n_tumour = np.sum(body == c_tumour)
    print(" ")
    print("Body")
    print("No. body border cells",n_border)
    print("No. body blood cells",n_blood)
    print("No. body prostate cells",n_prostate)
    print("No. body tumour cells",n_tumour)
    print("No. body cells A",n_border + n_blood + n_prostate + n_tumour)
    n_surface = np.sum(body_steel == c_surface)
    n_duplicate = np.sum(body_steel == c_duplicate)
    n_exterior = np.sum(body_steel == c_exterior)
    n_end = np.sum(body_steel == c_end)
    n_neighbour_s = np.sum(body_steel == c_neighbour)
    print(" ")
    print("Steer")
    print("No. steer surface cells",n_surface)
    print("No. steer duplicate cells",n_duplicate)
    print("No. steer exterior cells",n_exterior)
    print("No. steer end cells",n_end)
    print("No. steer neighbour cells",n_neighbour)
    print("No. steer cells",(n_surface + n_duplicate + n_exterior + n_end +
↪n_neighbour))
    #
    return
#
then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))

```

Date and time 2026-01-10 14:33:54.869095

Date and time 2026-01-10 14:33:54.869618
Time since last check is 0:00:00.000523

1.5.2 Plot body data

Return to ToC: »

```
[3]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
def plot_body(title, body_data, body_index, i_point, j_point, k_point,
    plot_point,
    plot_border, plot_blood, plot_prostate, plot_tumour, plot_surface,
    plot_duplicate, plot_exterior, plot_end, plot_neighbour,
    plot_test, plot_2D, plot_log,
    c_map, v_min = -1, v_max = -1):
    """
    Plot body_data in 3D (and in 2D if required) with optional fixed limits on
    the colour map.
    The data shown are selected using body_index.
    """
    debug = False
    #
    # Markers for 3D and 2D plots
    m3_point = '*'
    m3_border = 's'
    m3_blood = '.'
    m3_prostate = 'o'
    m3_tumour = 'o'
    m3_surface = 'o'
    m3_duplicate = 'o'
    m3_exterior = 'o'
    m3_end = 'o'
    m3_neighbour = 'o'
    m3_test = '*'
    #
    m2_point = '*'
    m2_border = 's'
    m2_blood = '.'
    m2_prostate = '+'
    m2_tumour = 'x'
    m2_surface = 's'
    m2_duplicate = 'D'
    m2_exterior = '.'
    m2_end = '^'
    m2_neighbour = 'v'
    m2_test = '*'
    #
    # Sizes for 3D and 2D plots
    s3_point = 20
```

```

s3_border = 0.0
s3_blood = 0.001
s3_prostate = 0.05
s3_tumour = 5
s3_surface = 5
s3_duplicate = 20
s3_exterior = 5
s3_end = 20
s3_neighbour = 20
s3_test = 10
#
s2_point = 20
s2_border = 20
s2_blood = 0.05
s2_prostate = 10
s2_tumour = 10
s2_surface = 10
s2_duplicate = 20
s2_exterior = 10
s2_end = 20
s2_neighbour = 20
s2_test = 10
#
if plot_log:
    plot_data = np.log(np.maximum(body_data, 1e-6*np.ones_like(body_data)))
else:
    plot_data = body_data
#
if debug:
    print(" ")
    print(f"Input v_min {v_min:.2f}, v_max {v_max:.2f}.")
if v_min < 0:
    v_min = np.amin(plot_data)
if v_max < 0:
    v_max = np.amax(plot_data)
if v_min >= v_max:
    v_min = v_max - 0.1
if plot_test:
    v_max = v_max + 1
#
if debug:
    print(" ")
    print(f"Used v_min {v_min:.2f}, v_max {v_max:.2f}.")
#
# Make 3D plot
fig = plt.figure(figsize = (5, 7))
#

```

```

ax = fig.add_subplot(1, 1, 1, projection = '3d')
ax.set_title(f"{title}, xyz")
#
if plot_blood:
    i_plot, j_plot, k_plot = np.where(body == c_blood)
    blood_body = plot_data[i_plot, j_plot, k_plot]
    ax.scatter(i_plot, j_plot, k_plot,
               marker = m3_blood, s = s3_blood, vmin= v_min, vmax = v_max,
               c = blood_body, alpha = 0.3, label = "Blood", cmap = c_map)
#
if plot_border:
    i_plot, j_plot, k_plot = np.where(body == c_border)
    border_body = plot_data[i_plot, j_plot, k_plot]
    ax.scatter(i_plot, j_plot, k_plot,
               marker = m3_border, s = s3_border, vmin= v_min, vmax = v_max,
               c = border_body, alpha = 0.3, label = "Border", cmap = c_map)
#
if plot_prostate:
    i_plot, j_plot, k_plot = np.where(body == c_prostate)
    prostate_body = plot_data[i_plot, j_plot, k_plot]
    ax.scatter(i_plot, j_plot, k_plot,
               marker = m3_prostate, s = s3_prostate, vmin= v_min, vmax =
↪v_max,
               c = prostate_body, alpha = 0.3, label = "Prostate", cmap =
↪c_map)
#
if plot_tumour:
    i_plot, j_plot, k_plot = np.where(body == c_tumour)
    tumour_body = plot_data[i_plot, j_plot, k_plot]
    im_t = ax.scatter(i_plot, j_plot, k_plot,
                      marker = m3_tumour, s = s3_tumour, vmin= v_min, vmax=
↪v_max,
                      c = tumour_body, alpha = 1.0, label = "Tumour", cmap=
↪c_map)
#
if plot_surface:
    i_plot, j_plot, k_plot = np.where(body_index == c_surface)
    surface_index = body_index[i_plot, j_plot, k_plot]
    ax.scatter(i_plot, j_plot, k_plot,
               marker = m3_surface, s = s3_surface, vmin= v_min, vmax =
↪v_max,
               c = surface_index, alpha = 1.0, label = "Surface", cmap =
↪c_map)
#
if plot_duplicate:
    i_plot, j_plot, k_plot = np.where(body_index == c_duplicate)

```

```

        dup_index = body_index[i_plot, j_plot, k_plot]
        ax.scatter(i_plot, j_plot, k_plot,
                   marker = m3_duplicate, s = s3_duplicate, vmin= v_min, vmax =
↪v_max,
                   c = dup_index, alpha = 1.0, label = "Duplicate", cmap =
↪c_map)
        #
        if plot_exterior:
            i_plot, j_plot, k_plot = np.where(body_index == c_exterior)
            exterior_index = body_index[i_plot, j_plot, k_plot]
            ax.scatter(i_plot, j_plot, k_plot,
                       marker = m3_exterior, s = s3_exterior, vmin= v_min, vmax =
↪v_max,
                       c = exterior_index, alpha = 1.0, label = "Exterior", cmap =
↪c_map)
        #
        if plot_end:
            i_plot, j_plot, k_plot = np.where(body_index == c_end)
            end_index = body_index[i_plot, j_plot, k_plot]
            ax.scatter(i_plot, j_plot, k_plot,
                       marker = m3_end, s = s3_end, vmin= v_min, vmax = v_max,
                       c = end_index, alpha = 1.0, label = "End", cmap = c_map)
        #
        if plot_neighbour:
            i_plot, j_plot, k_plot = np.where(body_index == c_neighbour)
            neigh_index = body_index[i_plot, j_plot, k_plot]
            ax.scatter(i_plot, j_plot, k_plot,
                       marker = m3_neighbour, s = s3_neighbour, vmin= v_min, vmax =
↪v_max,
                       c = neigh_index, alpha = 1.0, label = "Neighbour", cmap =
↪c_map)
        #
        if plot_test:
            i_plot, j_plot, k_plot = np.where(body_index == c_test)
            test_body = plot_data[i_plot, j_plot, k_plot]
            test_index = body_index[i_plot, j_plot, k_plot]
            test_use = np.maximum(test_body, test_index) + 1
            im_t = ax.scatter(i_plot, j_plot, k_plot,
                              marker = m3_test, s = s3_test, vmin= v_min, vmax =
↪v_max,
                              c = test_use, alpha = 1.0, label = title, cmap =
↪c_map)
        #
        if plot_point:
            ax.scatter(i_point, j_point, k_point,
                       marker = m3_point, s = s3_point,

```

```

        color = 'r', alpha = 1.0, label = "Point")

#
ax.set_xlim(0, n_cells_x + 2*n_edge - 1)
ax.set_ylim(0, n_cells_y + 2*n_edge - 1)
ax.set_zlim(0, n_cells_z + 2*n_edge - 1)
ax.set_xlabel('x')
ax.set_ylabel('y')
ax.set_zlabel('z')
#
ax.legend(loc = 'lower right')
ax.zaxis.labelpad = 3.0
#
# Finish and display 3D plot
fig.colorbar(im_t, ax = ax, fraction = 0.025, pad = 0.15)
#
plt.tight_layout()
plt.show()
#
# Make 2D plots if required
if plot_2D:
    fig = plt.figure(figsize = (7, 7))
    #
    ax_xy = fig.add_subplot(2, 2, 1)
    ax_xy.set_title(f"{title}, plane at k = {k_point}")
    #
    ax_xz = fig.add_subplot(2, 2, 2)
    ax_xz.set_title(f"{title}, plane at j = {j_point}")
    #
    ax_yz = fig.add_subplot(2, 2, 3)
    ax_yz.set_title(f"{title}, plane at i = {i_point}")
    #
    if plot_blood:
        i_plot, j_plot = np.where(body[:, :, k_point] == c_blood)
        colors = plot_data[i_plot, j_plot, k_point]
        ax_xy.scatter(i_plot, j_plot,
                     marker = m2_blood, s = s2_blood, vmin= v_min, vmax = ↵
↵v_max,
                     c = colors, alpha = 1.0, label = "Blood", cmap = ↵
↵c_map)
        #
        i_plot, k_plot = np.where(body[:, j_point, :] == c_blood)
        colors = plot_data[i_plot, j_point, k_plot]
        ax_xz.scatter(i_plot, k_plot,
                     marker = m2_blood, s = s2_blood, vmin= v_min, vmax = ↵
↵v_max,
                     c = colors, alpha = 1.0, label = "Blood", cmap = ↵
↵c_map)

```

```

#
j_plot, k_plot = np.where(body[i_point, :, :] == c_blood)
colors = plot_data[i_point, j_plot, k_plot]
ax_yz.scatter(j_plot, k_plot,
               marker = m2_blood, s = s2_blood, vmin= v_min, vmax =
↪v_max,
               c = colors, alpha = 1.0, label = "Blood", cmap =
↪c_map)

#
if plot_border:
    i_plot, j_plot = np.where(body[:, :, k_point] == c_border)
    colors = plot_data[i_plot, j_plot, k_point]
    ax_xy.scatter(i_plot, j_plot,
                  marker = m2_border, s = s2_border, vmin= v_min, vmax
↪= v_max,
                  c = colors, alpha = 1.0, label = "Border", cmap =
↪c_map)

#
i_plot, k_plot = np.where(body[:, j_point, :] == c_border)
colors = plot_data[i_plot, j_point, k_plot]
ax_xz.scatter(i_plot, k_plot,
               marker = m2_border, s = s2_border, vmin= v_min, vmax
↪= v_max,
               c = colors, alpha = 1.0, label = "Border", cmap =
↪c_map)

#
j_plot, k_plot = np.where(body[i_point, :, :] == c_border)
colors = plot_data[i_point, j_plot, k_plot]
ax_yz.scatter(j_plot, k_plot,
               marker = m2_border, s = s2_border, vmin= v_min, vmax
↪= v_max,
               c = colors, alpha = 1.0, label = "Border", cmap =
↪c_map)

#
if plot_prostate:
    i_plot, j_plot = np.where(body[:, :, k_point] == c_prostate)
    colors = plot_data[i_plot, j_plot, k_point]
    ax_xy.scatter(i_plot, j_plot,
                  marker = m2_prostate, s = s2_prostate, vmin= v_min,
↪vmax = v_max,
                  c = colors, alpha = 1.0, label = "Prostate", cmap =
↪c_map)

#
i_plot, k_plot = np.where(body[:, j_point, :] == c_prostate)
colors = plot_data[i_plot, j_point, k_plot]
ax_xz.scatter(i_plot, k_plot,

```

```

marker = m2_prostate, s = s2_prostate, vmin= v_min,
↪vmax = v_max,
c = colors, alpha = 1.0, label = "Prostate", cmap =
↪c_map)
#
j_plot, k_plot = np.where(body[i_point, :, :] == c_prostate)
colors = plot_data[i_point, j_plot, k_plot]
ax_yz.scatter(j_plot, k_plot,
marker = m2_prostate, s = s2_prostate, vmin= v_min,
↪vmax = v_max,
c = colors, alpha = 1.0, label = "Prostate", cmap =
↪c_map)
#
if plot_tumour:
i_plot, j_plot = np.where(body[:, :, k_point] == c_tumour)
colors = plot_data[i_plot, j_plot, k_point]
ax_xy.scatter(i_plot, j_plot,
marker = m2_tumour, s = s2_tumour, vmin= v_min, vmax
↪= v_max,
c = colors, alpha = 1.0, label = "Tumour", cmap =
↪c_map)
#
i_plot, k_plot = np.where(body[:, j_point, :] == c_tumour)
colors = plot_data[i_plot, j_point, k_plot]
ax_xz.scatter(i_plot, k_plot,
marker = m2_tumour, s = s2_tumour, vmin= v_min, vmax
↪= v_max,
c = colors, alpha = 1.0, label = "Tumour", cmap =
↪c_map)
#
j_plot, k_plot = np.where(body[i_point, :, :] == c_tumour)
colors = plot_data[i_point, j_plot, k_plot]
ax_yz.scatter(j_plot, k_plot,
marker = m2_tumour, s = s2_tumour, vmin= v_min, vmax
↪= v_max,
c = colors, alpha = 1.0, label = "Tumour", cmap =
↪c_map)
#
if plot_surface:
i_plot, j_plot = np.where(body_index[:, :, k_point] == c_surface)
colors = body_index[i_plot, j_plot, k_point]
ax_xy.scatter(i_plot, j_plot,
marker = m2_surface, s = s2_surface, vmin= v_min,
↪vmax = v_max,
c = colors, alpha = 1.0, label = "Surface", cmap =
↪c_map)

```

```

#
i_plot, k_plot = np.where(body_index[:, j_point, :] == c_surface)
colors = body_index[i_plot, j_point, k_plot]
ax_xz.scatter(i_plot, k_plot,
               marker = m2_surface, s = s2_surface, vmin= v_min,
↳vmax = v_max,
               c = colors, alpha = 1.0, label = "Surface", cmap =
↳c_map)

#
j_plot, k_plot = np.where(body_index[i_point, :, :] == c_surface)
colors = body_index[i_point, j_plot, k_plot]
ax_yz.scatter(j_plot, k_plot,
               marker = m2_surface, s = s2_surface, vmin= v_min,
↳vmax = v_max,
               c = colors, alpha = 1.0, label = "Surface", cmap =
↳c_map)

#
if plot_duplicate:
    i_plot, j_plot = np.where(body_index[:, :, k_point] == c_duplicate)
    colors = body_index[i_plot, j_plot, k_point]
    ax_xy.scatter(i_plot, j_plot,
                  marker = m2_duplicate, s = s2_duplicate, vmin= v_min,
↳vmax = v_max,
                  c = colors, alpha = 1.0, label = "Duplicate", cmap =
↳c_map)

#
i_plot, k_plot = np.where(body_index[:, j_point, :] == c_duplicate)
colors = body_index[i_plot, j_point, k_plot]
ax_xz.scatter(i_plot, k_plot,
               marker = m2_duplicate, s = s2_duplicate, vmin= v_min,
↳vmax = v_max,
               c = colors, alpha = 1.0, label = "Duplicate", cmap =
↳c_map)

#
j_plot, k_plot = np.where(body_index[i_point, :, :] == c_duplicate)
colors = body_index[i_point, j_plot, k_plot]
ax_yz.scatter(j_plot, k_plot,
               marker = m2_duplicate, s = s2_duplicate, vmin= v_min,
↳vmax = v_max,
               c = colors, alpha = 1.0, label = "Duplicate", cmap =
↳c_map)

#
if plot_exterior:
    i_plot, j_plot = np.where(body_index[:, :, k_point] == c_exterior)
    colors = body_index[i_plot, j_plot, k_point]
    ax_xy.scatter(i_plot, j_plot,

```

```

marker = m2_exterior, s = s2_exterior, vmin= v_min,
↪vmax = v_max,
c = colors, alpha = 1.0, label = "Exterior", cmap =
↪c_map)
#
i_plot, k_plot = np.where(body_index[:, j_point, :] == c_exterior)
colors = body_index[i_plot, j_point, k_plot]
ax_xz.scatter(i_plot, k_plot,
marker = m2_exterior, s = s2_exterior, vmin= v_min,
↪vmax = v_max,
c = colors, alpha = 1.0, label = "Exterior", cmap =
↪c_map)
#
j_plot, k_plot = np.where(body_index[i_point, :, :] == c_exterior)
colors = body_index[i_point, j_plot, k_plot]
ax_yz.scatter(j_plot, k_plot,
marker = m2_exterior, s = s2_exterior, vmin= v_min,
↪vmax = v_max,
c = colors, alpha = 1.0, label = "Exterior", cmap =
↪c_map)
#
if plot_end:
i_plot, j_plot = np.where(body_index[:, :, k_point] == c_end)
colors = body_index[i_plot, j_plot, k_point]
ax_xy.scatter(i_plot, j_plot,
marker = m2_end, s = s2_end, vmin= v_min, vmax =
↪v_max,
c = colors, alpha = 1.0, label = "End", cmap = c_map)
#
i_plot, k_plot = np.where(body_index[:, j_point, :] == c_end)
colors = body_index[i_plot, j_point, k_plot]
ax_xz.scatter(i_plot, k_plot,
marker = m2_end, s = s2_end, vmin= v_min, vmax =
↪v_max,
c = colors, alpha = 1.0, label = "End", cmap = c_map)
#
j_plot, k_plot = np.where(body_index[i_point, :, :] == c_end)
colors = body_index[i_point, j_plot, k_plot]
ax_yz.scatter(j_plot, k_plot,
marker = m2_end, s = s2_end, vmin= v_min, vmax =
↪v_max,
c = colors, alpha = 1.0, label = "End", cmap = c_map)
#
if plot_neighbour:
i_plot, j_plot = np.where(body_index[:, :, k_point] == c_neighbour)
colors = body_index[i_plot, j_plot, k_point]

```

```

        ax_xy.scatter(i_plot, j_plot,
                      marker = m2_neighbour, s = s2_neighbour, vmin= v_min,
↪vmax = v_max,
                      c = colors, alpha = 1.0, label = "Neighbour", cmap =
↪c_map)
        #
        i_plot, k_plot = np.where(body_index[:, j_point, :] == c_neighbour)
        colors = body_index[i_plot, j_point, k_plot]
        ax_xz.scatter(i_plot, k_plot,
                      marker = m2_neighbour, s = s2_neighbour, vmin= v_min,
↪vmax = v_max,
                      c = colors, alpha = 1.0, label = "Neighbour", cmap =
↪c_map)
        #
        j_plot, k_plot = np.where(body_index[i_point, :, :] == c_neighbour)
        colors = body_index[i_point, j_plot, k_plot]
        ax_yz.scatter(j_plot, k_plot,
                      marker = m2_neighbour, s = s2_neighbour, vmin= v_min,
↪vmax = v_max,
                      c = colors, alpha = 1.0, label = "Neighbour", cmap =
↪c_map)
        #
        if plot_test:
            i_plot, j_plot = np.where(body_index[:, :, k_point] == c_test)
            colors_body = plot_data[i_plot, j_plot, k_point]
            colors_index = body_index[i_plot, j_plot, k_point]
            colors = np.maximum(colors_body, colors_index) + 1
            ax_xy.scatter(i_plot, j_plot,
                          marker = m2_test, s = s2_test, vmin= v_min, vmax =
↪v_max,
                          c = colors, alpha = 1.0, label = title, cmap = c_map)
            #
            i_plot, k_plot = np.where(body_index[:, j_point, :] == c_test)
            colors_body = plot_data[i_plot, j_point, k_plot]
            colors_index = body_index[i_plot, j_point, k_plot]
            colors = np.maximum(colors_body, colors_index) + 1
            ax_xz.scatter(i_plot, k_plot,
                          marker = m2_test, s = s2_test, vmin= v_min, vmax =
↪v_max,
                          c = colors, alpha = 1.0, label = title, cmap = c_map)
            #
            j_plot, k_plot = np.where(body_index[i_point, :, :] == c_test)
            colors_body = plot_data[i_point, j_plot, k_plot]
            colors_index = body_index[i_point, j_plot, k_plot]
            colors = np.maximum(colors_body, colors_index) + 1
            ax_yz.scatter(j_plot, k_plot,

```

```

marker = m2_test, s = s2_test, vmin= v_min, vmax = v_max,
↪v_max,
c = colors, alpha = 1.0, label = title, cmap = c_map)

#
ax_xy.set_xlim(0, n_cells_x + 2*n_edge - 1)
ax_xy.set_ylim(0, n_cells_y + 2*n_edge - 1)
ax_xy.set_xlabel('x')
ax_xy.set_ylabel('y')
ax_xy.legend(loc = 'lower right')
#
ax_xz.set_xlim(0, n_cells_x + 2*n_edge - 1)
ax_xz.set_ylim(0, n_cells_z + 2*n_edge - 1)
ax_xz.set_xlabel('x')
ax_xz.set_ylabel('z')
ax_xz.legend(loc = 'lower right')
#
ax_yz.set_xlim(0, n_cells_y + 2*n_edge - 1)
ax_yz.set_ylim(0, n_cells_z + 2*n_edge - 1)
ax_yz.set_xlabel('y')
ax_yz.set_ylabel('z')
ax_yz.legend(loc = 'lower right')
#
plt.tight_layout()
plt.show()

#
return
#
then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))

```

Date and time 2026-01-10 14:33:54.964266

Date and time 2026-01-10 14:33:54.968202

Time since last check is 0:00:00.003936

1.5.3 Set initial PSA levels

Return to ToC: »

```

[4]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
def initialise_PSA(set_level, r_prop, with_plots, i_plot, j_plot, k_plot):
'''
    Set initial PSA levels for body

```

```

'''
#
debug = False
with_plots = True
#
# For PSA values set 1
if set_level == 2:
    init_fact = 1.0
elif set_level == 1:
    init_fact = 0.5
else:
    init_fact = 0.0001
#
# For PSA values set 2
#init_fact *= 20
#
# PSA array
PSA = np.zeros((n_is, n_js, n_ks))
#
# Set concentration in blood.
n_blood = np.sum(body == c_blood)
if set_level == 2:
    PSA[body == c_blood] = (0.8*init_fact*sig_prostate*np.ones(n_blood)*
                           (1 + r_prop*rng.random(n_blood)))
elif set_level == 1:
    PSA[body == c_blood] = (0.1*init_fact*sig_prostate*np.ones(n_blood)*
                           (1 + r_prop*rng.random(n_blood)))
else:
    PSA[body == c_blood] = 0.0
#
# Set concentration in prostate
n_prostate = np.sum(body == c_prostate)
PSA[body == c_prostate] = (init_fact*sig_prostate*np.ones(n_prostate)*
                           (1 + r_prop*rng.random(n_prostate)))
#
# Set concentration in tumour
n_tumour = np.sum(body == c_tumour)
PSA[body == c_tumour] = (init_fact*sig_tumour*np.ones(n_tumour)*
                        (1 + r_prop*rng.random(n_tumour)))
#
# Set concentration in borders
PSA = set_borders(n_is, n_js, n_ks, PSA)
#
if debug:
    print(" ")
    print(f"Min initial PSA value {np.amin(PSA):.4f}")
    print(f"Max initial PSA value {np.amax(PSA):.4f}")

```

```

#
if with_plots:
    title = "PSA, t = 0"
    v_min = -1.0
    v_max = -1.0
    plot_point = False
    plot_border = True
    plot_blood = True
    plot_prostate = True
    plot_tumour = True
    plot_surface = False
    plot_dup = False
    plot_ext = False
    plot_end = False
    plot_neigh = False
    plot_test = False
    #
    plot_2D = True
    plot_log = False
    #plot_log = True
    #c_map = cm.viridis
    c_map = cm.plasma
    #
    plot_body(title, PSA, body_steer, i_plot, j_plot, k_plot, plot_point,
              plot_border, plot_blood, plot_prostate, plot_tumour,
    ↪plot_surface,
              plot_dup, plot_ext, plot_end, plot_neigh, plot_test, plot_2D,
    ↪plot_log,
              c_map, v_min = v_min, v_max = v_max)
    #
    return PSA
#
then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))

```

Date and time 2026-01-10 14:33:54.975952

Date and time 2026-01-10 14:33:54.976353

Time since last check is 0:00:00.000401

1.5.4 Set PSA level in borders

Return to ToC: »

```

[5]: import datetime
     now = datetime.datetime.now()

```

```

print("Date and time",str(now))
#
def set_borders(n_is, n_js, n_ks, PSA):
    '''
    Set PSA concentrations in border to values in adjacent body cells.
    '''
    i = 0
    for j in range(0, n_js):
        for k in range(0, n_ks):
            PSA[i, j, k] = PSA[i + 1, j, k]
    i = n_is - 1
    for j in range(0, n_js):
        for k in range(0, n_ks):
            PSA[i, j, k] = PSA[i - 1, j, k]
    j = 0
    for i in range(0, n_is):
        for k in range(0, n_ks):
            PSA[i, j, k] = PSA[i, j + 1, k]
    j = n_js - 1
    for i in range(0, n_is):
        for k in range(0, n_ks):
            PSA[i, j, k] = PSA[i, j - 1, k]
    k = 0
    for i in range(0, n_is):
        for j in range(0, n_js):
            PSA[i, j, k] = PSA[i, j, k + 1]
    k = n_ks - 1
    for i in range(0, n_is):
        for j in range(0, n_js):
            PSA[i, j, k] = PSA[i, j, k - 1]
    #
    return PSA
#
then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))

```

Date and time 2026-01-10 14:33:54.983548

Date and time 2026-01-10 14:33:54.984018

Time since last check is 0:00:00.000470

1.5.5 Find exterior cells

Exterior cells are the blood cells immediately outside the prostate and tumour.

Return to ToC: »

```

[6]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
def find_exterior(with_plots):
    '''
    Find cells immediately outside prostate and tumour
    '''
    #
    # Find indices of cells in prostate and tumour
    i_pt, j_pt, k_pt = np.where(np.logical_or(body == c_prostate, body ==
↪c_tumour))
    #
    # Check not at border
    out_of_body = False
    if np.amax(i_pt) + 2 > n_is or np.amin(i_pt) < 2:
        print(f"Body limit reached in x: min(i_pt) = {np.amin(i_pt)}, max(i_pt)
↪= {np.amax(i_pt)}")
        out_of_body = True
    if np.amax(j_pt) + 2 > n_js or np.amin(j_pt) < 2:
        print(f"Body limit reached in y: min(j_pt) = {np.amin(j_pt)}, max(j_pt)
↪= {np.amax(j_pt)}")
        out_of_body = True
    if np.amax(k_pt) + 2 > n_ks or np.amin(k_pt) < 2:
        print(f"Body limit reached in z: min(k_pt) = {np.amin(k_pt)}, max(k_pt)
↪= {np.amax(k_pt)}")
        out_of_body = True
    if out_of_body:
        return body_steer, out_of_body
    #
    n_new = np.sum(i_pt > 0)
    #
    # Find exterior cells and update flags in body_steer
    for n in range(0, n_new):
        indices = i_pt[n] - 1, j_pt[n], k_pt[n]
        if body[indices] == c_blood:
            body_steer[indices] = c_exterior
        #
        indices = i_pt[n] + 1, j_pt[n], k_pt[n]
        if body[indices] == c_blood:
            body_steer[indices] = c_exterior
        #
        indices = i_pt[n], j_pt[n] - 1, k_pt[n]
        if body[indices] == c_blood:
            body_steer[indices] = c_exterior
        #
        indices = i_pt[n], j_pt[n] + 1, k_pt[n]

```

```

        if body[indices] == c_blood:
            body_steer[indices] = c_exterior
        #
        indices = i_pt[n], j_pt[n], k_pt[n] - 1
        if body[indices] == c_blood:
            body_steer[indices] = c_exterior
        #
        indices = i_pt[n], j_pt[n], k_pt[n] + 1
        if body[indices] == c_blood:
            body_steer[indices] = c_exterior
        #
    if with_plots:
        #
        # Make plots showing surface cells
        v_min = -1.0
        v_max = -1.0
        plot_point = False
        plot_border = False
        plot_blood = False
        plot_prostate = False
        plot_tumour = False
        plot_surface = False
        plot_dup = False
        plot_ext = True
        plot_end = False
        plot_neigh = False
        plot_test = False
        #
        plot_2D = True
        plot_log = False
        c_map = cm.viridis
        #
        title = f"Exterior, ({i_tumour}, {j_tumour}, {k_tumour})"
        plot_body(title, body_steer, body_steer, i_tumour, j_tumour, k_tumour,
        ↪plot_point,
                                plot_border, plot_blood, plot_prostate, plot_tumour,
        ↪plot_surface,
                                plot_dup, plot_ext, plot_end, plot_neigh, plot_test, plot_2D,
        ↪plot_log,
                                c_map, v_min = v_min, v_max = v_max)
        #
    return body_steer, out_of_body
#
then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))

```

Date and time 2026-01-10 14:33:54.992689

Date and time 2026-01-10 14:33:54.993175

Time since last check is 0:00:00.000486

1.5.6 Find area of blood/tumour interface

Identify “btcells”, tumour cells in immediate contact with the blood.

Return to ToC: »

```
[7]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
def area_tumour_blood(with_plots, i_time, i_plot, j_plot, k_plot):
    '''
    Find the area of the tumour/blood interface
    '''
    if with_plots:
        body_steer_org = np.zeros((n_is, n_js, n_ks))
        body_steer_org[:] = body_steer[:]
    #
    # Find indices of cells in tumour
    i_t, j_t, k_t = np.where(body == c_tumour)
    #
    n_new = np.sum(i_t > 0)
    area = 0
    #
    # Find interface cells and number of faces in contact with blood cells.
    for n in range(0, n_new):
        cell = i_t[n], j_t[n], k_t[n]
        indices = i_t[n] - 1, j_t[n], k_t[n]
        if body[indices] == c_blood:
            body_steer[cell] = c_test
            area += 1
        #
        indices = i_t[n] + 1, j_t[n], k_t[n]
        if body[indices] == c_blood:
            body_steer[cell] = c_test
            area += 1
        #
        indices = i_t[n], j_t[n] - 1, k_t[n]
        if body[indices] == c_blood:
            body_steer[cell] = c_test
            area += 1
        #
        indices = i_t[n], j_t[n] + 1, k_t[n]
```

```

    if body[indices] == c_blood:
        body_steer[cell] = c_test
        area += 1
    #
    indices = i_t[n], j_t[n], k_t[n] - 1
    if body[indices] == c_blood:
        body_steer[cell] = c_test
        area += 1
    #
    indices = i_t[n], j_t[n], k_t[n] + 1
    if body[indices] == c_blood:
        body_steer[cell] = c_test
        area += 1
    #
    btcell = area > 0
    #
    if with_plots and btcell:
        #
        # Steer plotting
        plot_point = False
        plot_border = True
        plot_blood = True
        plot_prostate = True
        plot_tumour = True
        plot_surface = False
        plot_dup = False
        plot_ext = False
        plot_end = False
        plot_neigh = False
        plot_test = True
        #
        plot_log = False
        plot_2D = False
        #
        v_min = -1.0
        v_max = -1.0
        #
        title = f"Interface, time {i_time}"
        plot_body(title, body, body_steer, i_plot, j_plot, k_plot, plot_point,
                  plot_border, plot_blood, plot_prostate, plot_tumour,
↪plot_surface,
                  plot_dup, plot_ext, plot_end, plot_neigh, plot_test, plot_2D,
↪plot_log,
                  c_map, v_min = v_min, v_max = v_max)
        #
        body_steer[:] = body_steer_org[:]
    #

```

```

    return btcell, area
#
then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))

```

Date and time 2026-01-10 14:33:54.999501

Date and time 2026-01-10 14:33:55.000162

Time since last check is 0:00:00.000661

1.5.7 Diffuse, create and decay PSA

Return to ToC: »

```

[8]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
def do_diffusion(PSA, beta, r_prop, n_times, conv_test,
                 with_init, set_level, with_all_plots, i_plot, j_plot, k_plot):
    """
    Run diffusion for existing body.
    """
    debug = False
    #
    #dt = 0.04 # PSA values set 1
    dt = 0.0001 # PSA values set 2
    nt_min = 2

    #nt_min = 20
    #
    if with_init:
        #
        # Initialise PSA here again so don't have to rerun above cell!
        with_plots = True
        PSA = initialise_PSA(set_level, r_prop, with_plots, i_plot, j_plot,
↪k_plot)
        #
        #c_map = cm.viridis
        c_map = cm.plasma
        #
        # Choose times at which PSA distribution plotted
        make_plot = np.zeros(4).astype(int)
        make_plot[0] = 1
        make_plot[1] = n_times//16
        make_plot[2] = n_times//4

```

```

make_plot[3] = n_times - 1
#
time = np.zeros(n_times)
i_ptime = np.zeros(n_times).astype(int)
n_tplots = 5
tplot_i = np.zeros(n_tplots).astype(int)
tplot_j = np.zeros(n_tplots).astype(int)
tplot_k = np.zeros(n_tplots).astype(int)
tplot_i[0], tplot_j[0], tplot_k[0] = i_plot, j_plot, k_plot
tplot_i[1], tplot_j[1], tplot_k[1] = n_is//2, n_js//2, n_ks//2
tplot_i[2], tplot_j[2], tplot_k[2] = 0, 0, 0
tplot_i[3], tplot_j[3], tplot_k[3] = 1, 1, 1
tplot_i[4], tplot_j[4], tplot_k[4] = n_is//4, n_js//4, n_ks//4
#
t_dev_ijk = np.zeros((n_times, n_tplots))
t_dev_i = np.zeros((n_times, n_is))
t_dev_j = np.zeros((n_times, n_js))
t_dev_k = np.zeros((n_times, n_ks))
#
# Identify exterior cells
with_plots_here = False
body_steer, out_of_body = find_exterior(with_plots_here)
if out_of_body:
    return PSA
#
# Do diffusion
conv = False
for nt in range(0, n_times):
    #
    i_ptime[nt] = nt
    time[nt] = nt*dt
    for tp in range(0, n_tplots):
        t_dev_ijk[nt, tp] = PSA[tplot_i[tp], tplot_j[tp], tplot_k[tp]]
    #
    t_dev_i[nt, :] = PSA[:, j_plot, k_plot]
    t_dev_j[nt, :] = PSA[i_plot, :, k_plot]
    t_dev_k[nt, :] = PSA[i_plot, j_plot, :]
    #
    # Do PSA diffusion
    delta_PSA = np.zeros((n_is, n_js, n_ks))
    #
    for i in range(n_edge, n_cells_x + n_edge):
        for j in range(n_edge, n_cells_y + n_edge):
            for k in range(n_edge, n_cells_z + n_edge):
                #
                # Calculate PSA change for prostate, tumour, "exterior"

```

→ blood

```

        if (body[i, j, k] == c_prostate or
            body[i, j, k] == c_tumour or
            body_steer[i, j, k] == c_exterior):
            delta_PSA[i, j, k] = dt*beta*(PSA[i - 1, j, k] + PSA[i,
↪+ 1, j, k] +
                                                    PSA[i, j - 1, k] + PSA[i,
↪j + 1, k] +
                                                    PSA[i, j, k - 1] + PSA[i,
↪j, k + 1] -
                                                    6*PSA[i, j, k])

        #
        #
        #
        # Find average of change in exterior PSA level
        ext_inds = np.where(body_steer == c_exterior)
        avg_new_PSA = np.average(delta_PSA[ext_inds])
        #
        # Set all blood changes to average external PSA value
        delta_PSA[body == c_blood] = avg_new_PSA
        #
        # Do PSA decay
        n_blood = np.sum(body == c_blood)
        delta_PSA[body == c_blood] -= dt/tau_blood*PSA[body == c_blood]
        #
        n_prostate = np.sum(body == c_prostate)
        delta_PSA[body == c_prostate] -= dt/tau_prostate*PSA[body == c_prostate]
        #
        n_tumour = np.sum(body == c_tumour)
        delta_PSA[body == c_tumour] -= dt/tau_tumour*PSA[body == c_tumour]
        #
        # Do PSA creation
        delta_PSA[body == c_prostate] += \
            dt*sig_prostate*np.ones(n_prostate)*(1 + r_prop*rng.
↪random(n_prostate))
        #
        delta_PSA[body == c_tumour] += \
            dt*sig_tumour*np.ones(n_tumour)*(1 + r_prop*rng.random(n_tumour))
        #
        PSA = PSA + delta_PSA
        #
        # Update border
        PSA = set_borders(n_is, n_js, n_ks, PSA)
        #
        # Interim plot
        if nt in make_plot and with_all_plots:
            if debug:
                print(" ")

```

```

        print(f"Min PSA value {np.amin(PSA):.4f}")
        print(f"Max PSA value {np.amax(PSA):.4f}")
    #
    # Steer plotting
    plot_point = False
    plot_border = True
    plot_blood = True
    plot_prostate = True
    plot_tumour = True
    plot_surface = False
    plot_dup = False
    plot_ext = False
    plot_end = False
    plot_neigh = False
    plot_test = False
    #
    #plot_log = True
    plot_log = False
    plot_2D = True
    #
    #v_min = -6.0
    #v_max = 1.5
    v_min = -1.0
    v_max = -1.0
    #
    title = f"PSA, t = {nt}"
    plot_body(title, PSA, body_steer, i_plot, j_plot, k_plot,
    ↪plot_point,
                                plot_border, plot_blood, plot_prostate, plot_tumour,
    ↪plot_surface,
                                plot_dup, plot_ext, plot_end, plot_neigh, plot_test,
    ↪plot_2D, plot_log,
                                c_map, v_min = v_min, v_max = v_max)

    #
    ext_test = abs(np.amax(delta_PSA[ext_inds]/PSA[ext_inds]))
    inds_here = np.logical_or(body == c_prostate, body == c_tumour)
    prostate_test = abs(np.amax(delta_PSA[inds_here]/PSA[inds_here]))
    epsilon = 1e-28
    if (epsilon < ext_test < conv_test and
        epsilon < prostate_test < conv_test and
        nt > nt_min):
        print(f"Diffusion converged, nt = {nt}, ext_test = {ext_test:.6e}, "
              f"prostate_test = {prostate_test:.6e}")
        conv = True
        break

    #
    if not conv:

```

```

        print(f"Diffusion didn't converge, nt = {nt}, ext_test = {ext_test:.
↪6e}, "
              f"prostate_test = {prostate_test:.6e}")

        #
        title = f"PSA, t = {nt}"
        plot_point = False
        plot_border = True
        plot_blood = True
        plot_prostate = True
        plot_tumour = True
        plot_surface = False
        plot_dup = False
        plot_ext = False
        plot_end = False
        plot_neigh = False
        plot_test = False
        #
        plot_2D = True
        #plot_log = True
        plot_log = False
        #
        #v_min = -6.0
        #v_max = 1.5
        v_min = -1.0
        v_max = -1.0
        #
        if debug:
            print(" ")
            print(f"Min PSA value {np.amin(PSA):.4f}")
            print(f"Max PSA value {np.amax(PSA):.4f}")
        #
        plot_body(title, PSA, body_steer, i_plot, j_plot, k_plot, plot_point,
                  plot_border, plot_blood, plot_prostate, plot_tumour, plot_surface,
                  plot_dup, plot_ext, plot_end, plot_neigh, plot_test, plot_2D,
↪plot_log,
                  c_map, v_min = v_min, v_max = v_max)

        #
        i_ptime = i_ptime[0:nt]
        tplot_i = tplot_i[0:nt]
        tplot_j = tplot_j[0:nt]
        tplot_k = tplot_k[0:nt]
        t_dev_ijk = t_dev_ijk[0:nt, :]
        t_dev_i = t_dev_i[0:nt, :]
        t_dev_j = t_dev_j[0:nt, :]
        t_dev_k = t_dev_k[0:nt, :]
        #

```

```

    plot_time_dev(iptime, tplot_i, tplot_j, tplot_k, t_dev_ijk, t_dev_i,
    ↪t_dev_j, t_dev_k,
                i_plot, j_plot, k_plot)

    #
    return PSA
#
then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))

```

Date and time 2026-01-10 14:33:55.013741

Date and time 2026-01-10 14:33:55.014892

Time since last check is 0:00:00.001151

1.5.8 Plot time development of PSA levels

The “time” here is that required for the PSA levels to reach a stable(ish) state.

Return to ToC: »

```

[9]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
def plot_time_dev(time, tplot_i, tplot_j, tplot_k, t_dev_ijk, t_dev_i, t_dev_j,
    ↪t_dev_k,
                i_plot, j_plot, k_plot):
    """
    Plot time development of PSA concentrations at some specified points, given
    ↪in t_dev_ijk, and
    along lines defined by i_plot, j_plot and k_plot.
    Make sure the maximum concentrations are in the zeroth component of
    ↪t_dev_ijk if you want
    to use the scaling that comes when plot_log = False!
    """
    #
    debug = False
    #
    plot_log = True
    #
    # Set times at which lines in i, j, and k are displayed
    plot_time_A = min(5, np.amax(time).astype(int))
    plot_step_A = 1
    plot_time_B = min(30, np.amax(time).astype(int))
    plot_step_B = 10
    plot_time_C = np.amax(time).astype(int)

```

```

plot_step_C = max(np.amax(time).astype(int)//10, 1)
#
# Make plots at specified points
n_tplots = len(tplot_i)
#
fig = plt.figure(figsize = (7, 12))
#
ax = fig.add_subplot(4, 1, 1)
ax.set_title(f"PSA with t at specified points")
ax.set_xlabel("t")
if plot_log:
    ax.set_ylabel("log(PSA)")
    for tp in range(0, n_tplots):
        bool_plot = t_dev_ijk[:, tp] > 0
        ax.plot(time[bool_plot], np.log(t_dev_ijk[bool_plot, tp]),
                label = f"({tplot_i[tp]}, {tplot_j[tp]}, {tplot_k[tp]})")
else:
    max_zero = np.amax(t_dev_ijk[:, 0])
    max_other = np.amax(t_dev_ijk[:, 1:n_tplots])
    max_ratio = max_zero/max_other
    ax.set_ylabel("PSA")
    for tp in range(0, n_tplots):
        scale = 1 + 0.2*max_ratio*(tp > 0)
        ax.plot(time[:, tp], scale*t_dev_ijk[:, tp],
                label = f"scale {scale:.0f}, ({tplot_i[tp]}, {tplot_j[tp]}, {tplot_k[tp]})")
ax.grid(color = 'g')
ax.legend(loc = "upper right")
#
# Make plot at fixed i
plot_log = True
#
cell_x = np.linspace(0, n_is - 1, n_is)
cell_y = np.linspace(0, n_js - 1, n_js)
cell_z = np.linspace(0, n_ks - 1, n_ks)
#
ax = fig.add_subplot(4, 1, 2)
ax.set_title(f"PSA with t along x at i = {i_plot}")
ax.set_xlabel("x")
ax.set_ylabel("PSA")
for nt in range(0, plot_time_A, plot_step_A):
    ax.plot(cell_x[:, nt], t_dev_i[nt, :], label = f"t = {nt}")
for nt in range(plot_time_A, plot_time_B, plot_step_B):
    ax.plot(cell_x[:, nt], t_dev_i[nt, :], label = f"t = {nt}")
for nt in range(plot_time_B, plot_time_C, plot_step_C):
    if nt == plot_time_B:
        ax.plot(cell_x[:, nt], t_dev_i[nt, :], label = f"Others, t  $\geq$  {nt}")

```

```

        else:
            ax.plot(cell_x[:,], t_dev_i[nt, :])
    if plot_log:
        ax.set_yscale('log')
    ax.grid(color = 'g')
    ax.legend()
    #
    # Make plot at fixed j
    ax = fig.add_subplot(4, 1, 3)
    ax.set_title(f"PSA with time along y at j = {j_plot}")
    ax.set_xlabel("y")
    ax.set_ylabel("PSA")
    for nt in range(0, plot_time_A, plot_step_A):
        ax.plot(cell_y[:,], t_dev_j[nt, :], label = f"t = {nt}")
    for nt in range(plot_time_A, plot_time_B, plot_step_B):
        ax.plot(cell_y[:,], t_dev_j[nt, :], label = f"t = {nt}")
    for nt in range(plot_time_B, plot_time_C, plot_step_C):
        if nt == plot_time_B:
            ax.plot(cell_y[:,], t_dev_j[nt, :], label = f"Others, t  $\geq$  {nt}")
        else:
            ax.plot(cell_y[:,], t_dev_j[nt, :])
    if plot_log:
        ax.set_yscale('log')
    ax.grid(color = 'g')
    ax.legend()
    #
    # Make plot at fixed k
    ax = fig.add_subplot(4, 1, 4)
    ax.set_title(f"PSA with t along z at k = {k_plot}")
    ax.set_xlabel("z")
    ax.set_ylabel("PSA")
    for nt in range(0, plot_time_A, plot_step_A):
        ax.plot(cell_z[:,], t_dev_k[nt, :], label = f"t = {nt}")
    for nt in range(plot_time_A, plot_time_B, plot_step_B):
        ax.plot(cell_z[:,], t_dev_k[nt, :], label = f"t = {nt}")
    for nt in range(plot_time_B, plot_time_C, plot_step_C):
        if nt == plot_time_B:
            ax.plot(cell_z[:,], t_dev_k[nt, :], label = f"Others, t  $\geq$  {nt}")
        else:
            ax.plot(cell_z[:,], t_dev_k[nt, :])
            ax.plot(cell_z[:,], t_dev_k[nt, :])
    if plot_log:
        ax.set_yscale('log')
    ax.grid(color = 'g')
    ax.legend()
    #
    plt.tight_layout()

```

```

plt.show()
#
return
#
then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))

```

Date and time 2026-01-10 14:33:55.025138

Date and time 2026-01-10 14:33:55.025942

Time since last check is 0:00:00.000804

1.5.9 Choose position for duplicate cell

Return to ToC: »

```

[10]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
def find_duplicator(with_plots):
    '''
    Find one of cells in tumour surface to serve as position of duplicate
    '''
    debug = False
    #
    # Check whether there is already a duplicate (can only do one at a time!)
    if np.sum(body_steer == c_duplicate) > 0:
        print(" ")
        print("Found pre-existing duplicate in find_duplicator - stop")
        sys.exit(0)
    #
    duplicate = np.zeros(3).astype(int)
    #
    # Find indices of cells in tumour
    out_of_body = False
    i_t, j_t, k_t = np.where(body == c_tumour)
    if np.amax(i_t) + 2 > n_is or np.amin(i_t) < 2:
        print(f"Body limit reached in x: min(i_t) = {np.amin(i_t)}, max(i_t) = {np.amax(i_t)}")
        out_of_body = True
    if np.amax(j_t) + 2 > n_js or np.amin(j_t) < 2:
        print(f"Body limit reached in y: min(j_t) = {np.amin(j_t)}, max(j_t) = {np.amax(j_t)}")
        out_of_body = True
    if np.amax(k_t) + 2 > n_ks or np.amin(k_t) < 2:

```

```

        print(f"Body limit reached in z: min(k_t) = {np.amin(k_t)}, max(k_t) = {
↪ np.amax(k_t)}")
        out_of_body = True
    #
    if out_of_body:
        return duplicate, body_steer, out_of_body
    #
    n_t = len(i_t)
    #
    # Find surface cells and update flags in body_steer array
    for n in range(0, n_t):
        indices = i_t[n] - 1, j_t[n], k_t[n]
        if body[indices] != c_tumour:
            body_steer[indices] = c_surface
        #
        indices = i_t[n] + 1, j_t[n], k_t[n]
        if body[indices] != c_tumour:
            body_steer[indices] = c_surface
        #
        indices = i_t[n], j_t[n] - 1, k_t[n]
        if body[indices] != c_tumour:
            body_steer[indices] = c_surface
        #
        indices = i_t[n], j_t[n] + 1, k_t[n]
        if body[indices] != c_tumour:
            body_steer[indices] = c_surface
        #
        indices = i_t[n], j_t[n], k_t[n] - 1
        if body[indices] != c_tumour:
            body_steer[indices] = c_surface
        #
        indices = i_t[n], j_t[n], k_t[n] + 1
        if body[indices] != c_tumour:
            body_steer[indices] = c_surface
        #
    if with_plots:
        #
        # Make plots showing surface cells
        v_min = -1.0
        v_max = -1.0
        #
        plot_point = False
        plot_border = False
        plot_blood = False
        plot_prostate = False
        plot_tumour = False
        plot_surface = True

```

```

    plot_dup = False
    plot_ext = False
    plot_end = False
    plot_neigh = False
    plot_test = False
    #
    plot_2D = True
    plot_log = False
    c_map = cm.viridis
    #
    title = f"Surface ({i_tumour}, {j_tumour}, {k_tumour})"
    plot_body(title, body_steer, body_steer, i_tumour, j_tumour, k_tumour,
    ↪plot_point,
        plot_border, plot_blood, plot_prostate, plot_tumour,
    ↪plot_surface,
        plot_dup, plot_ext, plot_end, plot_neigh, plot_test, plot_2D,
    ↪plot_log,
        c_map, v_min = v_min, v_max = v_max)

    #
    # Randomly choose surface cell for duplication
    surface = np.where(body_steer == c_surface)
    i_surface = surface[0]
    j_surface = surface[1]
    k_surface = surface[2]
    n_surface = len(i_surface)
    ind_dup = rng.integers(0, high = n_surface, size = 1)[0]
    i_dup = i_surface[ind_dup]
    j_dup = j_surface[ind_dup]
    k_dup = k_surface[ind_dup]
    #
    duplicate[0] = i_dup
    duplicate[1] = j_dup
    duplicate[2] = k_dup
    #
    if debug:
        print(" ")
        print(f"i_t {i_t}")
        print(f"j_t {j_t}")
        print(f"k_t {k_t}")
        print(f"i_surface {i_surface}, j_surface {j_surface}, k_surface
    ↪{k_surface}")
        print(f"n_surface {n_surface}")
        print(f"ind_dup {ind_dup}")
        print(f"i_dup {i_dup}, j_dup {j_dup}, k_dup {k_dup}")
        print(f"Duplicate body type {body[i_dup, j_dup, k_dup]}")
    #

```

```

    # Keep this below the debug printout above or you will get confused as
    ↪ c_duplicate
    # overwrites one of the surface values!
    body_steer[i_dup, j_dup, k_dup] = c_duplicate
    #
    if with_plots:
        #
        # Make plot showing the cell to be duplicated
        v_min = -1.0
        v_max = -1.0
        #
        plot_point = False
        plot_border = False
        plot_blood = False
        plot_prostate = False
        plot_tumour = False
        plot_surface = True
        plot_dup = True
        plot_ext = False
        plot_end = False
        plot_neigh = False
        plot_test = False
        #
        plot_2D = True
        plot_log = False
        c_map = cm.viridis
        #
        title = f"Duplicate ({i_dup}, {j_dup}, {k_dup})"
        plot_body(title, body_steer, body_steer, i_tumour, j_tumour, k_tumour,
        ↪ plot_point,
                plot_border, plot_blood, plot_prostate, plot_tumour,
        ↪ plot_surface,
                plot_dup, plot_ext, plot_end, plot_neigh, plot_test, plot_2D,
        ↪ plot_log,
                c_map, v_min = v_min, v_max = v_max)
        #
        #
        return duplicate, body_steer, out_of_body
#
then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))

```

Date and time 2026-01-10 14:33:55.036898

Date and time 2026-01-10 14:33:55.037734

Time since last check is 0:00:00.000836

1.5.10 Show all changes in body

Return to ToC: »

```
[11]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
def show_change(body_org, i_plot, j_plot, k_plot, with_plots, title):
    '''
        Plot changes due to duplication(s). Highlight changes between body_org and
        ↪current body.
    '''
    debug = False
    #
    body_change = np.zeros((n_is, n_js, n_ks))
    #
    # Label changes as test
    body_change[body != body_org] = c_test
    if debug:
        print(" ")
        print("np.where(body_change == c_test)",np.where(body_change == c_test))
    #
    i_change, j_change, k_change = np.where(body_change == c_test)
    if debug:
        print(" ")
        print(f"Number of body changes detected {int(np.sum(body_change ==
        ↪c_test)))}")
        print(f"Change i min {np.amin(i_change)}, i max {np.amax(i_change)}")
        print(f"Change j min {np.amin(j_change)}, j max {np.amax(j_change)}")
        print(f"Change k min {np.amin(k_change)}, k max {np.amax(k_change)}")
        print(" ")
        print(f"Change x min {cell_x[np.amin(i_change)]}, x max {cell_x[np.
        ↪amax(i_change)]}")
        print(f"Change y min {cell_y[np.amin(j_change)]}, y max {cell_y[np.
        ↪amax(j_change)]}")
        print(f"Change z min {cell_z[np.amin(k_change)]}, z max {cell_z[np.
        ↪amax(k_change)]}")
        print(" ")
        print(f"Prostate centre, indices {i_prostate}, {j_prostate},
        ↪{k_prostate}")
        print(f"Prostate radius {prostate_rad}")
        print(" ")
        print(f"Tumour centre, indices {i_tumour}, {j_tumour}, {k_tumour}")
        print(f"Tumour radius {tumour_rad}")
```

```

#
# Make plot showing changes due to duplication
if with_plots:
    print("")
    v_min = -1.0
    v_max = -1.0
    #
    plot_point = True
    plot_border = False
    plot_blood = False
    plot_prostate = False
    plot_tumour = False
    plot_surface = False
    plot_dup = False
    plot_ext = False
    plot_end = False
    plot_neigh = False
    plot_test = True
    #
    plot_2D = True
    plot_log = False
    c_map = cm.viridis
    #
    plot_body(title, body_change, body_change, i_plot, j_plot, k_plot,
    ↪plot_point,
    plot_border, plot_blood, plot_prostate, plot_tumour,
    ↪plot_surface,
    plot_dup, plot_ext, plot_end, plot_neigh, plot_test, plot_2D,
    ↪plot_log,
    c_map, v_min = v_min, v_max = v_max)

    return
#
then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))

```

Date and time 2026-01-10 14:33:55.045047

Date and time 2026-01-10 14:33:55.045475

Time since last check is 0:00:00.000428

1.5.11 Find new cell positions

Return to ToC: »

```

[12]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
def position_finder(body_steer, i_dup, j_dup, k_dup, with_plots):
    '''
        Find the "neighbour" cell position to accommodate the "duplicate" and the
        ↪ "end" position
        for the neighbour. The end is a position outside the prostate and tumour.
        ↪ If
        compact is True, an attempt is first made to find a neighbour that is not
        ↪ part of the tumour
        and after that, tumour cells are allowed to be neighbours. If compact is
        ↪ False,
        tumour cells are allowed to be neighbours from the start.
    '''
    debug = False
    compact = True
    #
    neighbour = np.zeros(3).astype(int)
    end_point = np.zeros(3).astype(int)
    #
    # Check whether there are too many duplicates (can only do one at a time!)
    n_duplicates = np.sum(body_steer == c_duplicate)
    if n_duplicates > 1:
        print(" ")
        print(f"Found {n_duplicates} duplicates in position_finder - stop")
        sys.exit(0)
    #
    # Find distances from cell to be duplicated to exterior cells
    # If find_exterior has already been run, don't do it again!
    n_ext = np.sum(body_steer == c_exterior)
    if n_ext < 1:
        body_steer, out_of_body = find_exterior(with_plots)
        if out_of_body:
            return body_steer, neighbour, end_point, out_of_body
    #
    n_ext = np.sum(body_steer == c_exterior)
    d_to_e_sq = np.zeros(n_ext)
    i_d_to_e, j_d_to_e, k_d_to_e = np.where(body_steer == c_exterior)
    d_to_e_sq = (i_dup - i_d_to_e)**2 + (j_dup - j_d_to_e)**2 + (k_dup -
    ↪ k_d_to_e)**2
    #
    # Find indices in dup_to_ext_sq that give minimum distance
    min_dist_ind = np.argsort(d_to_e_sq)
    #

```

```

    # Randomly order min_dist_ind where there are groups of distances that are
    the same
    # (Not sure that this is necessary!)
    new_dist_ind = np.zeros(n_ext).astype(int)
    #
    un_dist_array, un_dist_ind, n_un_dist = np.unique(d_to_e_sq, return_index =
    True,

                                                    return_inverse = False,
                                                    return_counts = True)

    n_groups = len(n_un_dist)
    n_bot = 0
    for n in range(0, n_groups):
        n_top = n_bot + n_un_dist[n]
        inds_here = np.zeros(n_un_dist[n]).astype(int)
        inds_here[0:n_un_dist[n]] = min_dist_ind[n_bot:n_top]
        rng.shuffle(inds_here)
        new_dist_ind[n_bot:n_top] = inds_here[0:n_un_dist[n]]
        n_bot = n_top

    #
    # Use below rather than above if don't want to do explicit random ordering!
    #new_dist_ind = min_dist_ind
    #
    # Define "end" cell, checking that it is not same as duplicate.
    duplicate = np.array([i_dup, j_dup, k_dup]).astype(int)
    origin = np.zeros(3).astype(int)
    end_test = np.zeros(3).astype(int)
    if debug:
        print(" ")
        print("Find end point")
        print("No. in exterior, len(min_dist_ind)", len(min_dist_ind))
        print("i_dup, j_dup, k_dup", i_dup, j_dup, k_dup)

    #
    w = 0
    out_of_body = False
    while w < len(new_dist_ind) and np.all(end_point == origin):
        min_ind = new_dist_ind[w]
        end_test[0] = i_d_to_e[min_ind]
        end_test[1] = j_d_to_e[min_ind]
        end_test[2] = k_d_to_e[min_ind]
        if debug:
            print(f"w {w}, end_point {end_point}, end_test {end_test}")
        if not np.all(end_test == duplicate):
            min_d_to_e = min_ind
            end_point[:] = end_test[:]
        w += 1
    if np.all(end_point == origin):
        print(" ")

```

```

    print("No end point found - stop")
    sys.exit(0)
if debug:
    print(" ")
    print(f"duplicate {duplicate}")
    print(f"end_point {end_point}")
#
i_end, j_end, k_end = end_point[0], end_point[1], end_point[2]
if i_end > n_is - 2 or i_end < 2:
    print(" ")
    print(f"End point out of body, i_end {i_end}")
    out_of_body = True
if j_end > n_js - 2 or j_end < 2:
    print(" ")
    print(f"End point out of body, j_end {j_end}")
    out_of_body = True
if k_end > n_ks - 2 or k_end < 2:
    print(" ")
    print(f"End point out of body, k_end {k_end}")
    out_of_body = True
if out_of_body:
    return body_steer, neighbour, end_point, out_of_body
#
body_steer[i_end, j_end, k_end] = c_end
#
if with_plots:
    #
    # Make plot showing the cell to be duplicated and end cell
    v_min = -1.0
    v_max = -1.0
    plot_point = False
    plot_border = False
    plot_blood = False
    plot_prostate = False
    plot_tumour = False
    plot_surface = True
    plot_dup = True
    plot_ext = True
    plot_end = True
    plot_neigh = False
    plot_test = False
    #
    plot_2D = True
    plot_log = False
    c_map = cm.viridis
    #
    title = f"End ({i_end}, {j_end}, {k_end})"

```

```

        plot_body(title, body_steer, body_steer, i_end, j_end, k_end,
        ↪plot_point,
                plot_border, plot_blood, plot_prostate, plot_tumour,
        ↪plot_surface,
                plot_dup, plot_ext, plot_end, plot_neigh, plot_test, plot_2D,
        ↪plot_log,
                c_map, v_min = v_min, v_max = v_max)

    #
    # Choose "neighbour" cell to shift to end position. Cell adjacent to
    ↪duplicate can be prostate,
    # tumour or blood. Will be shifted to blood position. Pick cell to shift at
    ↪random,
    # but check it isn't the end_point cell. If compact is True, check also that
    ↪it's
    # not a tumour cell!
    if i_dup > n_is - 2 or i_dup < 2:
        print(" ")
        print(f"Duplicate point out of body, i_dup {i_dup}")
        out_of_body = True
    if j_dup > n_js - 2 or j_dup < 2:
        print(" ")
        print(f"Duplicate point out of body, j_dup {j_dup}")
        out_of_body = True
    if k_dup > n_ks - 2 or k_dup < 2:
        print(" ")
        print(f"Duplicate point out of body, k_dup {k_dup}")
        out_of_body = True
    if out_of_body:
        return body_steer, neighbour, end_point, out_of_body

    #
    chooser = np.linspace(0, 5, 6).astype(int)
    rng.shuffle(chooser)
    neighbours = np.zeros((6, 3)).astype(int)
    neighbours[0, :] = np.array([i_dup - 1, j_dup, k_dup])
    neighbours[1, :] = np.array([i_dup + 1, j_dup, k_dup])
    neighbours[2, :] = np.array([i_dup, j_dup - 1, k_dup])
    neighbours[3, :] = np.array([i_dup, j_dup + 1, k_dup])
    neighbours[4, :] = np.array([i_dup, j_dup, k_dup - 1])
    neighbours[5, :] = np.array([i_dup, j_dup, k_dup + 1])

    #
    origin = np.zeros(3).astype(int)
    if debug:
        print(" ")
        print("Find neighbour")

    #
    if compact:

```

```

w = 0
while w < 6 and np.all(neighbour == origin):
    if not np.logical_or(np.all(neighbours[chooser[w], :] == end_point),
                          body[*neighbours[chooser[w]]] ==
↪c_tumour):
        neighbour[:] = neighbours[w, :]
        if debug:
            print(f"neighbour one, w {w}, end_point {end_point}, end_test_
↪{end_test}")
        w += 1
if np.all(neighbour == origin):
    w = 0
    while w < 6 and np.all(neighbour == origin):
        if not np.all(neighbours[chooser[w], :] == end_point):
            neighbour[:] = neighbours[chooser[w], :]
            if debug:
                print(f"neighbour two, w {w}, end_point {end_point}, end_test_
↪{end_test}")
            w += 1
    #
if np.all(neighbour == origin):
    print(" ")
    print("No neighbour found - stop")
    sys.exit(0)
#
body_steer[neighbour[0], neighbour[1], neighbour[2]] = c_neighbour
if debug:
    print(" ")
    print(f"duplicate {duplicate}")
    print(f"end_point {end_point}")
    print(f"neighbour {neighbour}")
if with_plots:
    #
    # Make plot showing neighbour, cell to be duplicated and end cell
    print(" ")
    print("duplicate", i_dup, j_dup, k_dup)
    print("number of duplicates", np.sum(body_steer == c_duplicate))
    v_min = -1.0
    v_max = -1.0
    plot_point = False
    plot_border = False
    plot_blood = False
    plot_prostate = False
    plot_tumour = False
    plot_surface = True
    plot_dup = True
    plot_ext = True

```

```

        plot_end = True
        plot_neigh = True
        plot_test = False
        #
        plot_2D = True
        plot_log = False
        c_map = cm.viridis
        #
        title = f"Neighbour ({neighbour[0]}, {neighbour[1]}, {neighbour[2]})"
        plot_body(title, body_steer, body_steer, *neighbour, plot_point,
                  plot_border, plot_blood, plot_prostate, plot_tumour,
↪plot_surface,
                  plot_dup, plot_ext, plot_end, plot_neigh, plot_test, plot_2D,
↪plot_log,
                  c_map, v_min = v_min, v_max = v_max)
        #
        return body_steer, neighbour, end_point, out_of_body
#
then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))

```

Date and time 2026-01-10 14:33:55.062920

Date and time 2026-01-10 14:33:55.064442

Time since last check is 0:00:00.001522

1.5.12 Shift cells to new positions

Return to ToC: »

```

[13]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
def cell_shifter(duplicate, neighbour, end_point, with_plots):
    '''
    Shift the "neighbour" cell in the body array to the "end" position and the
    "duplicate" to the neighbour position.
    '''
    debug = False
    #
    if debug:
        print(f" ")
        print(f"duplicate {duplicate}")
        print(f"end_point {end_point}")
        print(f"neighbour {neighbour}")

```

```

    print(" ")
    print("Initial values")
    print("body[*duplicate]", body[*duplicate])
    print("body[*neighbour]", body[*neighbour])
    print("body[*end_point]", body[*end_point])
#
body[*end_point] = body[*neighbour]
body[*neighbour] = body[*duplicate]
body[*duplicate] = c_tumour
#
if debug:
    print(" ")
    print("New values")
    print("body[*duplicate]", body[*duplicate])
    print("body[*neighbour]", body[*neighbour])
    print("body[*end_point]", body[*end_point])
#
if with_plots:
    #
    # Make plot showing results of copying
    v_min = -1.0
    v_max = -1.0
    plot_point = False
    plot_border = False
    plot_blood = True
    plot_prostate = True
    plot_tumour = True
    plot_surface = False
    plot_dup = False
    plot_ext = False
    plot_end = False
    plot_neigh = False
    plot_test = False
    #
    plot_2D = True
    plot_log = False
    c_map = cm.viridis
    #
    title = "After PSA update"
    plot_body(title, body, PSA, i_end, j_end, k_end, plot_point,
              plot_border, plot_blood, plot_prostate, plot_tumour,
↳ plot_surface,
              plot_dup, plot_ext, plot_end, plot_neigh, plot_test, plot_2D,
↳ plot_log,
              c_map, v_min = v_min, v_max = v_max)
    #
    return body

```

```
#
then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))
```

Date and time 2026-01-10 14:33:55.071540

Date and time 2026-01-10 14:33:55.072171

Time since last check is 0:00:00.000631

1.5.13 Update PSA array

Return to ToC: »

```
[14]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
def PSA_updater(PSA, duplicate, neighbour, endpoint, with_plots):
    """
    Update the PSA array using the "neighbour", "end", and "duplicate"
    ↪positions.
    """
    debug = False
    #
    PSA[*end_point] = PSA[*neighbour]
    PSA[*neighbour] = PSA[*duplicate]
    PSA[*duplicate] = np.mean(PSA[body == c_tumour])
    #
    if with_plots:
        #
        # Make plot showing results of updating
        v_min = -1.0
        v_max = -1.0
        plot_point = False
        plot_border = False
        plot_blood = True
        plot_prostate = True
        plot_tumour = True
        plot_surface = False
        plot_dup = False
        plot_ext = False
        plot_end = False
        plot_neigh = False
        plot_test = False
        #
        plot_2D = True
```

```

        plot_log = False
        #c_map = cm.viridis
        c_map = cm.plasma
        #
        title = "After PSA update"
        plot_body(title, body, PSA, i_end, j_end, k_end, plot_point,
                  plot_border, plot_blood, plot_prostate, plot_tumour,
        ↪plot_surface,
                  plot_dup, plot_ext, plot_end, plot_neigh, plot_test, plot_2D,
        ↪plot_log,
                  c_map, v_min = v_min, v_max = v_max)

        #
        return PSA
#
then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))

```

Date and time 2026-01-10 14:33:55.077794

Date and time 2026-01-10 14:33:55.078147

Time since last check is 0:00:00.000353

1.5.14 Reset body steering values

Return to ToC: »

```

[15]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
def body_steer_reset(with_plots):
    '''
    Reset indices in body_steer used to indicate surface cells, cell to
    ↪duplicate,
    exterior cells etc.
    '''
    #
    # Surface
    bool_sel = np.where(body_steer == c_surface)
    body_steer[bool_sel] = 0
    #
    # Duplicate
    bool_sel = np.where(body_steer == c_duplicate)
    body_steer[bool_sel] = 0
    #
    # Exterior

```

```

bool_sel = np.where(body_steer == c_exterior)
body_steer[bool_sel] = 0
#
# End
bool_sel = np.where(body_steer == c_end)
body_steer[bool_sel] = 0
#
# Neighbour
bool_sel = np.where(body_steer == c_neighbour)
body_steer[bool_sel] = 0
#
# Test
bool_sel = np.where(body_steer == c_test)
body_steer[bool_sel] = 0
#
if with_plots:
    #
    # Make plot showing result of reset
    v_min = -1.0
    v_max = -1.0
    plot_point = False
    plot_border = True
    plot_blood = True
    plot_prostate = True
    plot_tumour = True
    plot_surface = True
    plot_dup = True
    plot_ext = True
    plot_end = True
    plot_neigh = True
    plot_test = True
    #
    plot_2D = True
    plot_log = False
    c_map = cm.viridis
    #
    title = "After reset"
    plot_body(title, body_steer, body_steer, i_dup, j_dup, k_dup,
    ↪plot_point,
    plot_border, plot_blood, plot_prostate, plot_tumour,
    ↪plot_surface,
    plot_dup, plot_ext, plot_end, plot_neigh, plot_test, plot_2D,
    ↪plot_log,
    c_map, v_min = v_min, v_max = v_max)
    #
    return body_steer
#

```

```

then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))

```

Date and time 2026-01-10 14:33:55.084385

Date and time 2026-01-10 14:33:55.084773

Time since last check is 0:00:00.000388

1.6 Overview of running of model

In order to investigate changes in PSA as prostate cancer develops: 1) Initialise body structure: border, blood, and prostate. 2) Initialise PSA levels. 3) Run diffusion to get a “zero” point. 4) Add a tumour cell or cells. 5) Initialise PSA levels with the tumour. 6) Run diffusion. 7) Grow the tumour. 8) Run diffusion.

Repeat 7) and 8) until maximum required (or possible) tumour size reached.

After each run of diffusion, record the PSA level in the blood and other relevant variables.

1.7 Run complete model

Return to ToC: »

```

[19]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
# Set number of PSA arrays
# triple True and double True implies use PSA_top, PSA_mid and PSA_bot
# triple False and double True implies use PSA_top and PSA_bot
# triple and double False implies use PSA_top only.
# To get top and bottom limits (using triple or double), set with_init True.
# If have wuth_init True and triple and double False, PSA_top array will be
↪reinitialised
# after each duplication. If with_init is False, initialisation only happens
↪when the
# body is first created.
triple = False
double = False
with_init = False
growth_rate = 0.2
#n_real_times = 45
#n_real_times = 35
n_real_times = 25
#
# Set cell codes
#
c_test = -1

```

```

c_border = 1
c_blood = 2
c_prostate = 3
c_tumour = 4
c_next = 5
#
c_surface = 1
c_duplicate = 2
c_exterior = 3
c_end = 4
c_neighbour = 5
#
# Initialise body without tumour
#
debug = False
with_plots = False
#
# Width of edge of array, n_edge, should be set to 1.
#(The name n_edge is used as a reminder throughout that there is an edge!)
n_edge = 1
#
# Number of cells
#n_cells_x, n_cells_y, n_cells_z = 25, 27, 29
n_cells_x, n_cells_y, n_cells_z = 45, 47, 49
#n_cells_x, n_cells_y, n_cells_z = 50, 52, 54
#n_cells_x, n_cells_y, n_cells_z = 60, 62, 64
#n_cells_x, n_cells_y, n_cells_z = 70, 72, 74
#n_cells_x, n_cells_y, n_cells_z = 84, 84, 84
#
# Number of cells in body array
n_is = n_cells_x + 2*n_edge
n_js = n_cells_y + 2*n_edge
n_ks = n_cells_z + 2*n_edge
n_body = n_is*n_js*n_ks
body = np.zeros((n_is, n_js, n_ks)).astype(int)
body_steer = np.zeros((n_is, n_js, n_ks)).astype(int)
#
print(" ")
print(f"Body dimensions {n_is} in x, {n_js} in y, {n_ks} in z.")
print(f"Body size {n_body} cells.")
#
# Define prostate centre and radius (can be in centre of body or offset to_
↪allow for more growth)
centre = True
#
prostate_rad = 8
prostate_rad_2 = prostate_rad**2

```

```

#
if centre:
    i_prostate = n_edge + n_cells_x//2
    j_prostate = n_edge + n_cells_y//2
    k_prostate = n_edge + n_cells_z//2
else:
    i_prostate = n_edge + int(2*prostate_rad)
    j_prostate = n_edge + int(2*prostate_rad)
    k_prostate = n_edge + int(2*prostate_rad)
#
print(" ")
print(f"Prostate centre, indices {i_prostate}, {j_prostate}, {k_prostate}")
print(f"Prostate radius {prostate_rad}")
#
# Define tumour centre and radius
tumour_rad = 0.6
tumour_rad_2 = tumour_rad**2
if centre:
    i_tumour = i_prostate - prostate_rad//3
    j_tumour = j_prostate - prostate_rad//4
    k_tumour = k_prostate + prostate_rad//4
else:
    i_tumour = i_prostate + prostate_rad//2
    j_tumour = j_prostate + prostate_rad//3
    k_tumour = k_prostate + prostate_rad//2
#
print(" ")
print(f"Tumour centre, indices {i_tumour}, {j_tumour}, {k_tumour}")
print(f"Tumour radius {tumour_rad}")
#
index = 0
for i in range(0, n_is):
    for j in range(0, n_js):
        for k in range(0, n_ks):
            dist_prostate_2 = ((i - i_prostate)**2 +
                               (j - j_prostate)**2 +
                               (k - k_prostate)**2)
            #
            if dist_prostate_2 < prostate_rad_2:
                body[i, j, k] = c_prostate
                #
            elif (i < n_edge or j < n_edge or k < n_edge or
                  i > n_cells_x + n_edge - 1 or
                  j > n_cells_y + n_edge - 1 or
                  k > n_cells_z + n_edge - 1):
                body[i, j, k] = c_border
            else:

```

```

        body[i, j, k] = c_blood
    #
#
#
n_border_init = np.sum(body == c_border)
n_blood_init = np.sum(body == c_blood)
n_prostate_init = np.sum(body == c_prostate)
n_tumour_init = np.sum(body == c_tumour)
print(" ")
print(f"Initial number of cells in border is {n_border_init}")
print(f"Initial number of blood cells is {n_blood_init}")
print(f"Initial number of cells in prostate is {n_prostate_init}")
print(f"Initial number of cells in tumour is {n_tumour_init}")
print(f"Tumour growth rate is {growth_rate:.3f}")
#
if with_plots:
    plot_point = False
    plot_border = False
    plot_blood = True
    plot_prostate = True
    plot_tumour = True
    plot_surface = False
    plot_dup = False
    plot_ext = False
    plot_end = False
    plot_neigh = False
    plot_test = False
    #
    plot_2D = True
    plot_log = False
    #
    c_map = cm.viridis
    #c_map = cm.plasma
    #
    v_min = -1.0
    v_max = -1.0
    plot_body("Body", body, body_steer, i_tumour, j_tumour, k_tumour,
    ↪plot_point,
        plot_border, plot_blood, plot_prostate, plot_tumour, plot_surface,
        plot_dup, plot_ext, plot_end, plot_neigh, plot_test, plot_2D,
    ↪plot_log,
        c_map, v_min = v_min, v_max = v_max)
#
# Initialise PSA without tumour
# PSA decay rates set 1
#tau_prostate = 1/20.0
#tau_tumour = tau_prostate

```

```

#tau_blood = 1/2.0
#
# PSA production rates set
#sig_prostate = 2.0
#sig_tumour = 20.0
#sig_blood = 0.0
#
# PSA decay rates set 2
tau_prostate = 0.000217
tau_tumour = tau_prostate
tau_blood = 0.000144
#
# PSA production rates set 2
sig_prostate = 0.00802
sig_tumour = 0.96
sig_blood = 0.0
#
# Blood dilution factor
dil_blood = 0.02
#
# Set "diffusion" coefficient
beta = 0.1
#
# Allow for a proportion of random variation if required
r_prop = 0.0
#
# Set up large scale time array
times = np.linspace(0, n_real_times - 1, n_real_times).astype(int)
i_time = 0
print(f"-----",
      f"\b-----")
print(f"Time {times[i_time]}")
#
print("Initialise PSA_top, no tumour")
set_level = 2
PSA_top = initialise_PSA(set_level, r_prop, with_plots, i_prostate, j_prostate,
    ↪k_prostate)
if triple:
    print("Initialise PSA_mid, no tumour")
    set_level = 1
    PSA_mid = initialise_PSA(set_level, r_prop, with_plots, i_prostate,
    ↪j_prostate, k_prostate)
if double:
    print("Initialise PSA_bot, no tumour")
    set_level = 0
    PSA_bot = initialise_PSA(set_level, r_prop, with_plots, i_prostate,
    ↪j_prostate, k_prostate)

```

```

#
# Simulate diffusion, creation and decay of PSA without tumour
#
n_times = 250
conv_test = 0.001
with_all_plots = False
print("Diffusion PSA_top, no tumour")
set_level = 2
PSA_top = do_diffusion(PSA_top, beta, r_prop, n_times, conv_test,
                        with_init, set_level, with_all_plots,
                        i_prostate, j_prostate, k_prostate)

if triple:
    print("Diffusion PSA_mid, no tumour")
    set_level = 1
    with_init_here = False
    PSA_mid = do_diffusion(PSA_mid, beta, r_prop, n_times, conv_test,
                            with_init_here, set_level, with_all_plots,
                            i_prostate, j_prostate, k_prostate)

if double:
    print("Diffusion PSA_bot, no tumour")
    set_level = 0
    PSA_bot = do_diffusion(PSA_bot, beta, r_prop, n_times, conv_test,
                            with_init, set_level, with_all_plots,
                            i_prostate, j_prostate, k_prostate)

#
# Store PSA level at this time
#
PSA_top_time = np.zeros(n_real_times)
PSA_mid_time = np.zeros(n_real_times)
PSA_bot_time = np.zeros(n_real_times)
#
area_time = np.zeros(n_real_times)
btcell_time = np.zeros(n_real_times)
tumour_time = np.zeros(n_real_times)
prostate_time = np.zeros(n_real_times)
blood_time = np.zeros(n_real_times)
#
PSA_top_level = np.mean(PSA_top[body == c_blood])
if triple:
    PSA_mid_level = np.mean(PSA_mid[body == c_blood])
if double:
    PSA_bot_level = np.mean(PSA_bot[body == c_blood])
#
tumour_cells = np.sum(body == c_tumour)
prostate_cells = np.sum(body == c_prostate)
blood_cells = np.sum(body == c_blood)
#

```

```

PSA_top_time[i_time] = PSA_top_level
if triple:
    PSA_mid_time[i_time] = PSA_mid_level
if double:
    PSA_bot_time[i_time] = PSA_bot_level
#
tumour_time[i_time] = tumour_cells
prostate_time[i_time] = prostate_cells
blood_time[i_time] = blood_cells
print(f"At time {times[i_time]}:")
print(f"No. tumour cells {tumour_cells}, "
      f"prostate cells {prostate_cells}, blood cells {blood_cells}")
print(f"PSA_top_level {PSA_top_level:.6e}")
if triple:
    print(f"PSA_mid_level {PSA_mid_level:.6e}")
if double:
    print(f"PSA_bot_level {PSA_bot_level:.6e}")
#
# Add initial tumour
#
i_time = 1
print(f"-----",
      f"\b-----")
print(f"Time {times[i_time]}")
#
debug = False
with_plots = True
#
index = 0
for i in range(0, n_is):
    for j in range(0, n_js):
        for k in range(0, n_ks):
            dist_tumour_2 = ((i - i_tumour)**2 +
                           (j - j_tumour)**2 +
                           (k - k_tumour)**2)

            #
            if dist_tumour_2 < tumour_rad_2:
                body[i, j, k] = c_tumour
            #
        #
    #
n_border_init = np.sum(body == c_border)
n_blood_init = np.sum(body == c_blood)
n_prostate_init = np.sum(body == c_prostate)
n_tumour_init = np.sum(body == c_tumour)
print(" ")
print(f"Number of cells in border is {n_border_init}")

```

```

print(f"Number of blood cells is {n_blood_init}")
print(f"Number of cells in prostate is {n_prostate_init}")
print(f"Number of cells in tumour is {n_tumour_init}")
#
if with_plots:
    plot_point = False
    plot_border = False
    plot_blood = True
    plot_prostate = True
    plot_tumour = True
    plot_surface = False
    plot_dup = False
    plot_ext = False
    plot_end = False
    plot_neigh = False
    plot_test = False
    #
    plot_2D = True
    plot_log = False
    #
    c_map = cm.viridis
    #c_map = cm.plasma
    #
    v_min = -1.0
    v_max = -1.0
    plot_body("Body", body, body_steer, i_tumour, j_tumour, k_tumour,
    ↪plot_point,
        plot_border, plot_blood, plot_prostate, plot_tumour, plot_surface,
        plot_dup, plot_ext, plot_end, plot_neigh, plot_test, plot_2D,
    ↪plot_log,
        c_map, v_min = v_min, v_max = v_max)
#
# Simulate diffusion, creation and decay of PSA with initial tumour
#
print("Diffusion PSA_top, with initial tumour")
set_level = 2
PSA_top = do_diffusion(PSA_top, beta, r_prop, n_times, conv_test,
                        with_init, set_level, with_all_plots,
                        i_tumour, j_tumour, k_tumour)
if triple:
    print("Diffusion PSA_mid, with initial tumour")
    set_level = 1
    with_init_here = False
    PSA_mid = do_diffusion(PSA_mid, beta, r_prop, n_times, conv_test,
                            with_init_here, set_level, with_all_plots,
                            i_tumour, j_tumour, k_tumour)
if double:

```

```

print("Diffusion PSA_bot, with initial tumour")
set_level = 0
PSA_bot = do_diffusion(PSA_bot, beta, r_prop, n_times, conv_test,
                        with_init, set_level, with_all_plots,
                        i_tumour, j_tumour, k_tumour)

#
# Store PSA level at this time
#
PSA_top_time[i_time] = PSA_top_level
if triple:
    PSA_mid_time[i_time] = PSA_mid_level
if double:
    PSA_bot_time[i_time] = PSA_bot_level
#
with_plots_here = True
i_plot, j_plot, k_plot = i_tumour, j_tumour, k_tumour
btcell, bt_area = area_tumour_blood(with_plots_here, i_time, i_plot, j_plot,
    ↪k_plot)
#
area_time[i_time] = bt_area
btcell_time[i_time] = btcell
tumour_time[i_time] = tumour_cells
prostate_time[i_time] = prostate_cells
blood_time[i_time] = blood_cells
print(f"At time {times[i_time]}:")
print(f"No. tumour cells {tumour_cells}, "
      f"prostate cells {prostate_cells}, blood cells {blood_cells}")
print(f"PSA_top_level {PSA_top_level:.6e}")
if triple:
    print(f"PSA_mid_level {PSA_mid_level:.6e}")
if double:
    print(f"PSA_bot_level {PSA_bot_level:.6e}")
#
i_time = 2
out_of_body = False
while i_time < n_real_times and not out_of_body:
    #
    # Increase tumour size - make duplications
    #
    ↪
    ↪print(f"-----")
    ↪      f"\b-----")
    print(f"Time {times[i_time]}")
    body_org = np.zeros((n_is, n_js, n_ks))
    body_org[:] = body[:]
    #
    n_duplicates = int(np.exp(growth_rate*(i_time - 2)))

```

```

#
with_plots = False
for i in range(0, n_duplicates):
    duplicate, body_steer, out_of_body = find_duplicator(with_plots)
    if out_of_body:
        break
    body_steer, neighbour, end_point, out_of_body = \
        position_finder(body_steer, *duplicate, with_plots)
    if out_of_body:
        break
    body = cell_shifter(duplicate, neighbour, end_point, with_plots)
    PSA_top = PSA_updater(PSA_top, duplicate, neighbour, end_point,
↪with_plots)
    if triple:
        PSA_mid = PSA_updater(PSA_mid, duplicate, neighbour, end_point,
↪with_plots)
    if double:
        PSA_bot = PSA_updater(PSA_bot, duplicate, neighbour, end_point,
↪with_plots)
    #
    body_steer = body_steer_reset(with_plots)
#
if out_of_body:
    break
with_plots = False
title = "$\delta$ " + str(n_duplicates) + " duplications"
show_change(body_org, i_tumour, j_tumour, k_tumour, with_plots, title)
#
# Simulate diffusion, creation and decay of PSA with enlarged tumour
#
print("Diffusion PSA_top, with tumour")
set_level = 2
PSA_top = do_diffusion(PSA_top, beta, r_prop, n_times, conv_test,
                        with_init, set_level, with_all_plots,
                        i_tumour, j_tumour, k_tumour)

if triple:
    print("Diffusion PSA_mid, with tumour")
    set_level = 1
    with_init_here = False
    PSA_mid = do_diffusion(PSA_mid, beta, r_prop, n_times, conv_test,
                            with_init_here, set_level, with_all_plots,
                            i_tumour, j_tumour, k_tumour)

if double:
    print("Diffusion PSA_bot, with tumour")
    set_level = 0
    PSA_bot = do_diffusion(PSA_bot, beta, r_prop, n_times, conv_test,
                            with_init, set_level, with_all_plots,

```

```

                                i_tumour, j_tumour, k_tumour)

#
# Store PSA level at this time
PSA_top_level = np.mean(PSA_top[body == c_blood])
if triple:
    PSA_mid_level = np.mean(PSA_mid[body == c_blood])
if double:
    PSA_bot_level = np.mean(PSA_bot[body == c_blood])
#
tumour_cells = np.sum(body == c_tumour)
prostate_cells = np.sum(body == c_prostate)
blood_cells = np.sum(body == c_blood)
#
PSA_top_time[i_time] = PSA_top_level
if triple:
    PSA_mid_time[i_time] = PSA_mid_level
if double:
    PSA_bot_time[i_time] = PSA_bot_level
#
with_plots_here = True
i_plot, j_plot, k_plot = i_tumour, j_tumour, k_tumour
btcell, bt_area = area_tumour_blood(with_plots_here, i_time, i_plot,
↪j_plot, k_plot)
btcell_time[i_time] = btcell
area_time[i_time] = bt_area
tumour_time[i_time] = tumour_cells
prostate_time[i_time] = prostate_cells
blood_time[i_time] = blood_cells
print(f"At time {times[i_time]}:")
print(f"No. tumour cells {tumour_cells}, "
      f"prostate cells {prostate_cells}, blood cells {blood_cells}")
print(f"PSA_top_level {PSA_top_level:.6e}")
if triple:
    print(f"PSA_mid_level {PSA_mid_level:.6e}")
if double:
    print(f"PSA_bot_level {PSA_bot_level:.6e}")
i_time += 1

#
times = np.linspace(0, i_time - 1, i_time)
blood_time = blood_time[0:i_time]
prostate_time = prostate_time[0:i_time]
tumour_time = tumour_time[0:i_time]
area_time = area_time[0:i_time]
#
PSA_top_time = PSA_top_time[0:i_time]
PSA_mid_time = PSA_mid_time[0:i_time]
PSA_bot_time = PSA_bot_time[0:i_time]

```

```

#
most_time = blood_time + prostate_time + tumour_time
PSA_cells = tumour_cells + prostate_cells
#
btcell_color = np.zeros(len(tumour_time)).astype(str)
btcell_color[btcell_time > 0] = 'r'
btcell_color[btcell_time == 0] = 'b'
#
face_number = np.zeros(i_time)
face_number[tumour_time < 1] = 0.0
face_number[tumour_time > 0] = area_time[tumour_time > 0]/
    ↪tumour_time[tumour_time > 0]
#
fig = plt.figure(figsize = (6, 9))
#
ax = fig.add_subplot(3, 1, 1)
ax.set_title("Cells with time")
ax.set_xlabel("Time")
ax.set_ylabel("No. cells")
ax.plot(times, blood_time, marker = 'o', linestyle = ':', color = 'r', label =_
    ↪"Blood")
ax.plot(times, tumour_time, marker = 'o', linestyle = ':', color = 'b', label =_
    ↪"Tumour")
ax.plot(times, prostate_time, marker = 'o', linestyle = ':', color = 'c', label=_
    ↪"Prostate")
ax.set_yscale('log')
ax.grid(color = 'g')
ax.legend()
#
ax = fig.add_subplot(3, 1, 2)
ax.set_title("Tumour cells and interface area with time")
ax.set_xlabel("Time")
ax.set_ylabel("No. cells/cell faces")
ax.plot(times, tumour_time, marker = 'o', linestyle = ':', color = 'r', label =_
    ↪"Tumour cells")
ax.plot(times, area_time, marker = 'o', linestyle = ':', color = 'b', label =_
    ↪"Interface area")
ax.plot(times, face_number, marker = 'o', linestyle = ':', color = 'c',
    label = "Face number")
ax.set_yscale('log')
ax.grid(color = 'g')
ax.legend()
#
ax = fig.add_subplot(3, 1, 3)
ax.set_title("PSA level with time")
ax.set_xlabel("Time")

```

```

ax.set_ylabel("PSA")
if double:
    ax.plot(times, PSA_top_time, marker = 'v', linestyle = '', color = 'k')
    ax.plot(times, PSA_bot_time, marker = '^', linestyle = '', color = 'k')
    ax.fill_between(times, PSA_bot_time, PSA_top_time, color = 'k', alpha = 0.3)
    if triple:
        ax.plot(times, PSA_mid_time, marker = '+', linestyle = '-', color = 'k')
else:
    ax.plot(times, PSA_top_time, marker = 'o', linestyle = ':', color = 'k')
ax.grid(color = 'g')
#
plt.tight_layout()
plt.show()
#
PSA_cells_time = tumour_time + prostate_time
#
plot_log_here = False
#
fig = plt.figure(figsize = (6, 6))
#
ax = fig.add_subplot(2, 1, 1)
ax.set_title("PSA level as function of tumour cell number")
ax.set_xlabel("No. cells")
ax.set_ylabel("PSA")
if double:
    ax.scatter(tumour_time, PSA_top_time, marker = 'v', c = btcell_color)
    ax.scatter(tumour_time, PSA_bot_time, marker = '^', c = btcell_color)
    ax.fill_between(tumour_time, PSA_bot_time, PSA_top_time, color = 'c', alpha_
↳ 0.3)
    if triple:
        ax.scatter(tumour_time, PSA_mid_time, marker = '+', c = btcell_color)
else:
    ax.scatter(tumour_time, PSA_top_time, marker = 'o', c = btcell_color)
    ax.plot(tumour_time, PSA_top_time, marker = '', linestyle = ':', color =_
↳ 'c')
ax.grid(color = 'g')
if plot_log_here and len(tumour_time > 0):
    ax.set_xscale('log')
    ax.set_yscale('log')
#
ax = fig.add_subplot(2, 1, 2)
ax.set_title("PSA level as function of interface area")
ax.set_xlabel("Area")
ax.set_ylabel("PSA")
if double:
    ax.scatter(area_time, PSA_top_time, marker = 'v', c = btcell_color)
    ax.scatter(area_time, PSA_bot_time, marker = '^', c = btcell_color)

```

```

    ax.fill_between(area_time, PSA_bot_time, PSA_top_time, color = 'c', alpha = 0.3)
    if triple:
        ax.scatter(area_time, PSA_mid_time, marker = '+', c = btcell_color)
    else:
        ax.scatter(area_time, PSA_top_time, marker = 'o', c = btcell_color)
        ax.plot(area_time, PSA_top_time, marker = '', linestyle = ':', color = 'c')
ax.grid(color = 'g')
if plot_log_here:
    ax.set_xscale('log')
    ax.set_yscale('log')
#
plt.tight_layout()
plt.show()
#
then = now
now = datetime.datetime.now()
print("\nDate and time",str(now))
print("Time since last check is",str(now - then))

```

Date and time 2026-01-10 14:38:14.938947

Body dimensions 47 in x, 49 in y, 51 in z.

Body size 117453 cells.

Prostate centre, indices 23, 24, 25

Prostate radius 8

Tumour centre, indices 21, 22, 27

Tumour radius 0.6

Initial number of cells in border is 13818

Initial number of blood cells is 101532

Initial number of cells in prostate is 2103

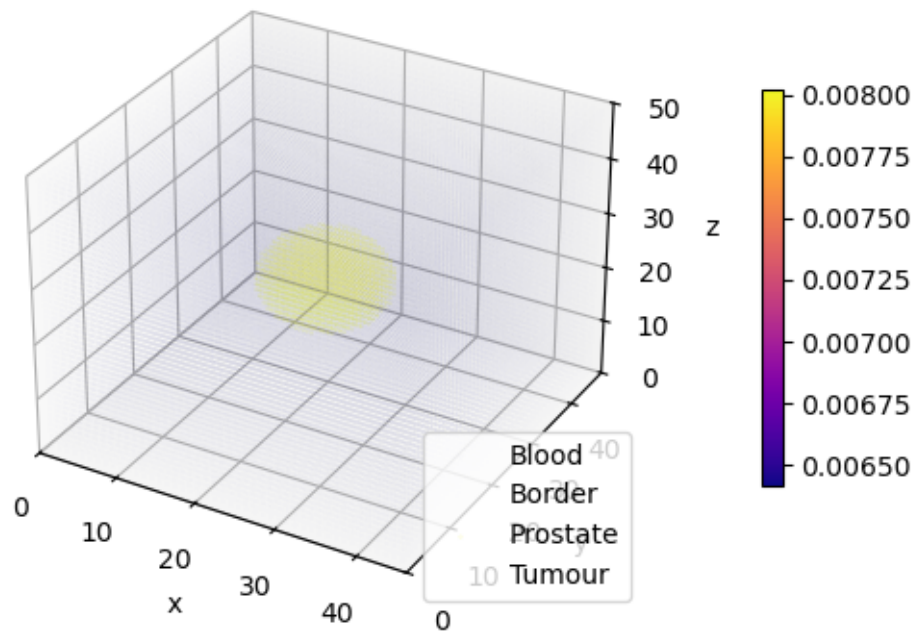
Initial number of cells in tumour is 0

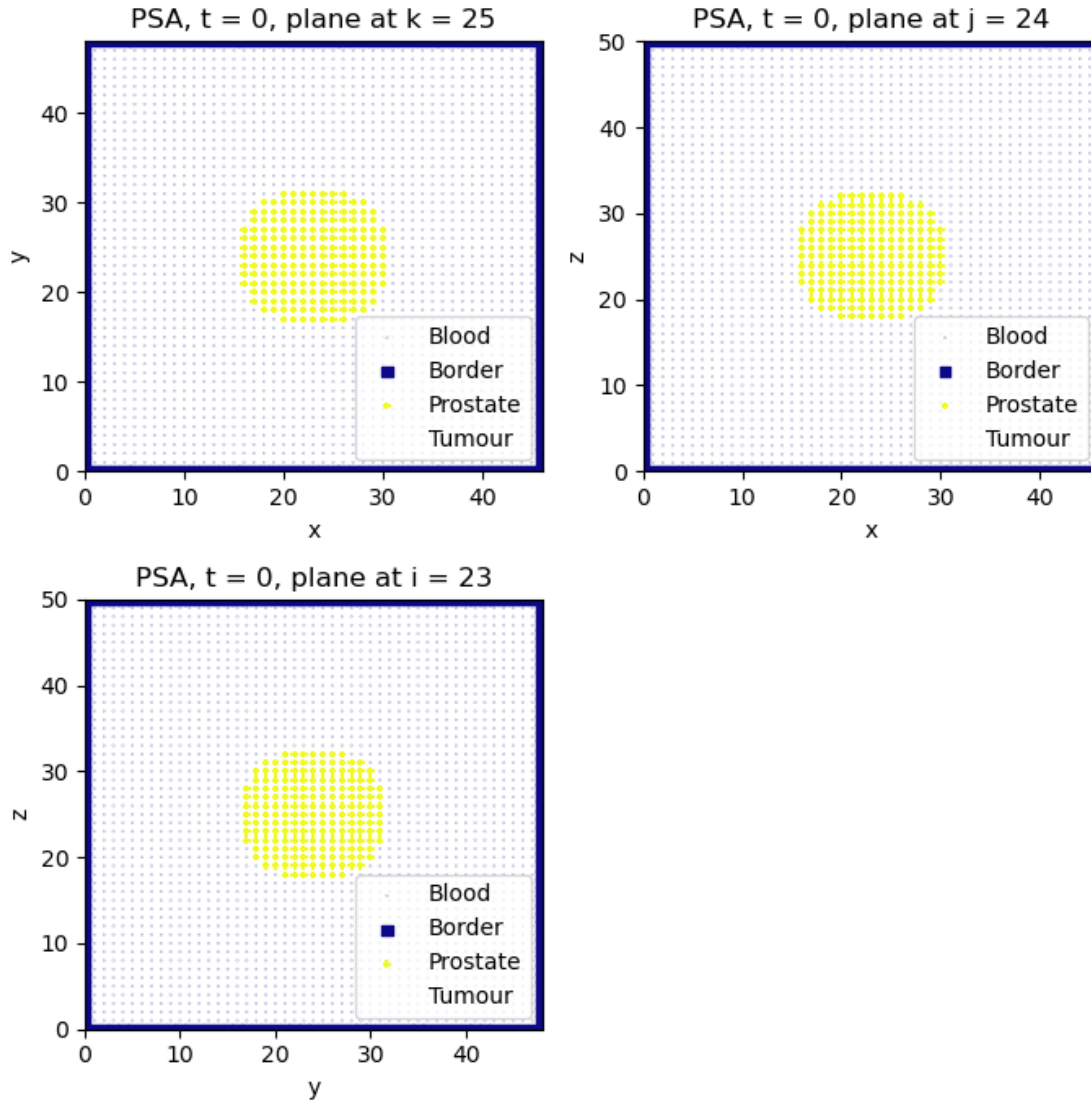
Tumour growth rate is 0.200

Time 0

Initialise PSA_top, no tumour

PSA, $t = 0$, xyz

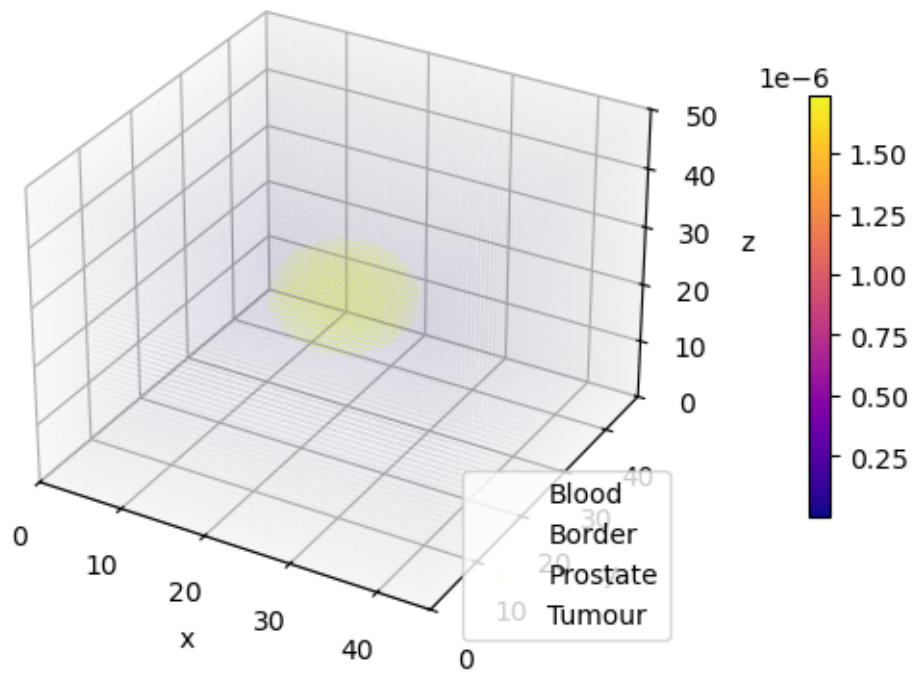


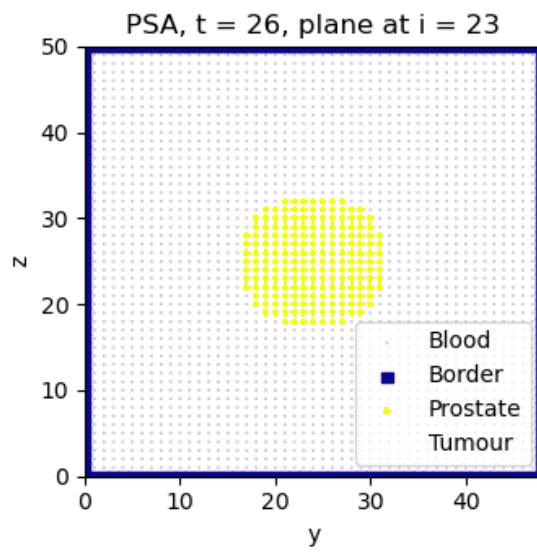
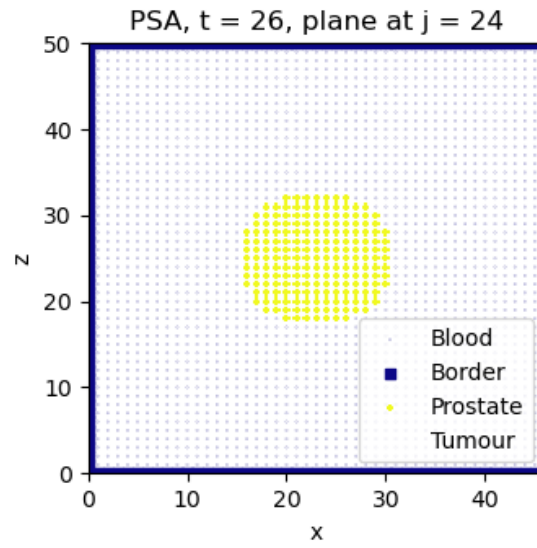
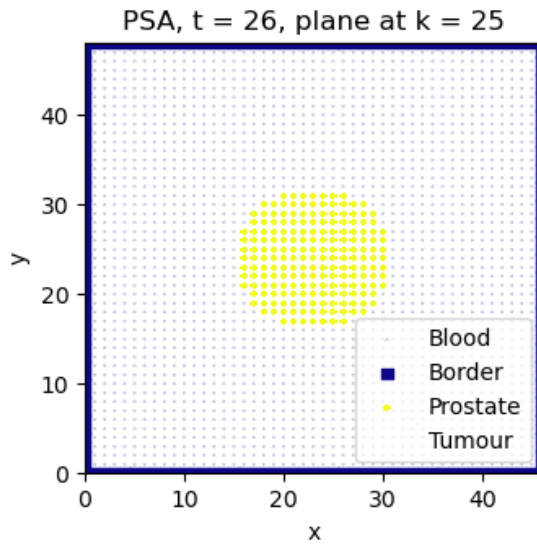


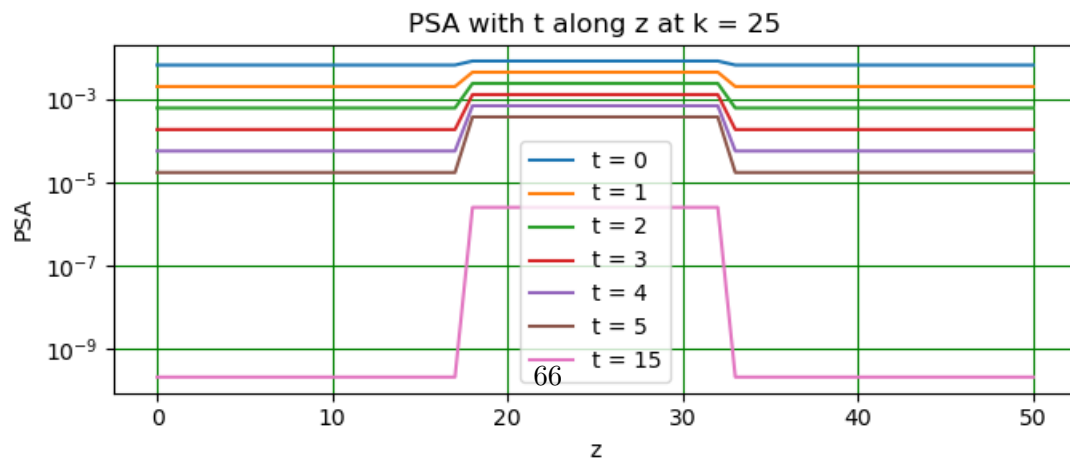
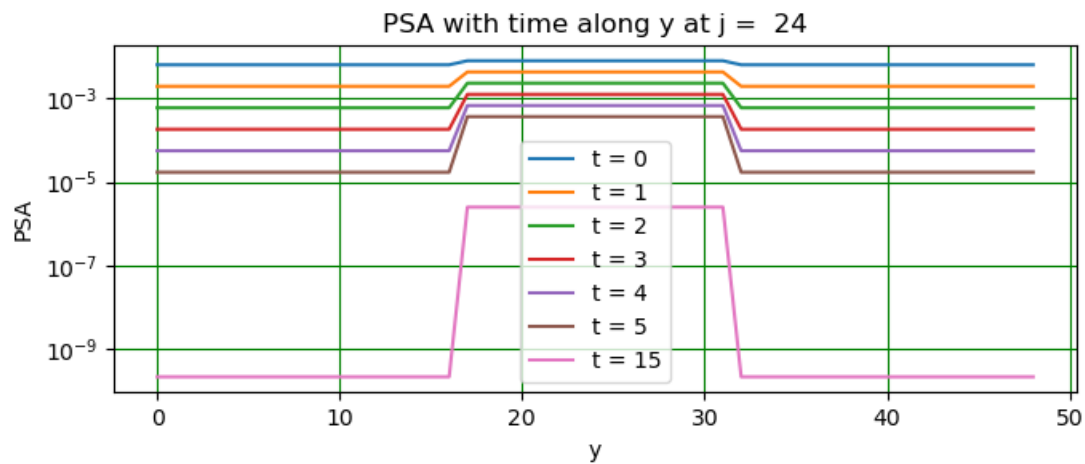
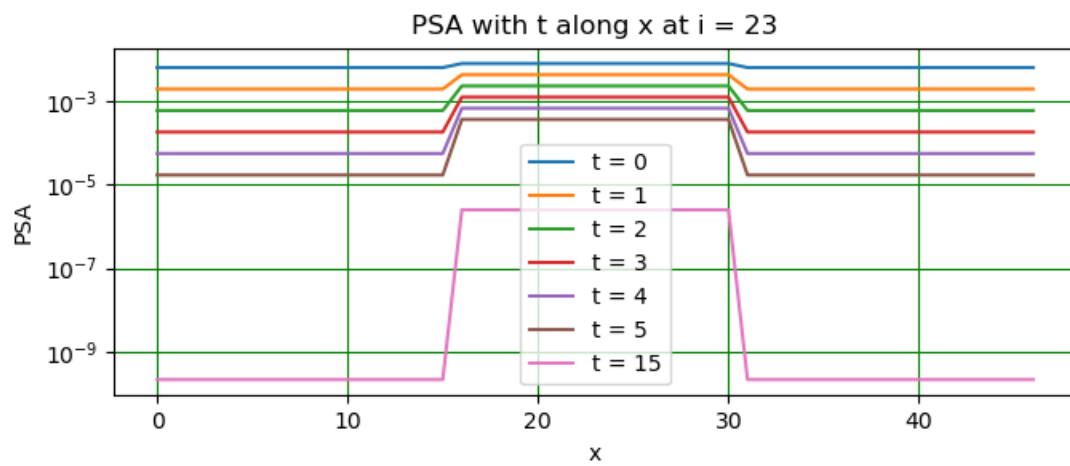
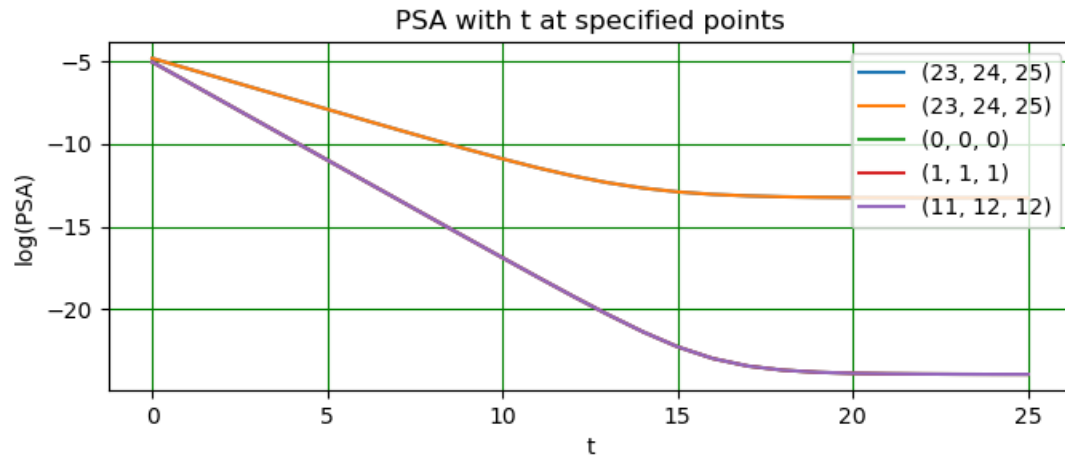
Diffusion PSA_top, no tumour

Diffusion converged, $nt = 26$, $ext_test = 6.717227e-04$, $prostate_test = 2.245043e-04$

PSA, $t = 26$, xyz







At time 0:

No. tumour cells 0, prostate cells 2103, blood cells 101532

PSA_top_level 4.067385e-11

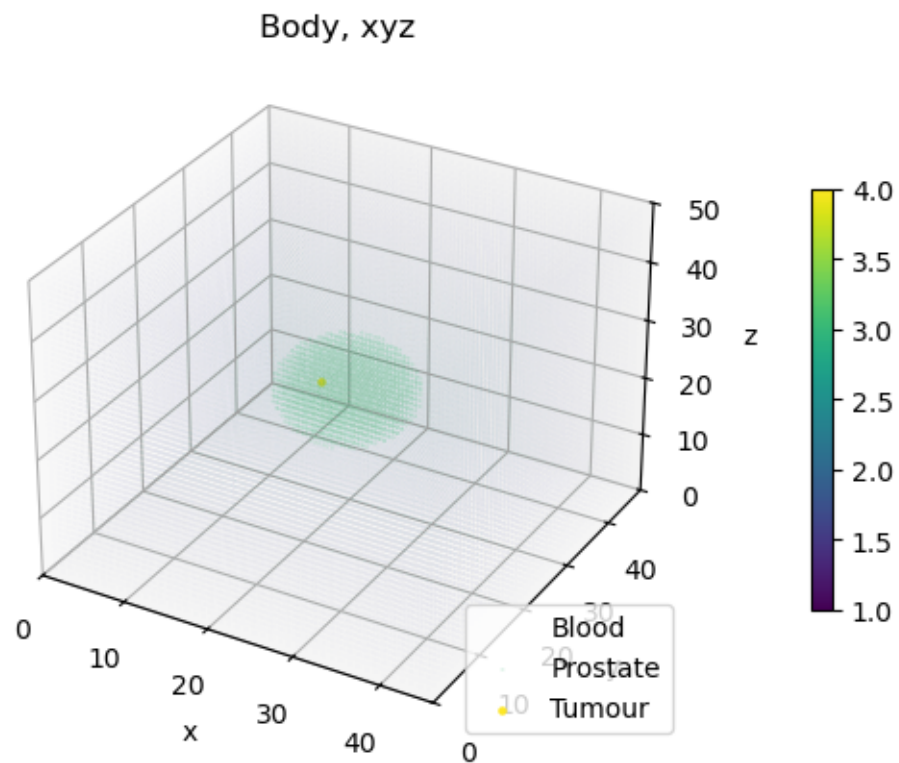
Time 1

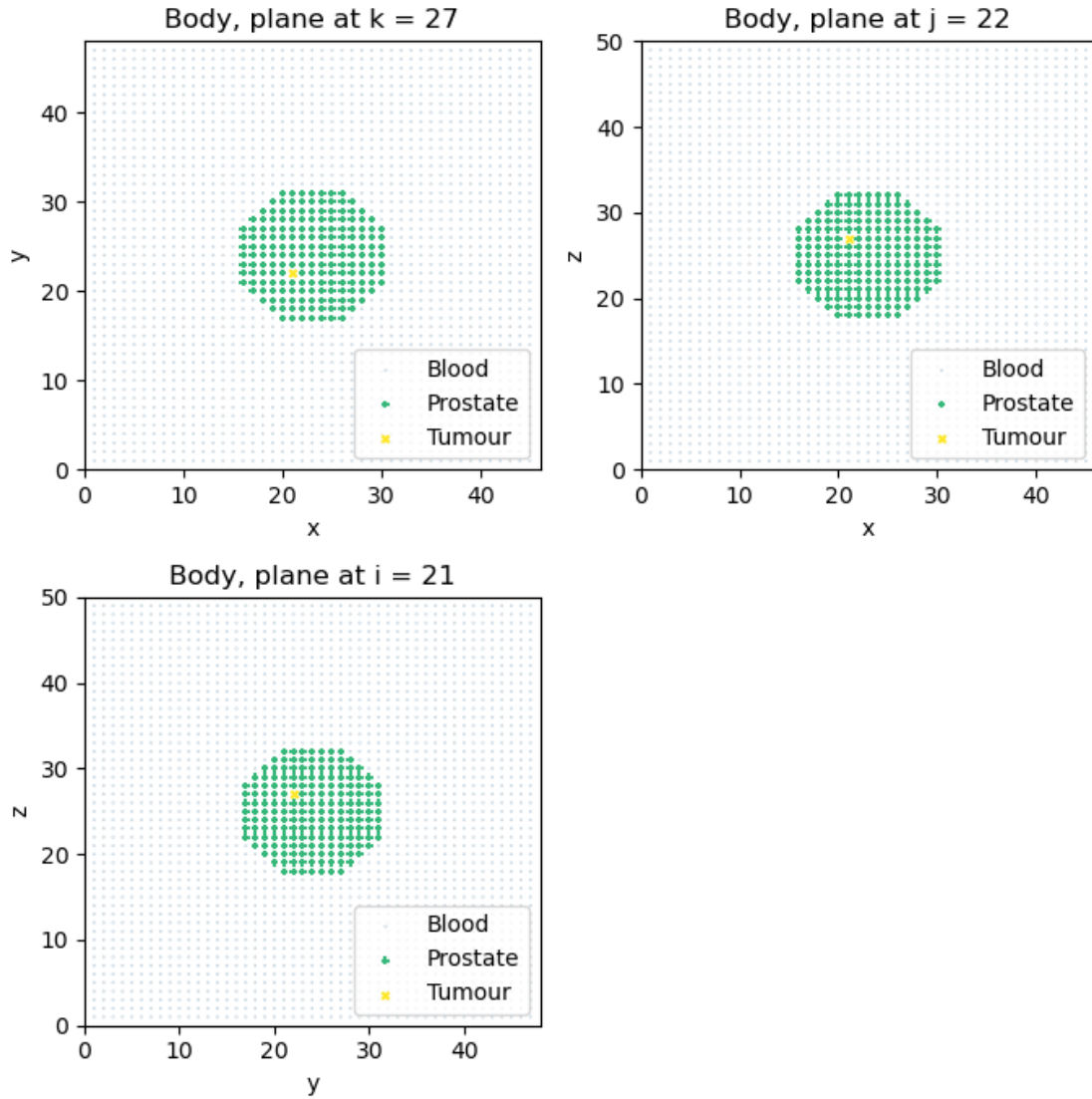
Number of cells in border is 13818

Number of blood cells is 101532

Number of cells in prostate is 2102

Number of cells in tumour is 1

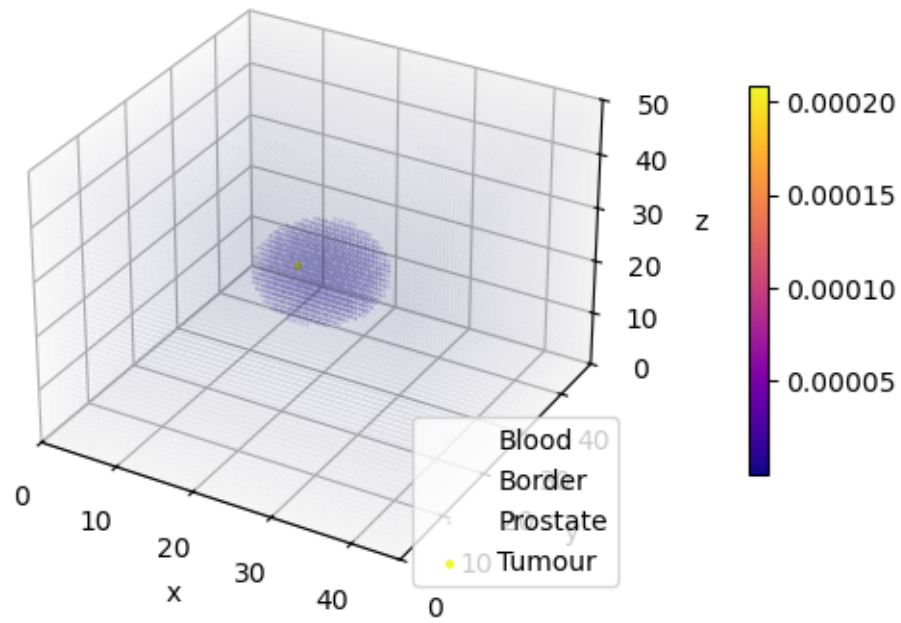


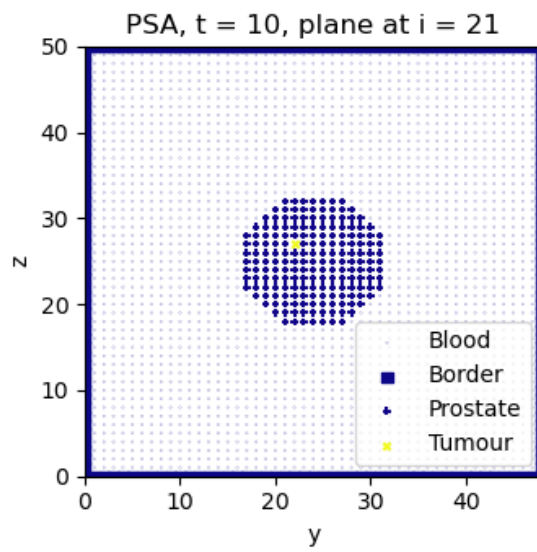
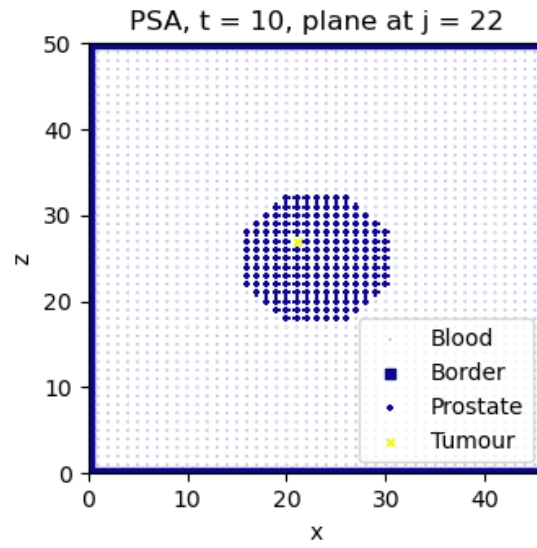
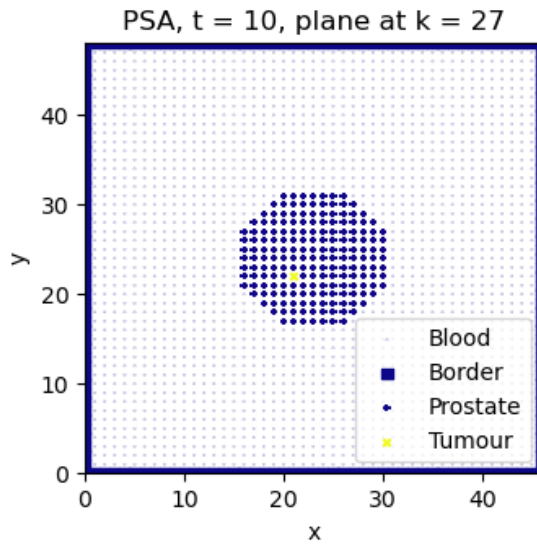


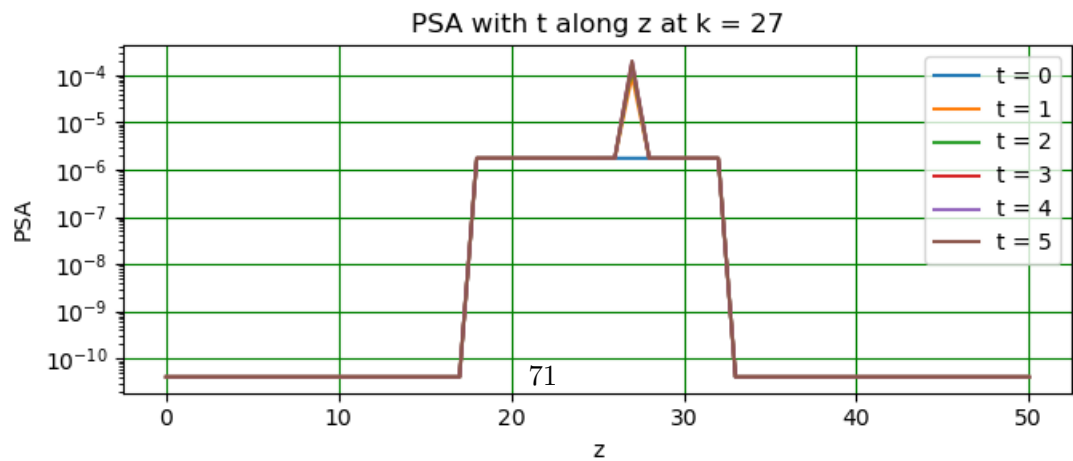
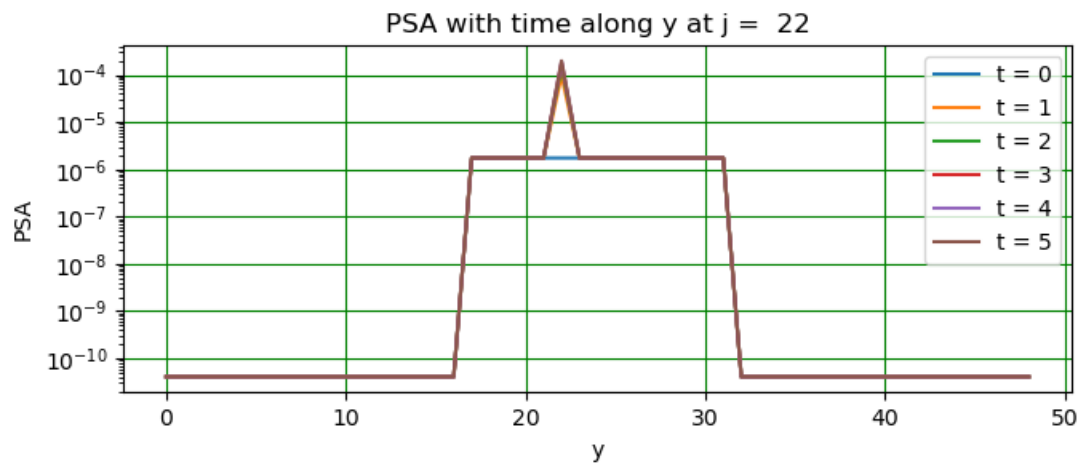
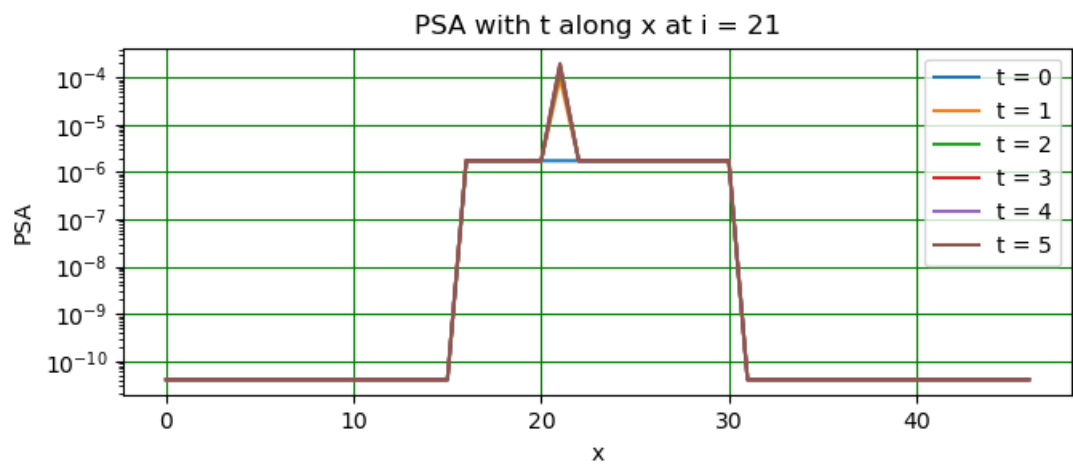
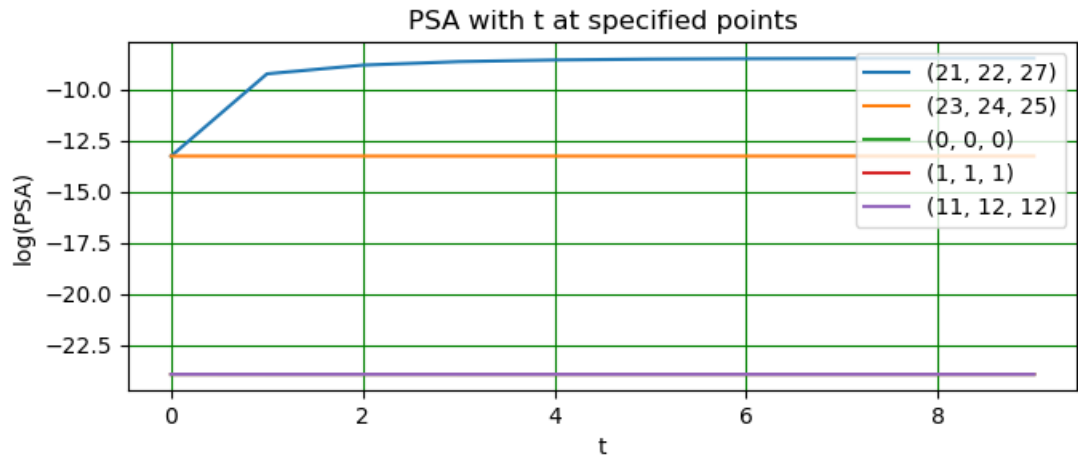
Diffusion PSA_top, with initial tumour

Diffusion converged, nt = 10, ext_test = 7.471608e-07, prostate_test = 9.488810e-04

PSA, $t = 10$, xyz







At time 1:

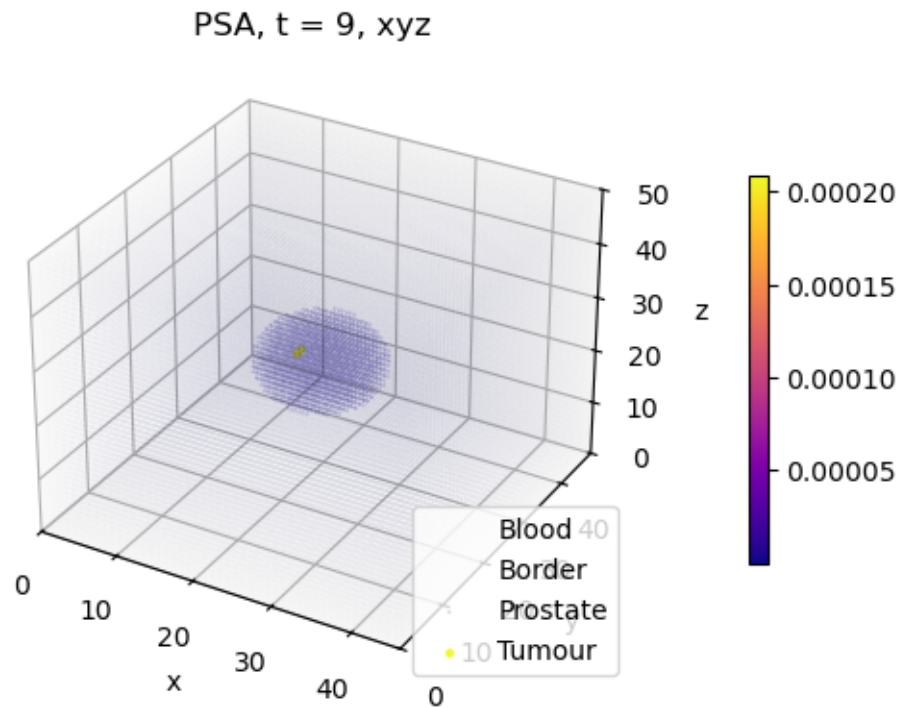
No. tumour cells 0, prostate cells 2103, blood cells 101532

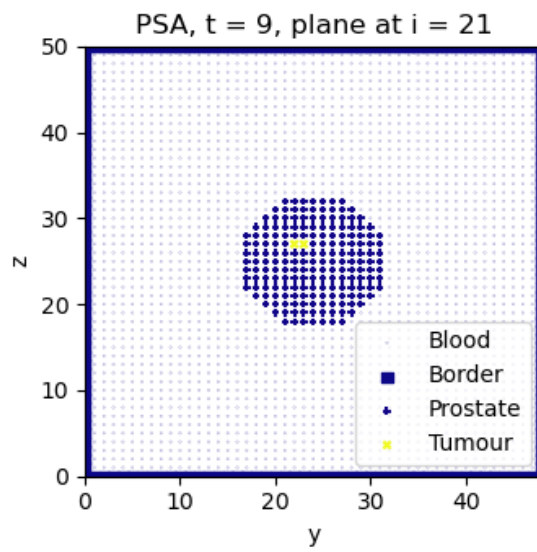
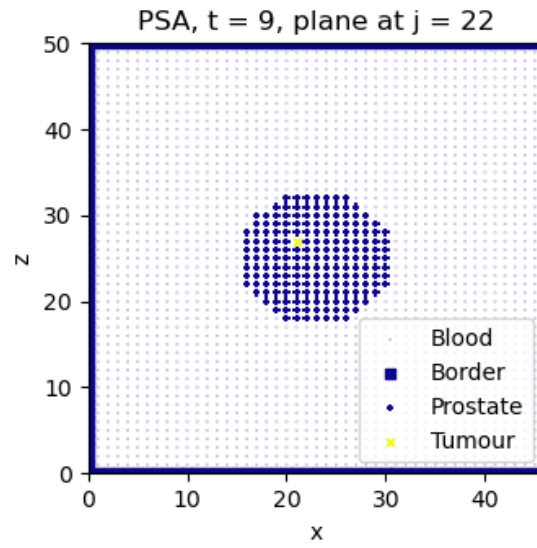
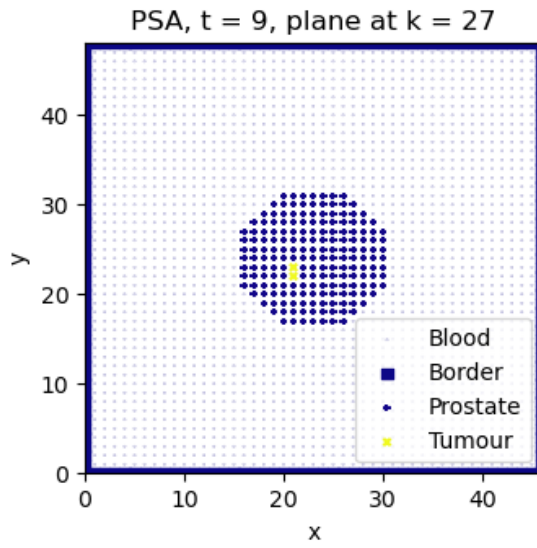
PSA_top_level 4.067385e-11

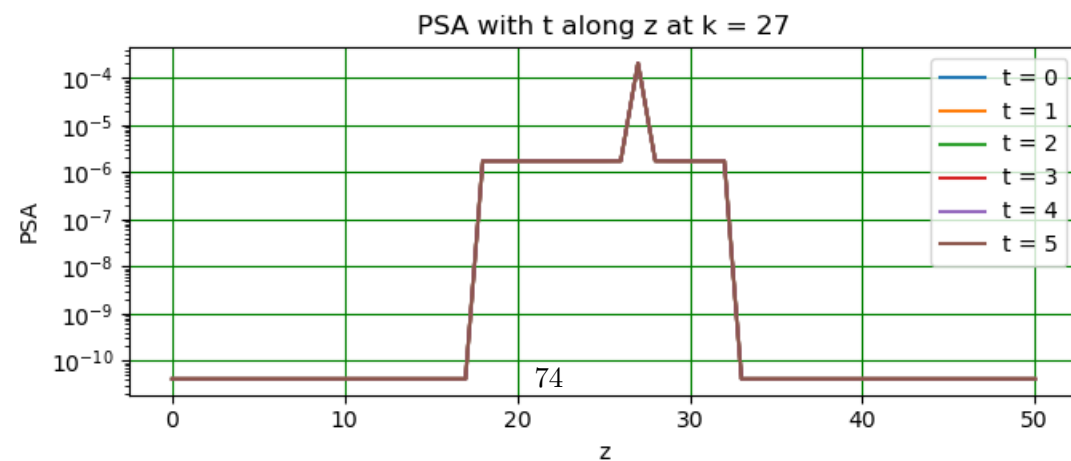
Time 2

Diffusion PSA_top, with tumour

Diffusion converged, nt = 9, ext_test = 2.461139e-08, prostate_test = 8.809597e-04







At time 2:

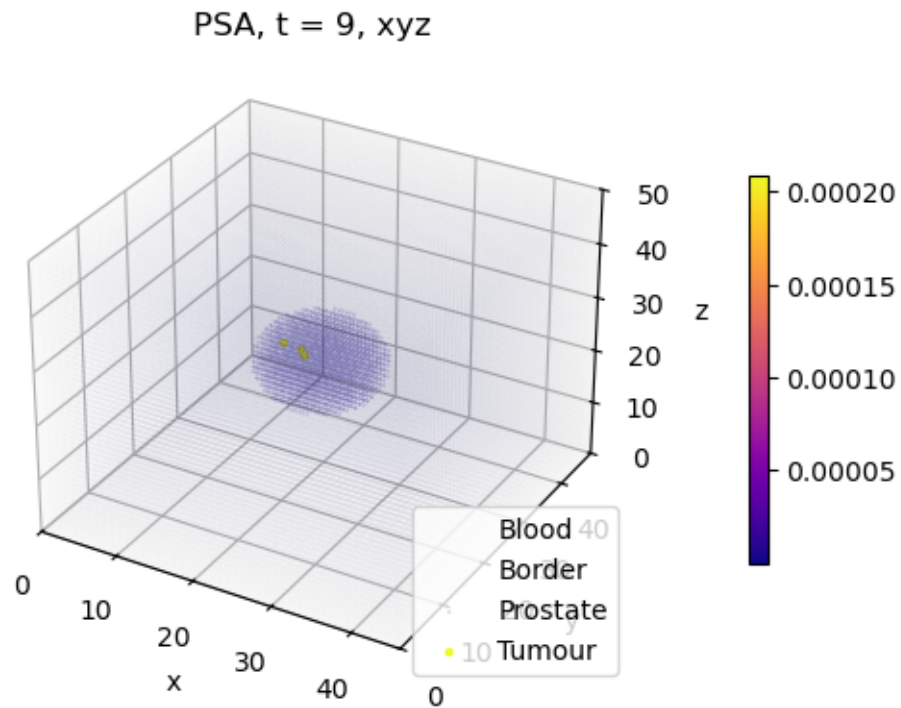
No. tumour cells 2, prostate cells 2102, blood cells 101531

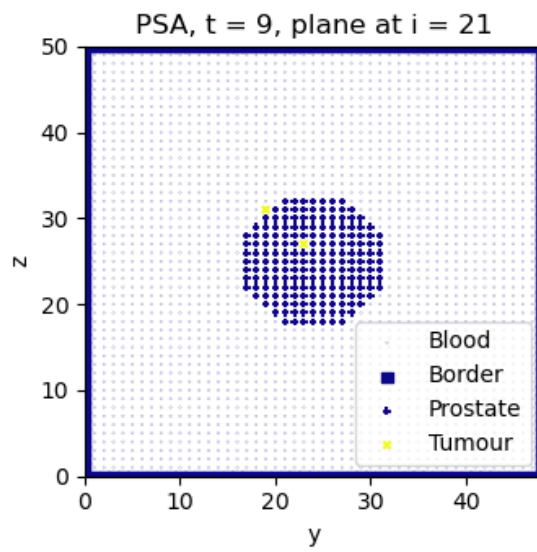
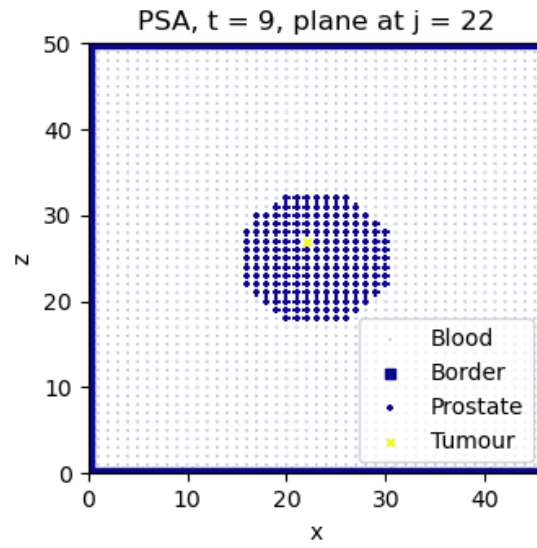
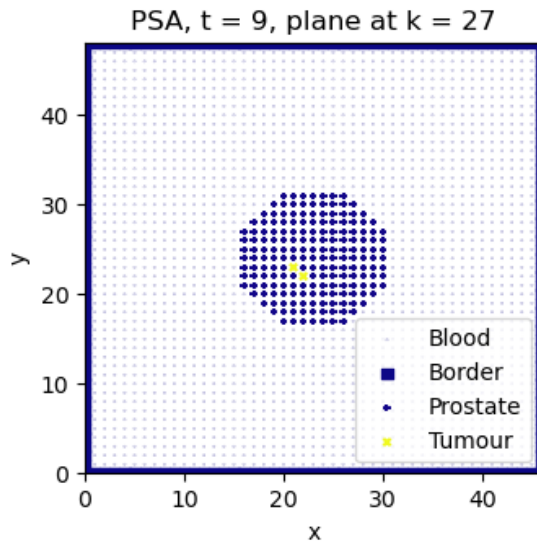
PSA_top_level 4.058518e-11

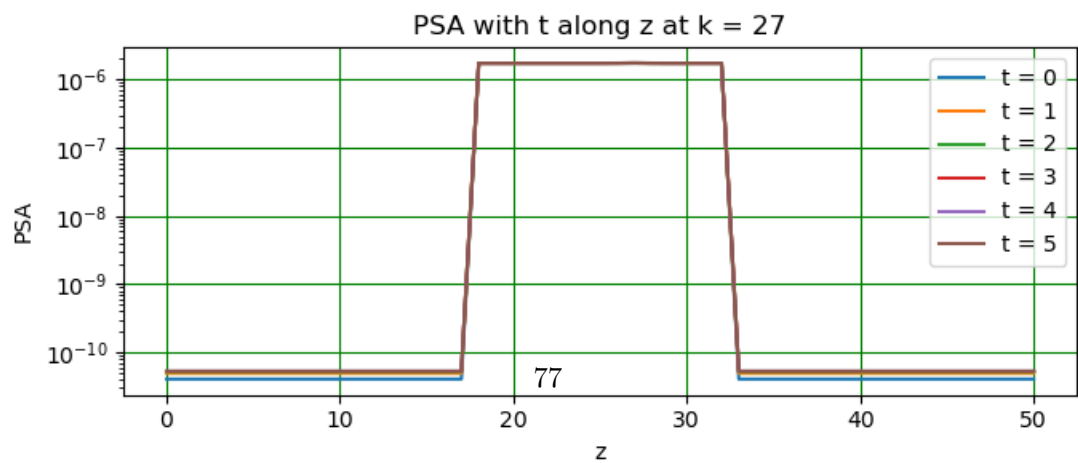
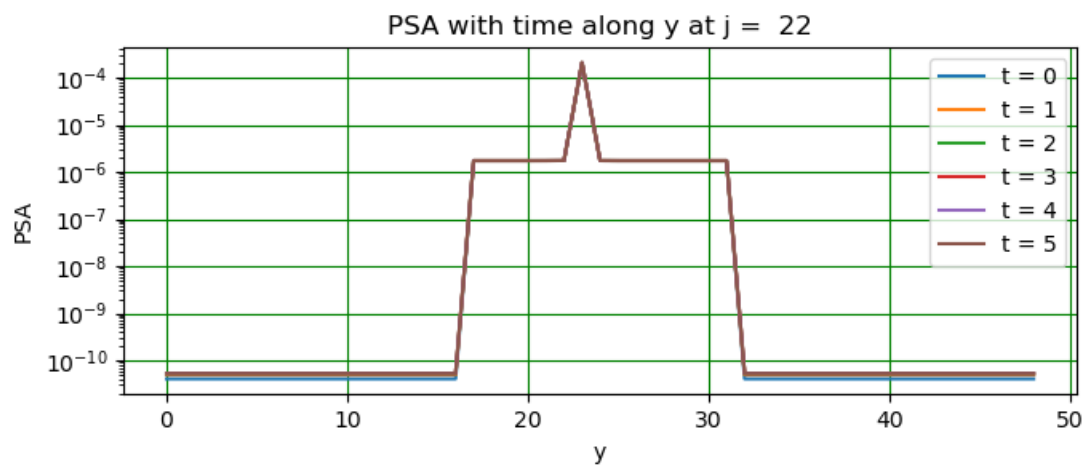
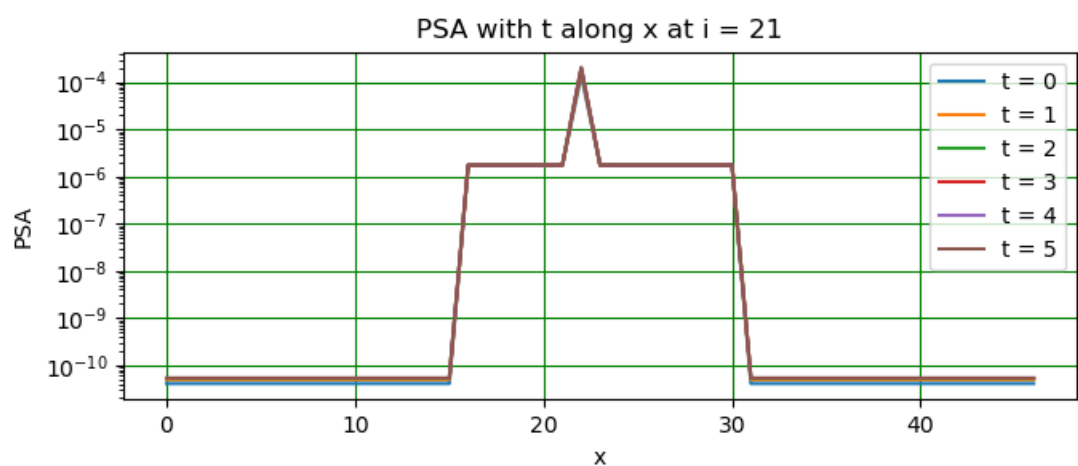
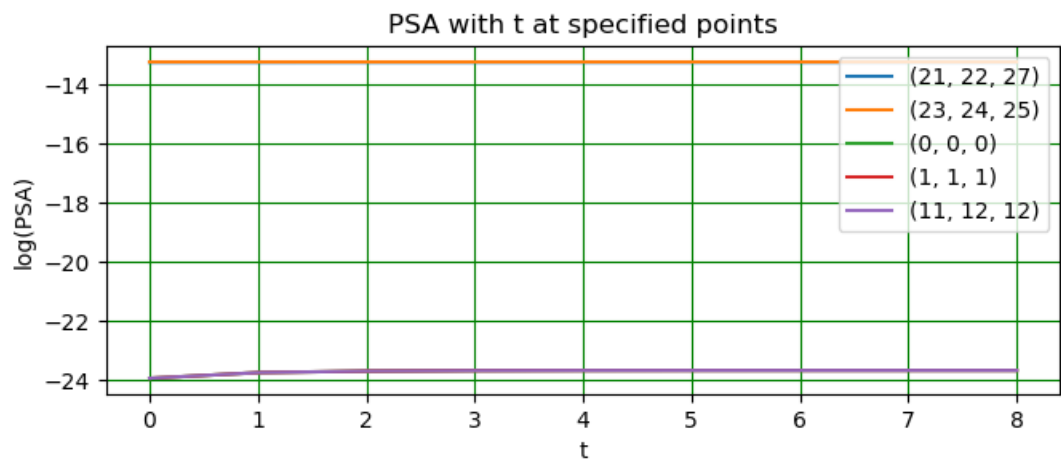
Time 3

Diffusion PSA_top, with tumour

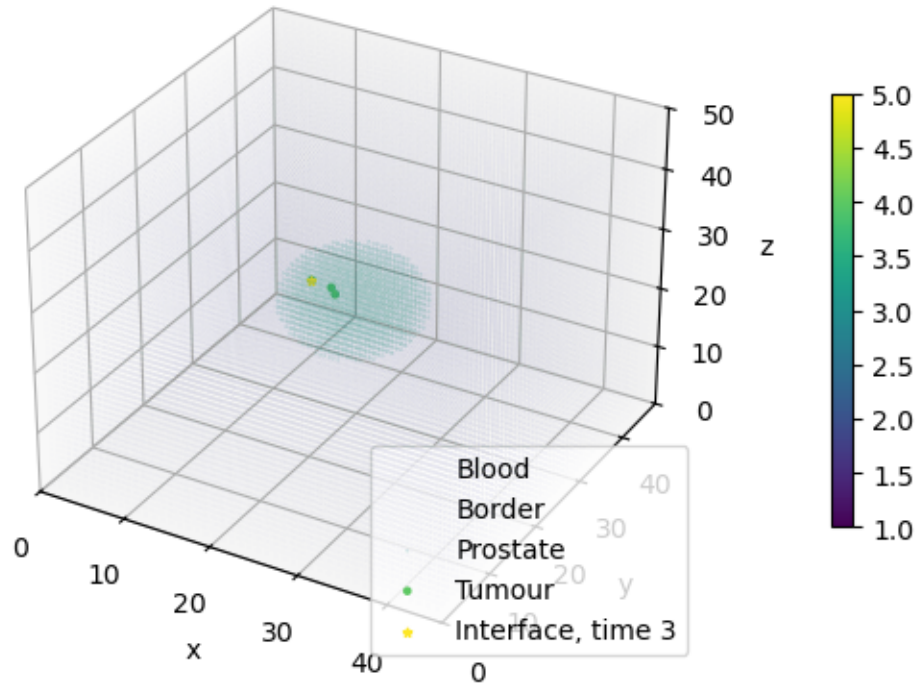
Diffusion converged, nt = 9, ext_test = 3.784569e-06, prostate_test = 5.870208e-04







Interface, time 3, xyz



At time 3:

No. tumour cells 3, prostate cells 2102, blood cells 101530

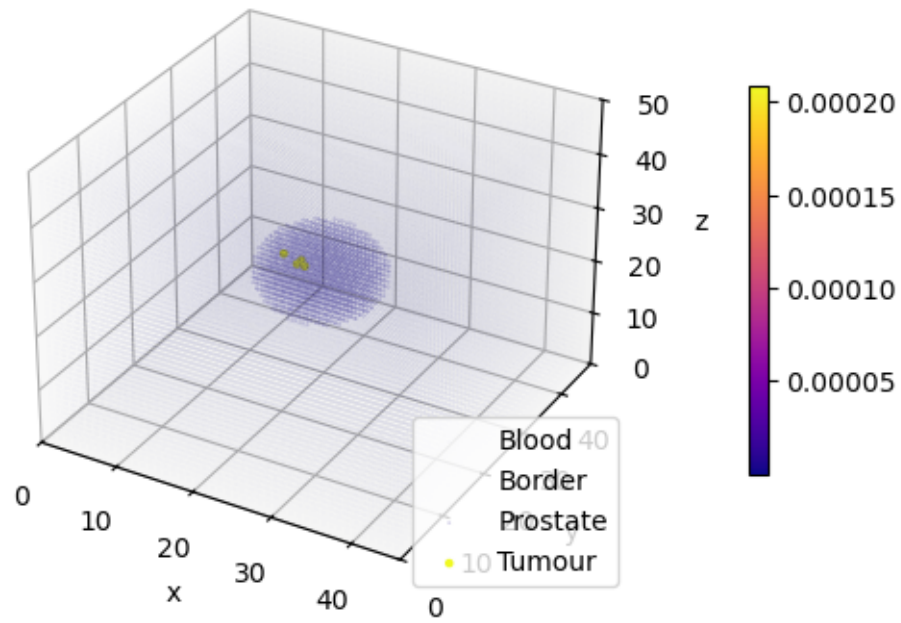
PSA_top_level 5.299088e-11

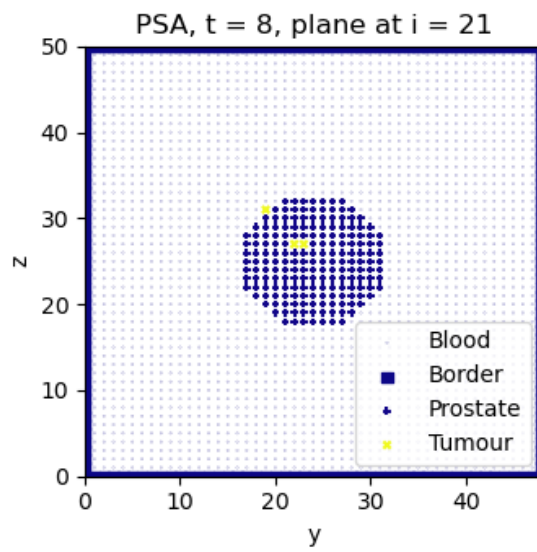
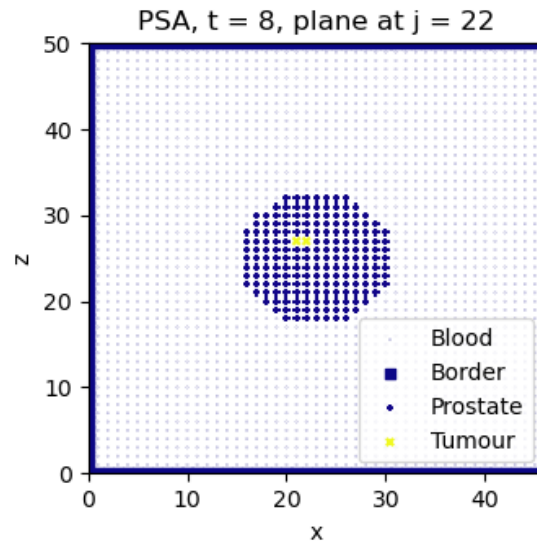
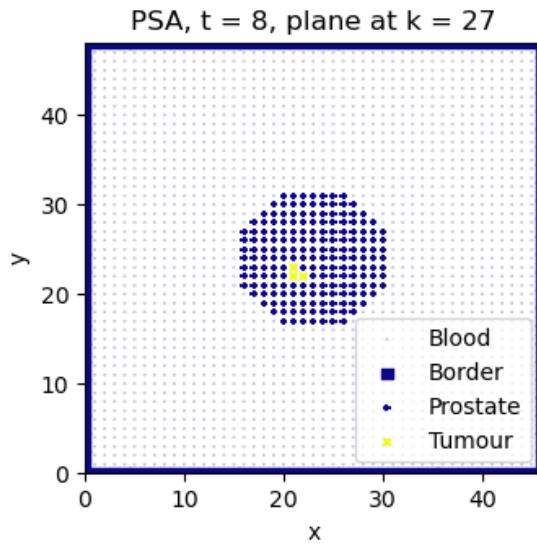
Time 4

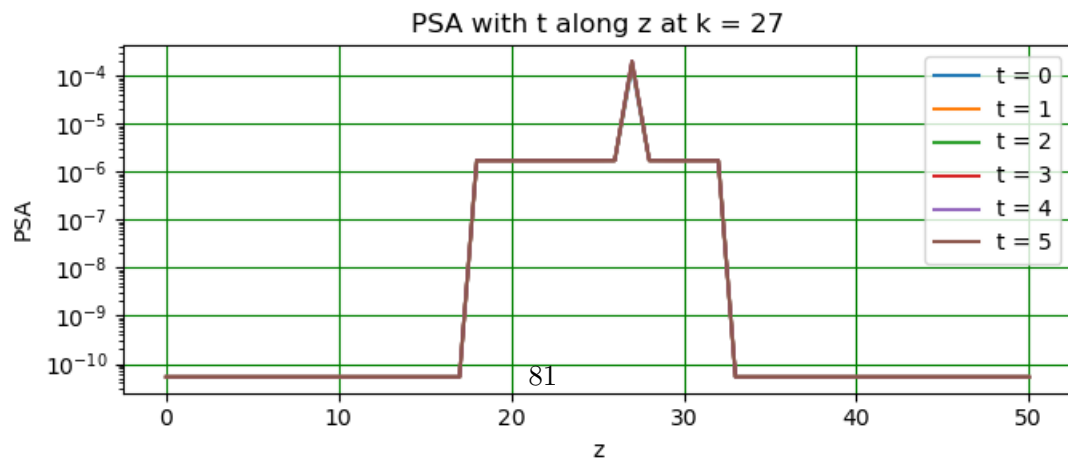
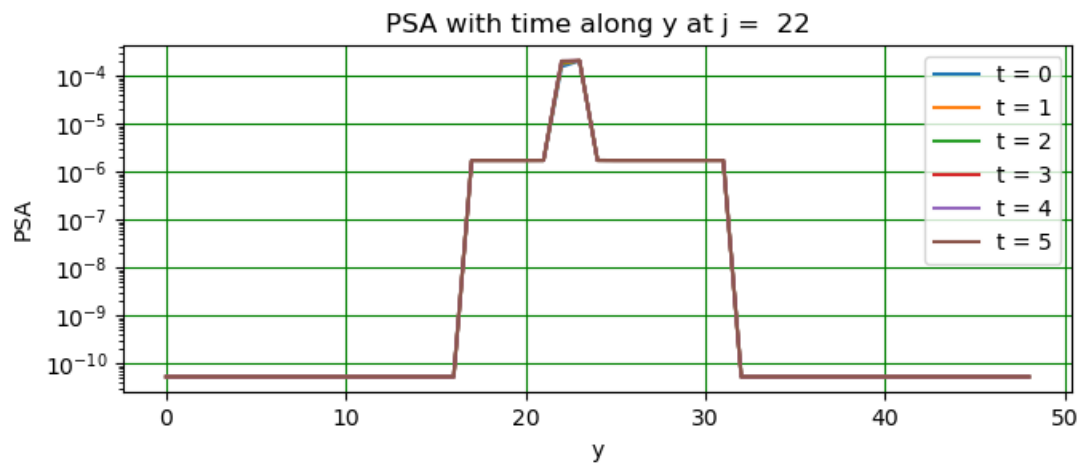
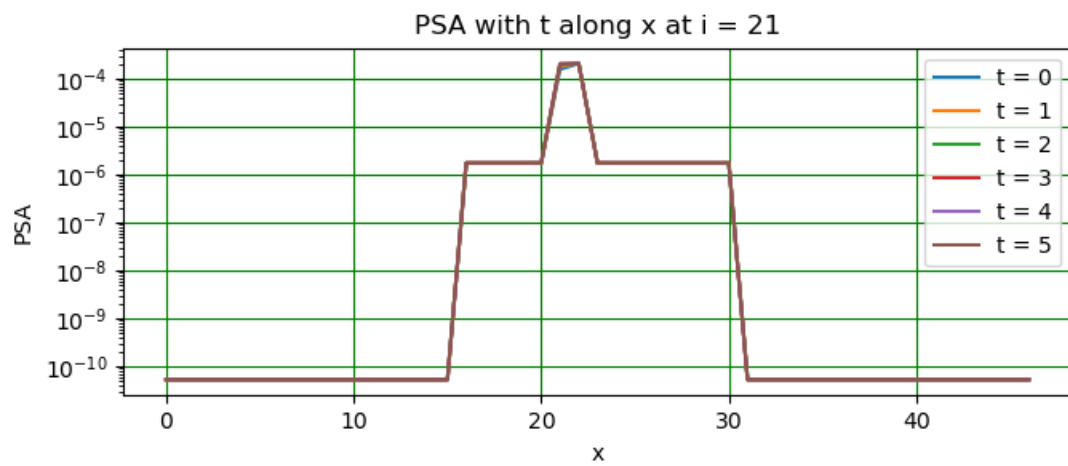
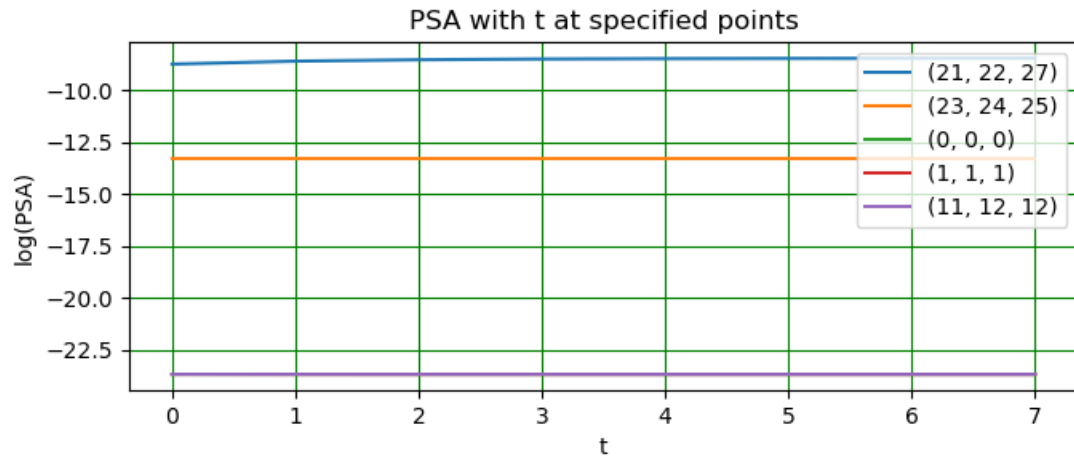
Diffusion PSA_top, with tumour

Diffusion converged, nt = 8, ext_test = 1.477116e-07, prostate_test =
8.167133e-04

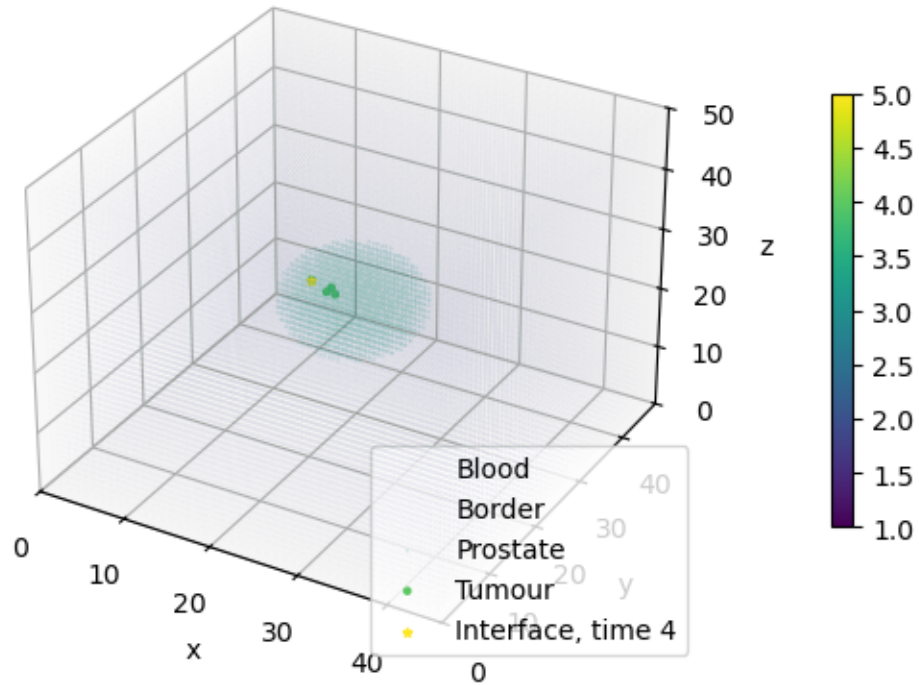
PSA, $t = 8$, xyz







Interface, time 4, xyz



At time 4:

No. tumour cells 4, prostate cells 2102, blood cells 101529

PSA_top_level 5.284337e-11

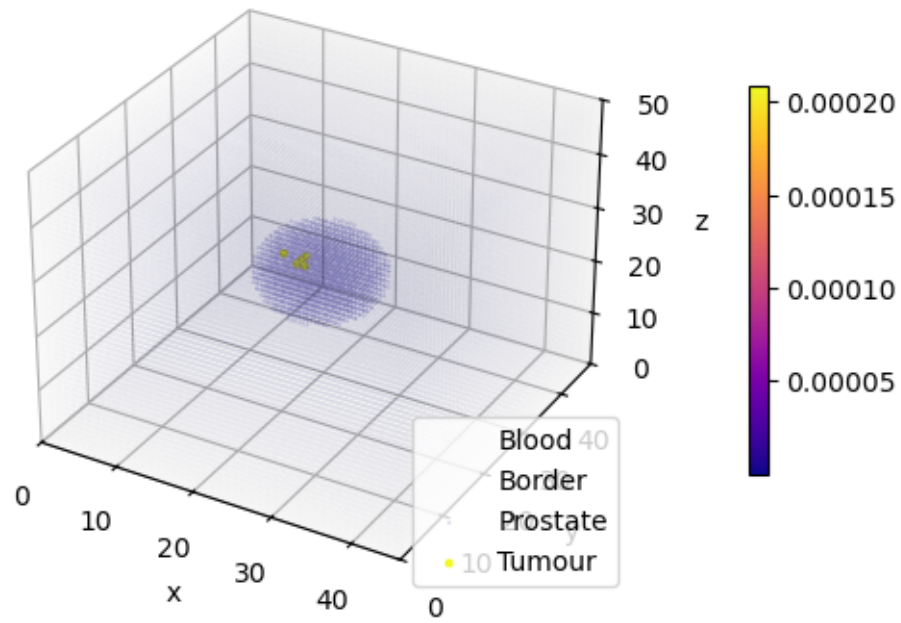
Time 5

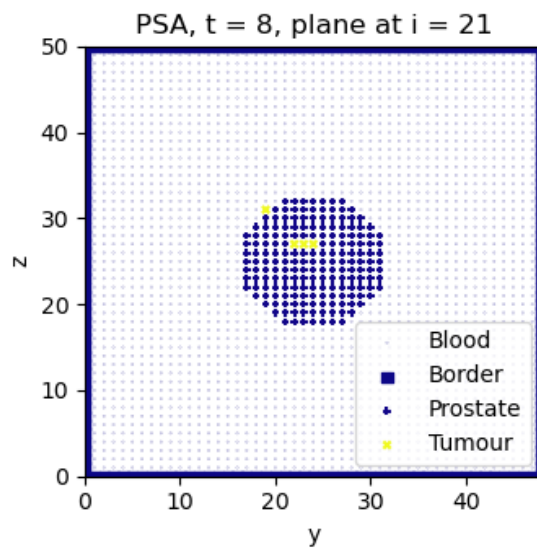
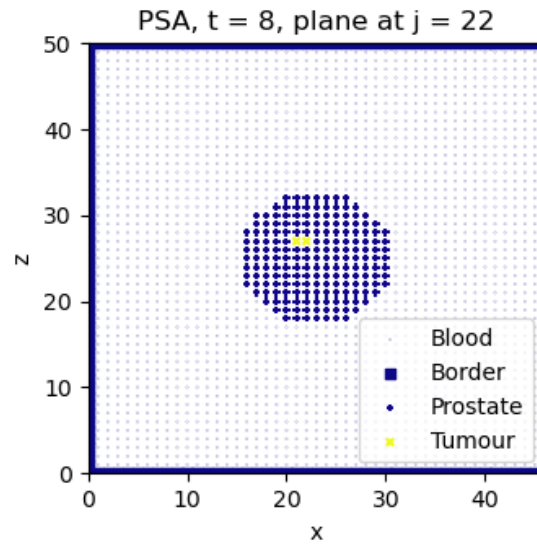
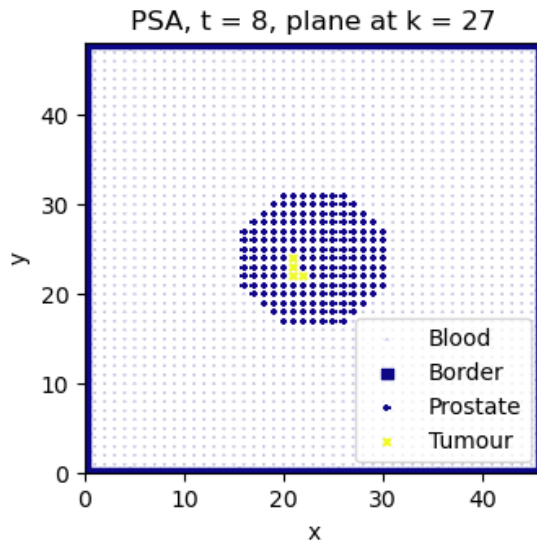
Diffusion PSA_top, with tumour

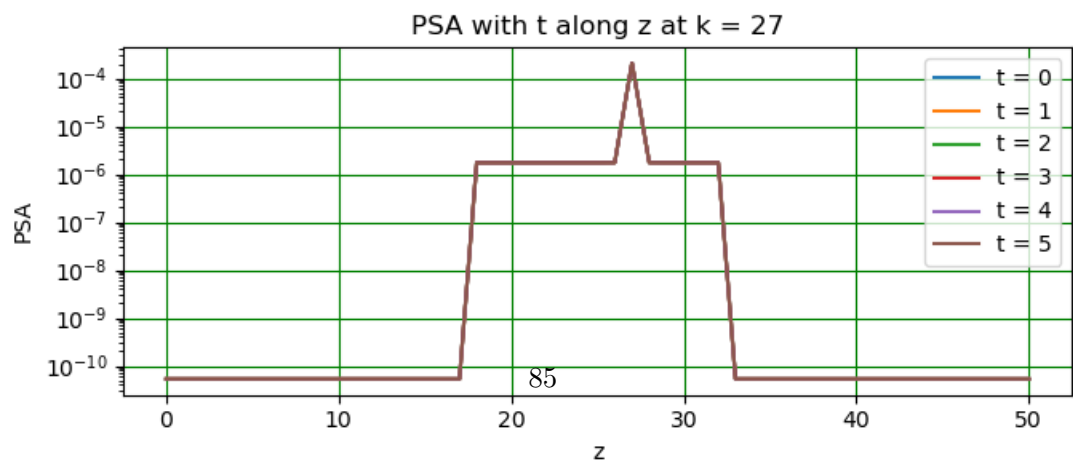
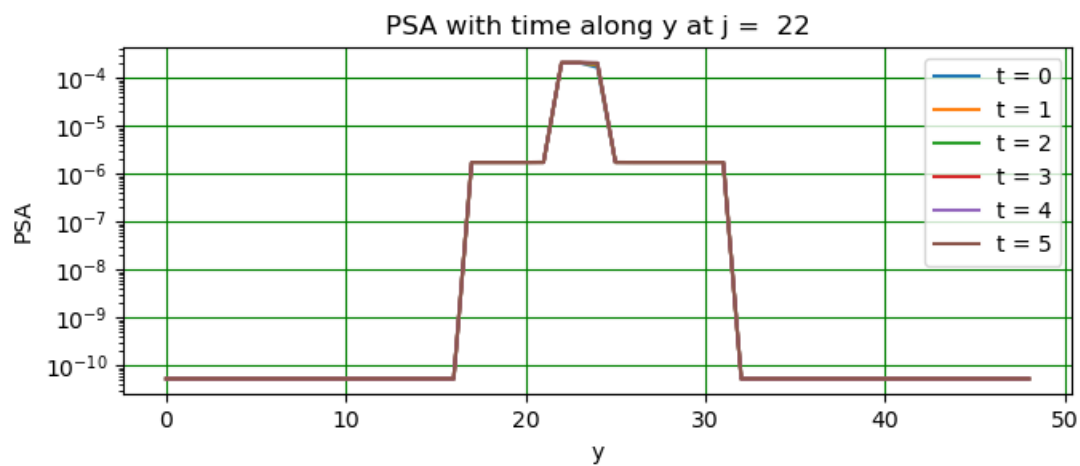
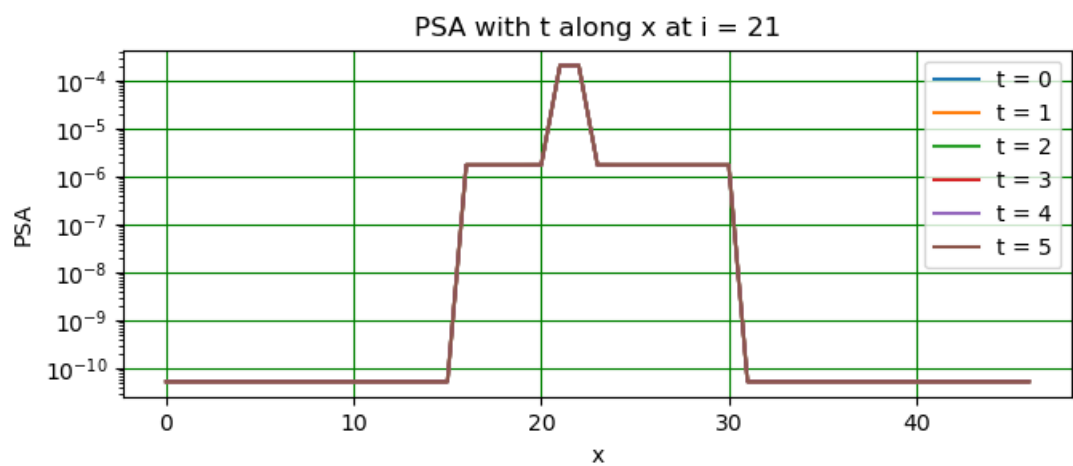
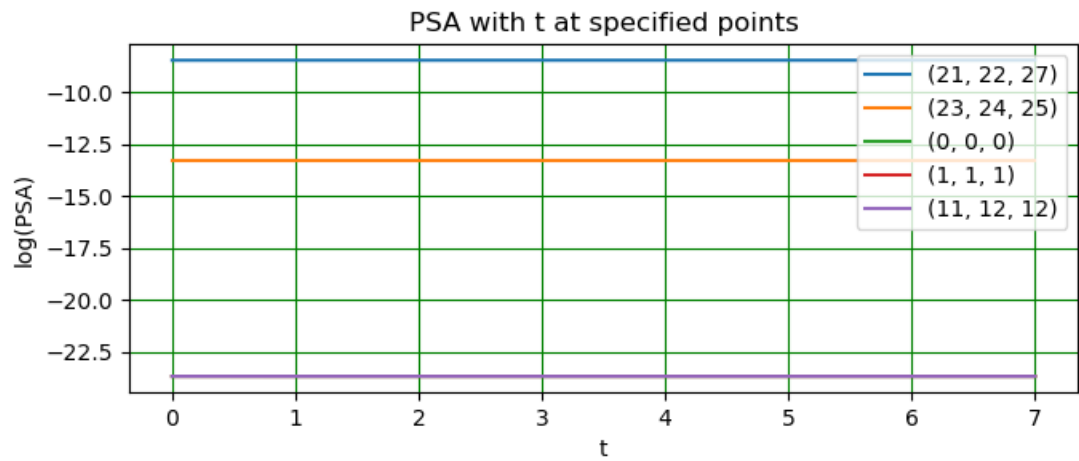
Diffusion converged, nt = 8, ext_test = 7.415641e-08, prostate_test =

6.533519e-04

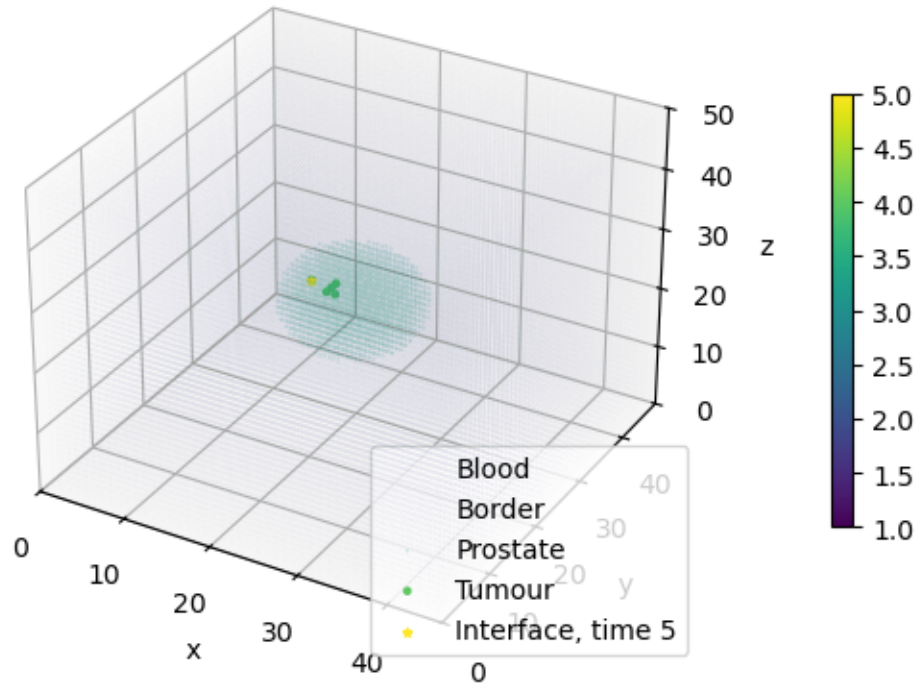
PSA, $t = 8$, xyz







Interface, time 5, xyz



At time 5:

No. tumour cells 5, prostate cells 2102, blood cells 101528

PSA_top_level 5.276988e-11

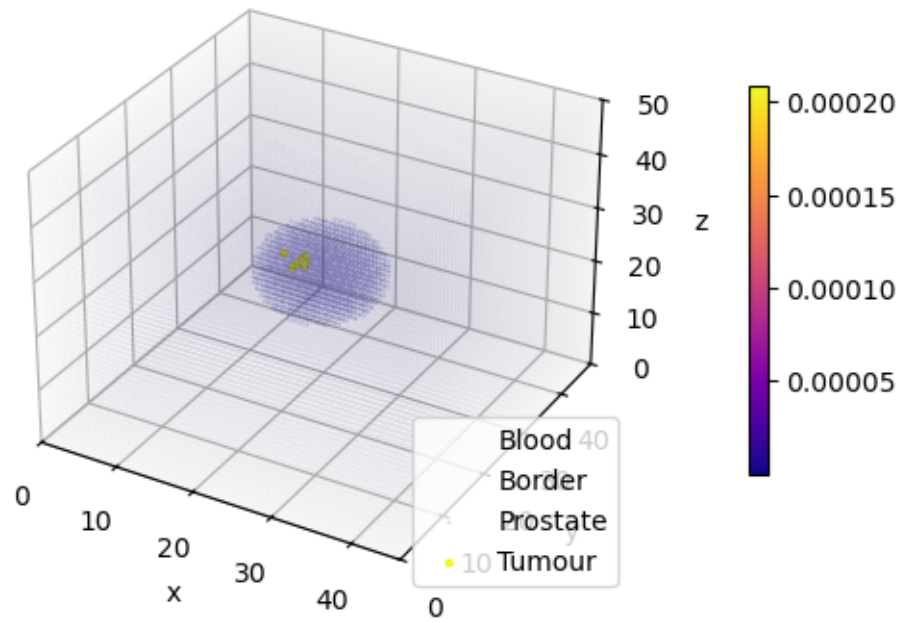
Time 6

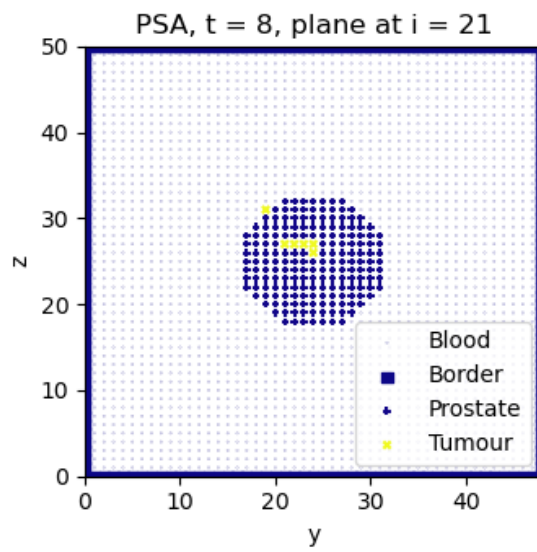
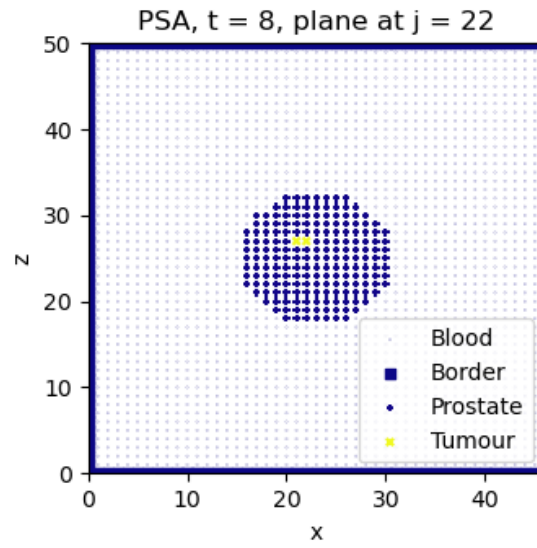
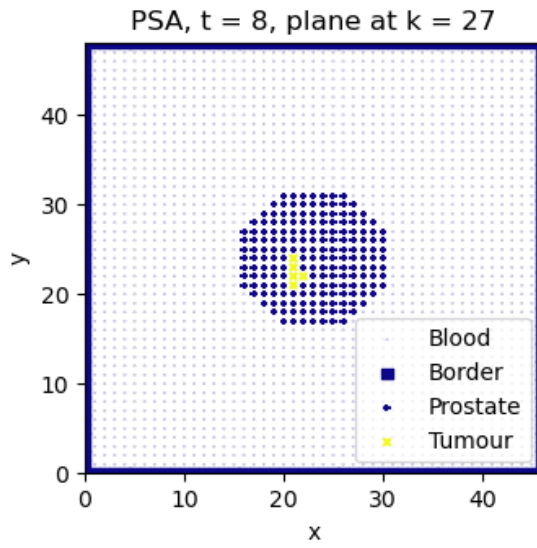
Diffusion PSA_top, with tumour

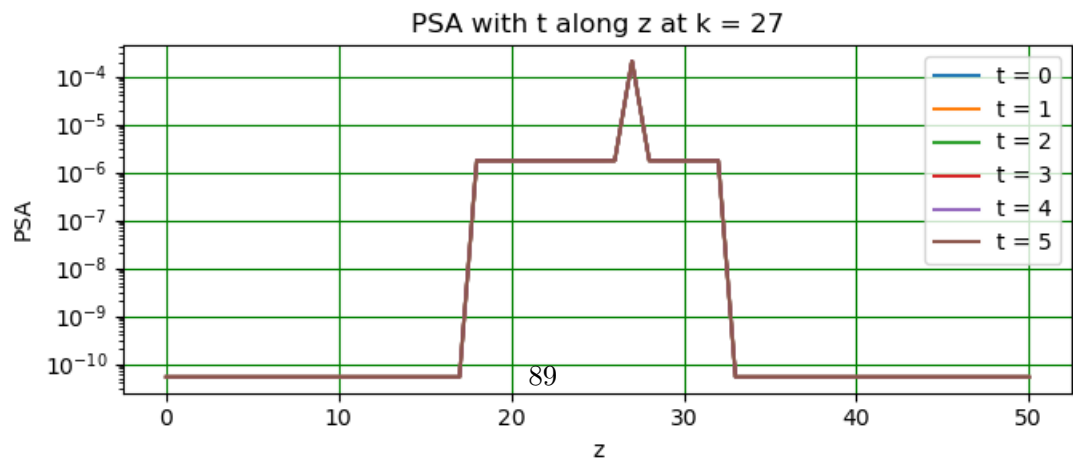
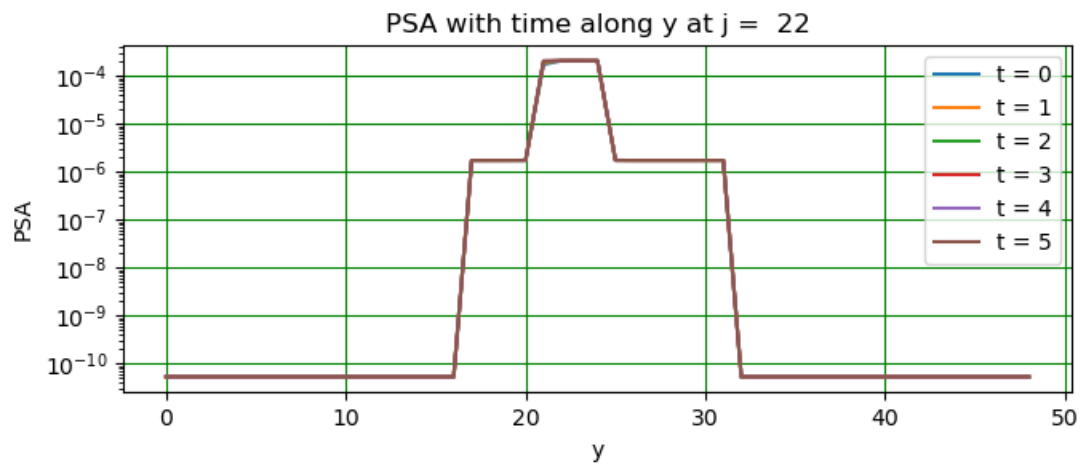
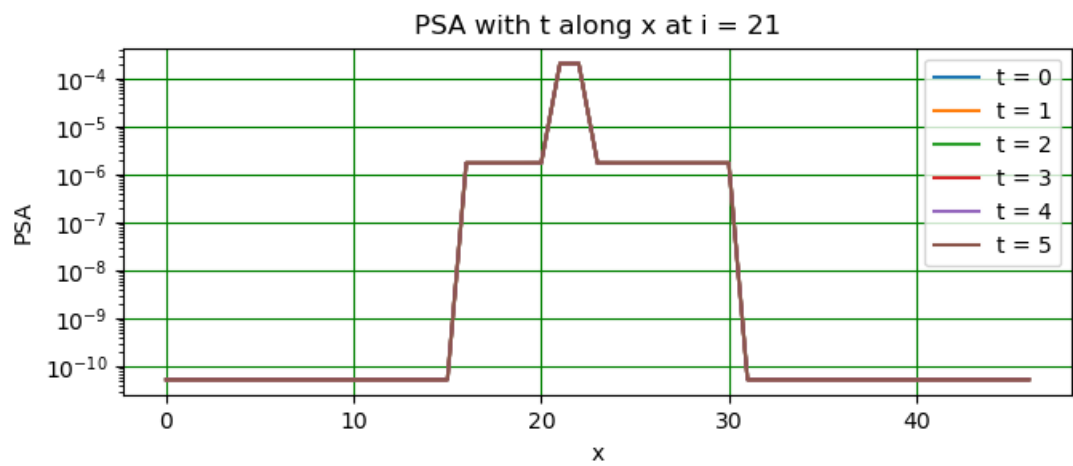
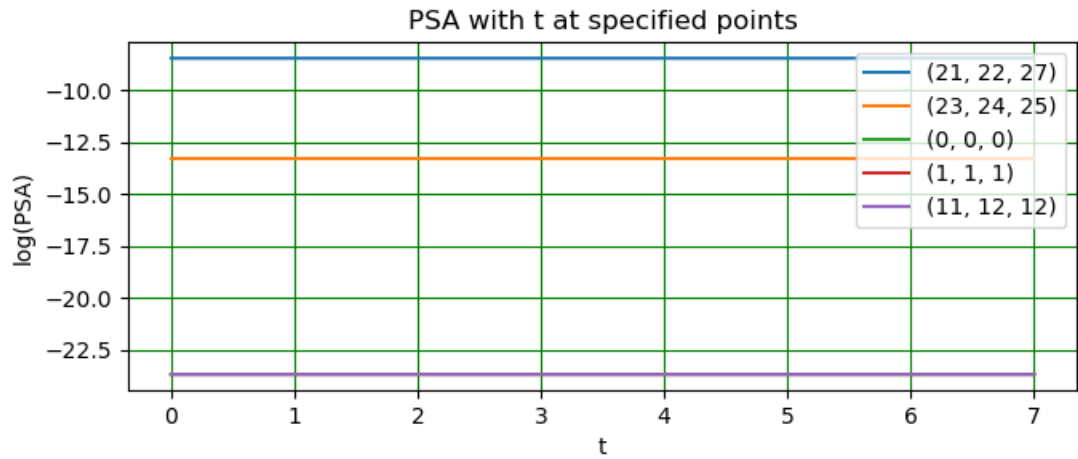
Diffusion converged, nt = 8, ext_test = 6.309882e-09, prostate_test =

5.442749e-04

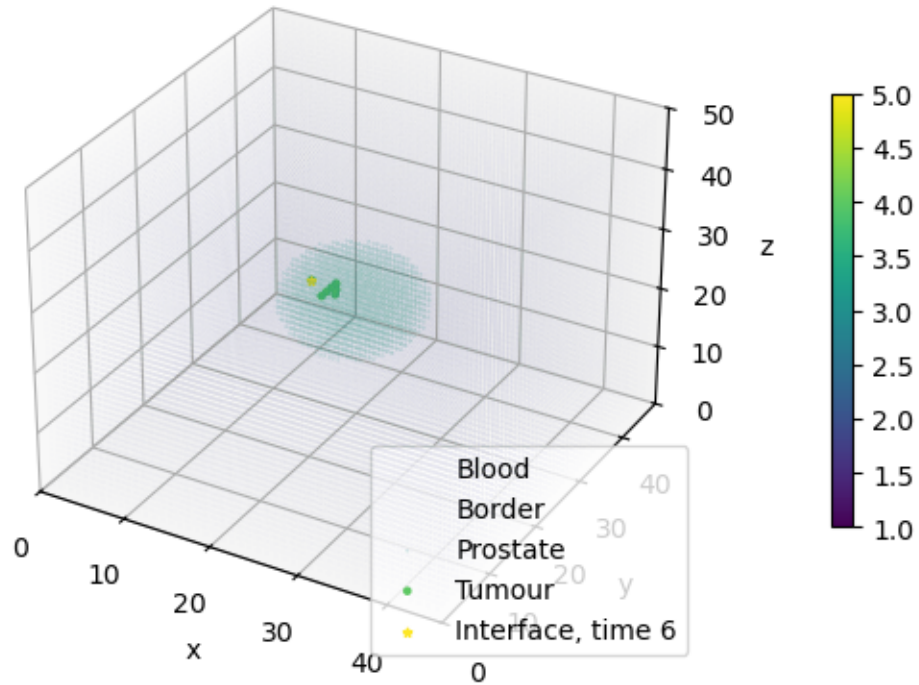
PSA, $t = 8$, xyz







Interface, time 6, xyz



At time 6:

No. tumour cells 7, prostate cells 2102, blood cells 101526

PSA_top_level 5.276619e-11

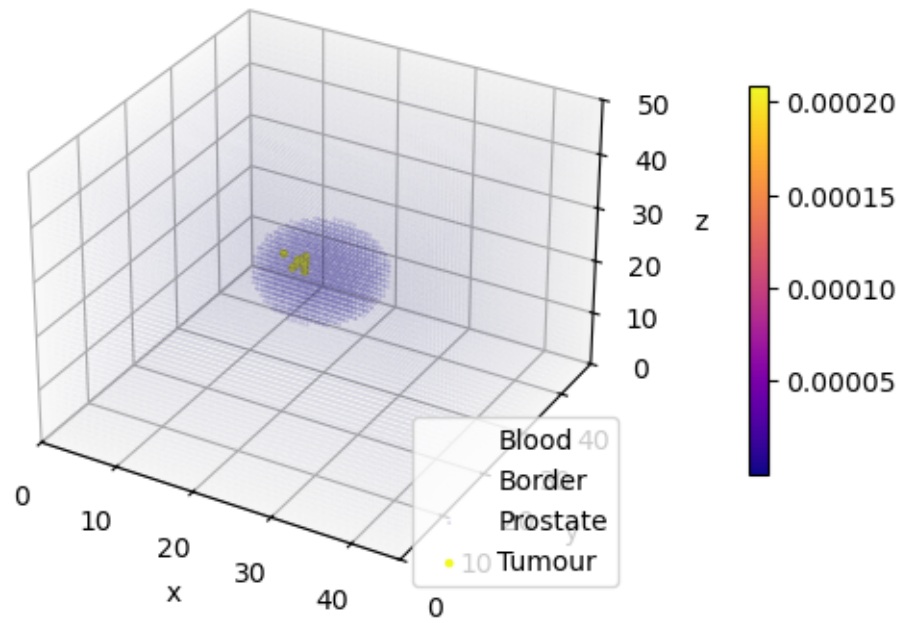
Time 7

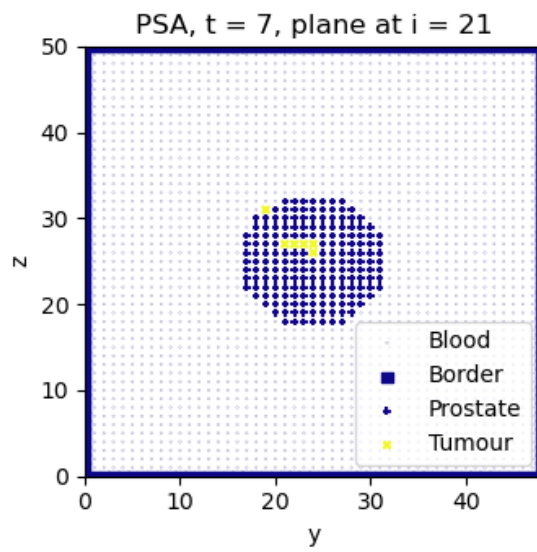
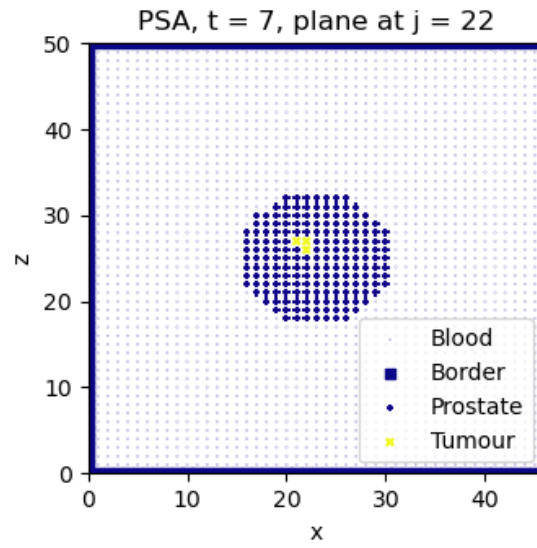
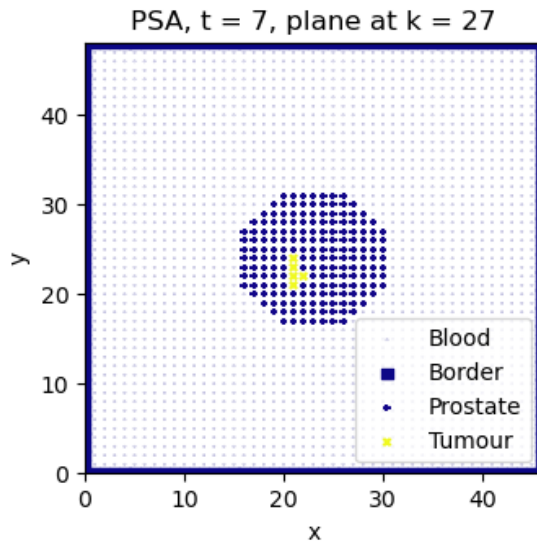
Diffusion PSA_top, with tumour

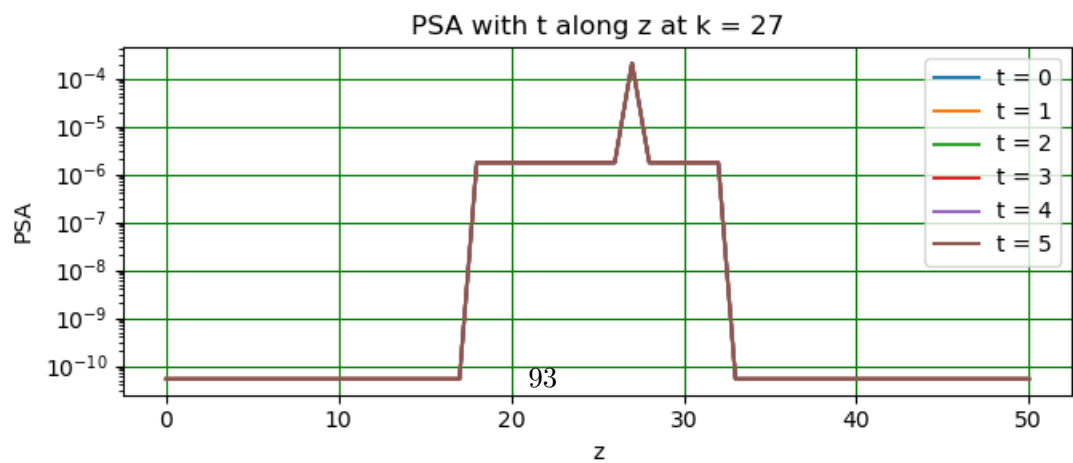
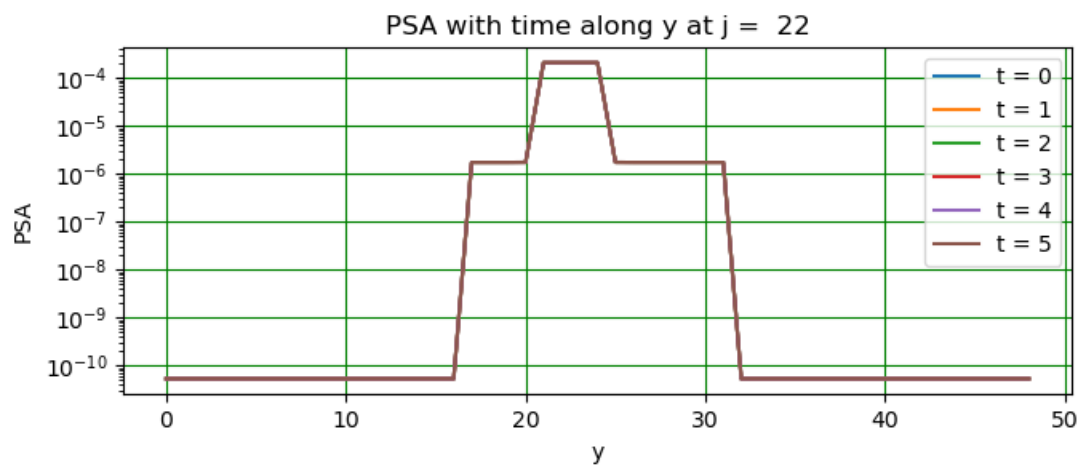
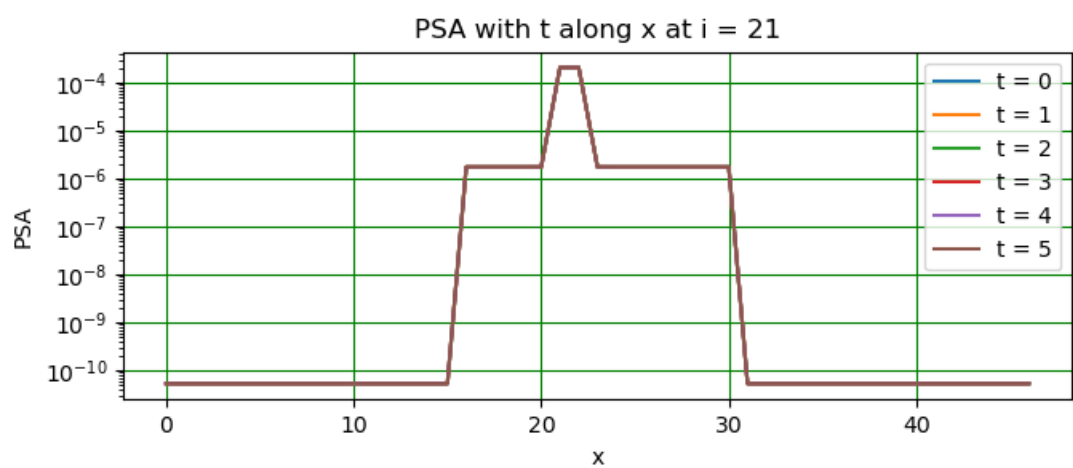
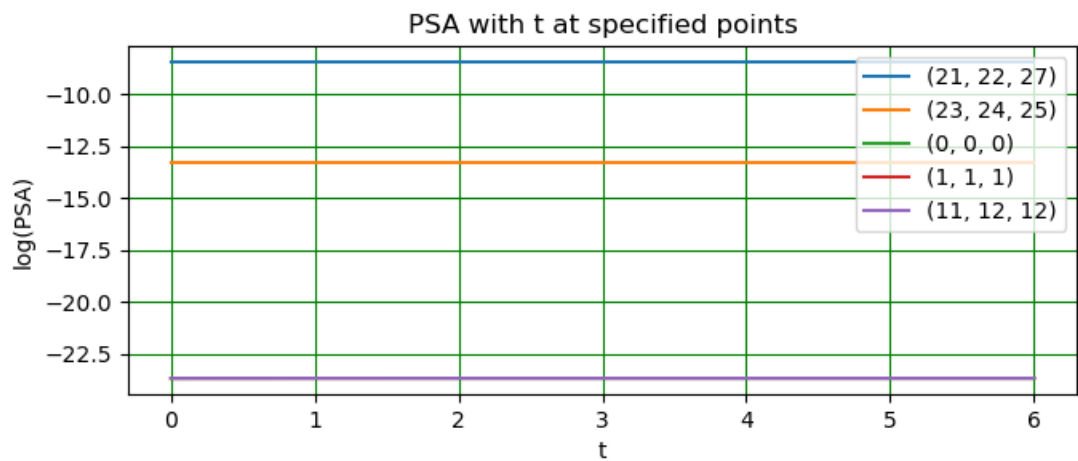
Diffusion converged, nt = 7, ext_test = 4.461020e-07, prostate_test =

7.577286e-04

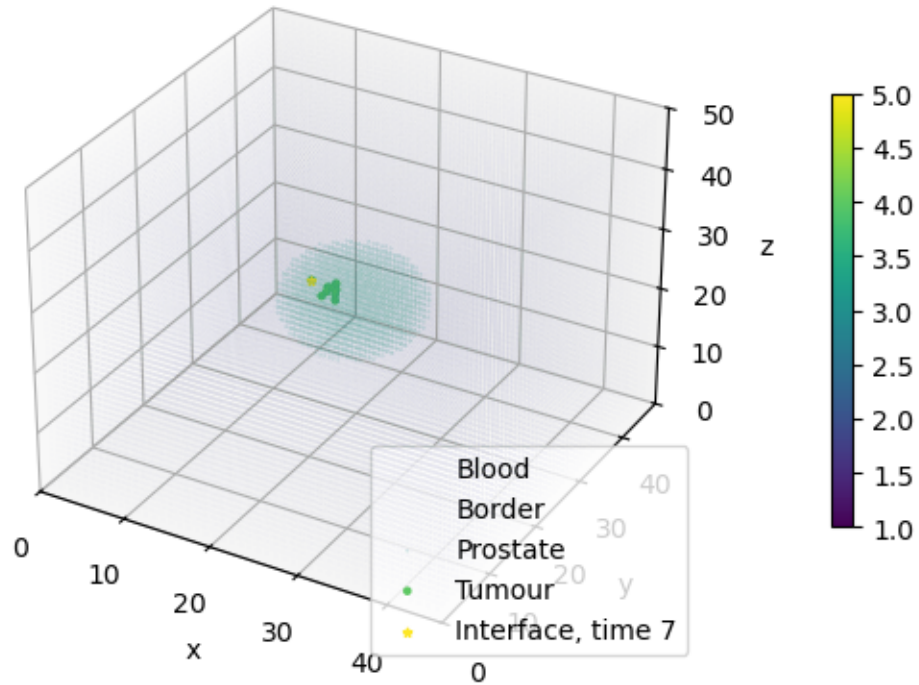
PSA, $t = 7$, xyz







Interface, time 7, xyz



At time 7:

No. tumour cells 9, prostate cells 2102, blood cells 101524

PSA_top_level 5.290530e-11

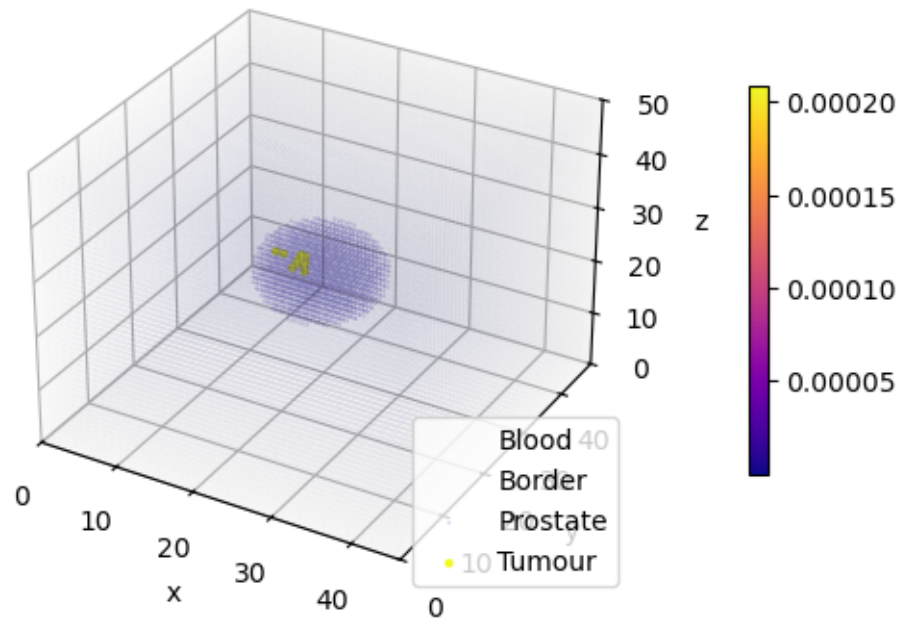
Time 8

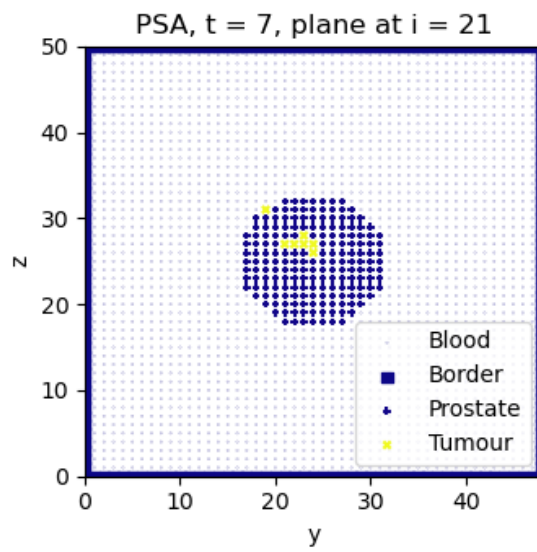
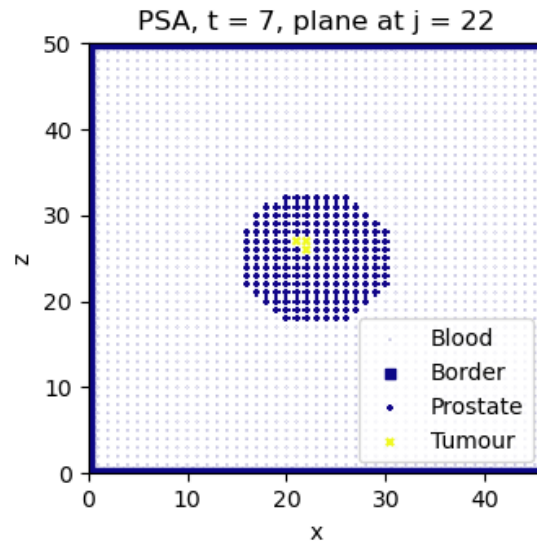
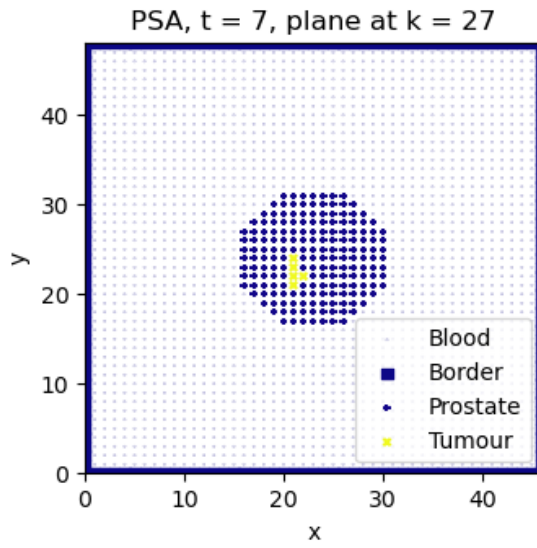
Diffusion PSA_top, with tumour

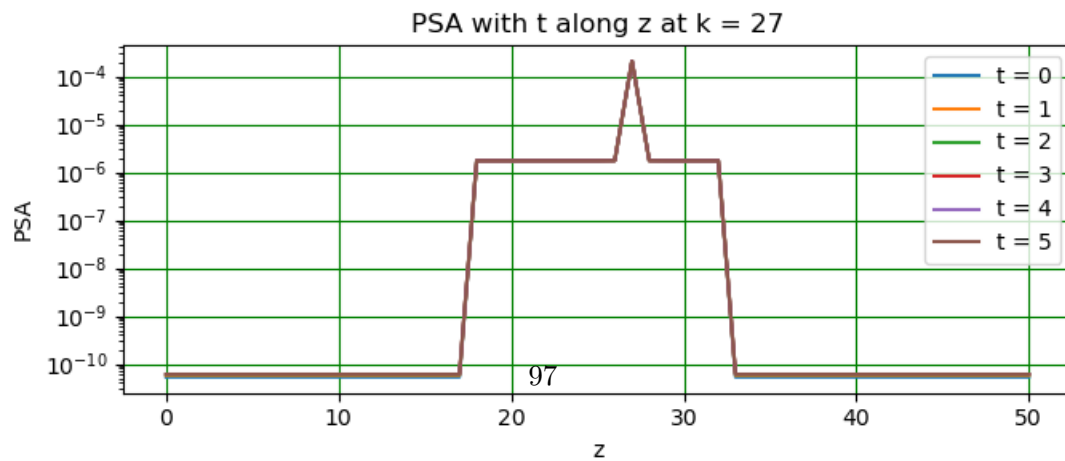
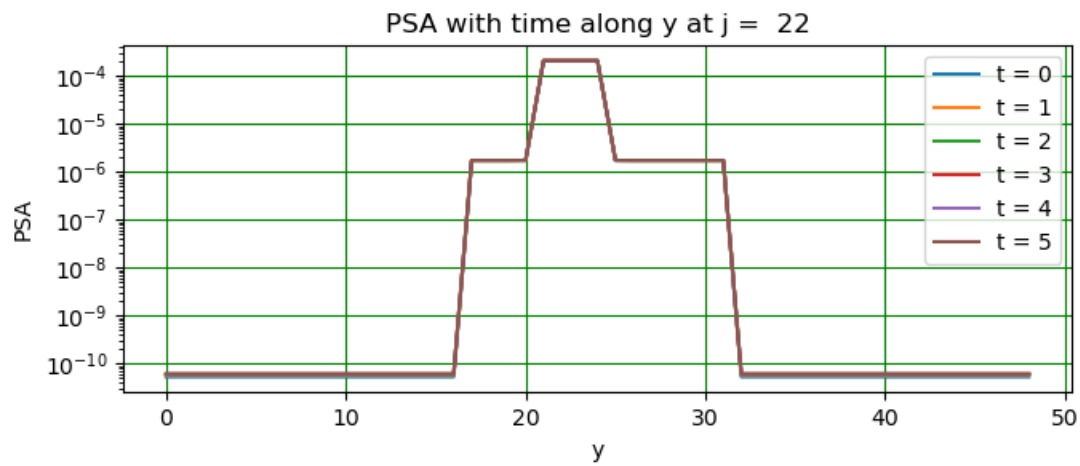
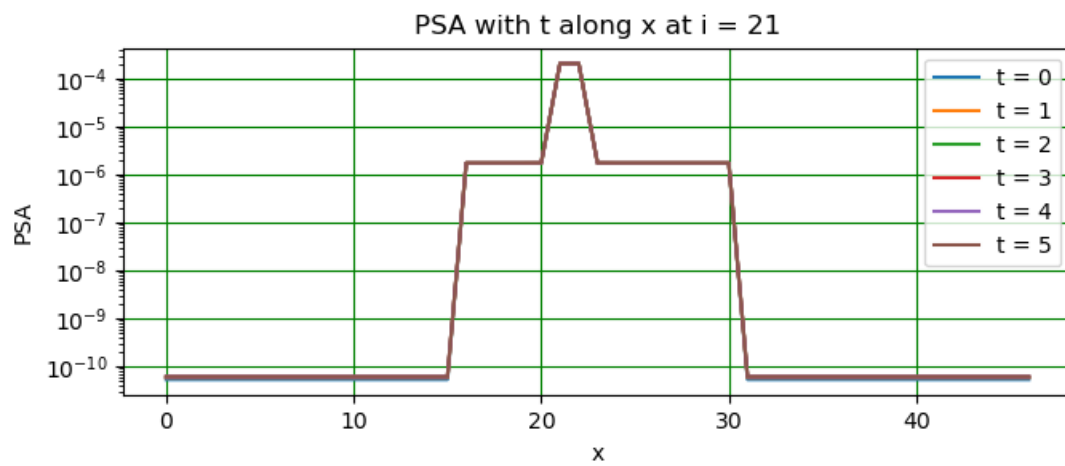
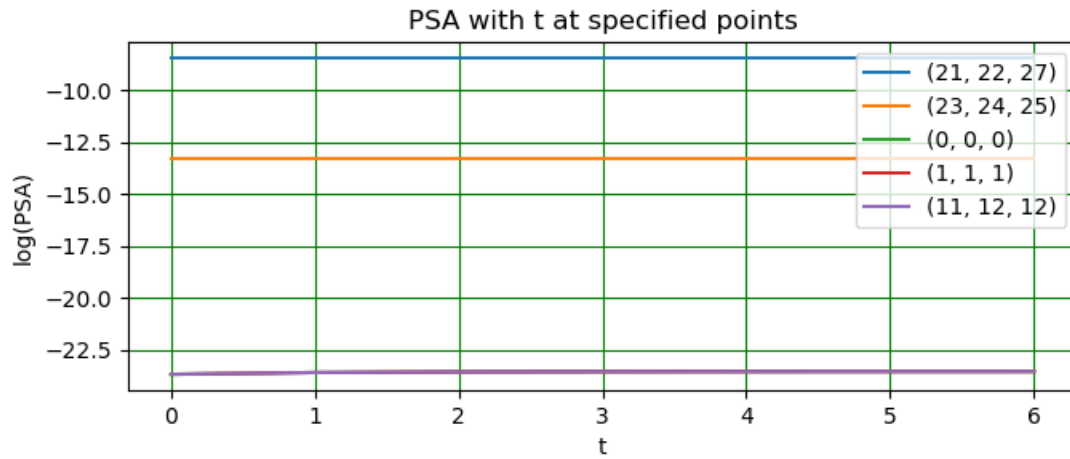
Diffusion converged, nt = 7, ext_test = 3.836313e-04, prostate_test =

6.106183e-04

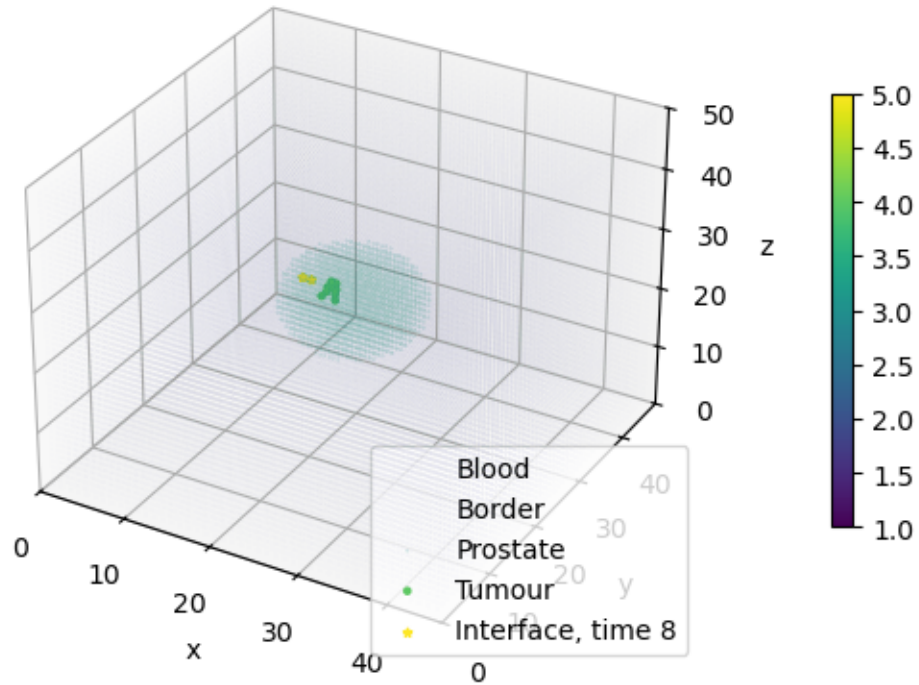
PSA, $t = 7$, xyz







Interface, time 8, xyz



At time 8:

No. tumour cells 12, prostate cells 2102, blood cells 101521

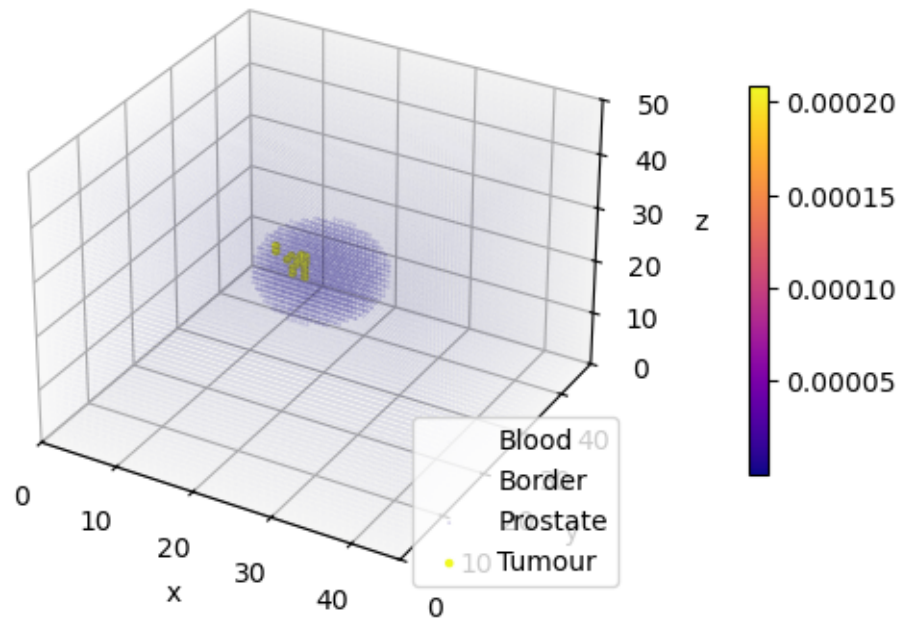
PSA_top_level 6.105627e-11

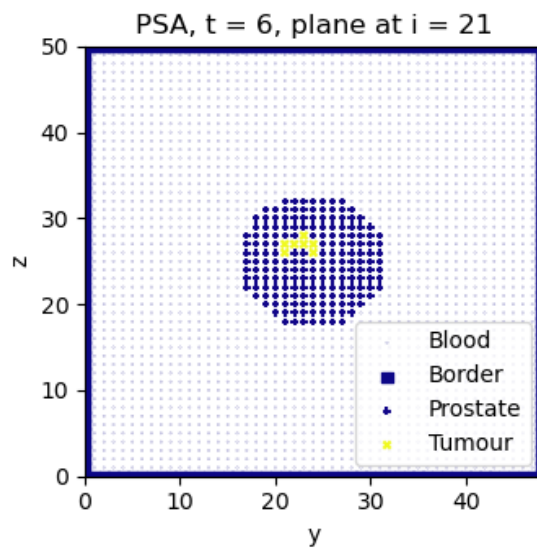
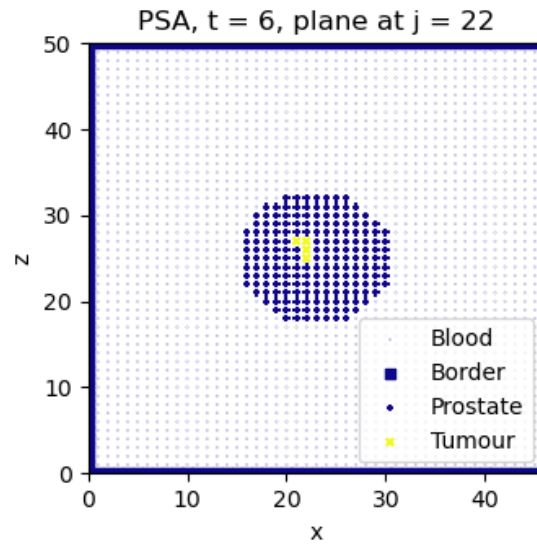
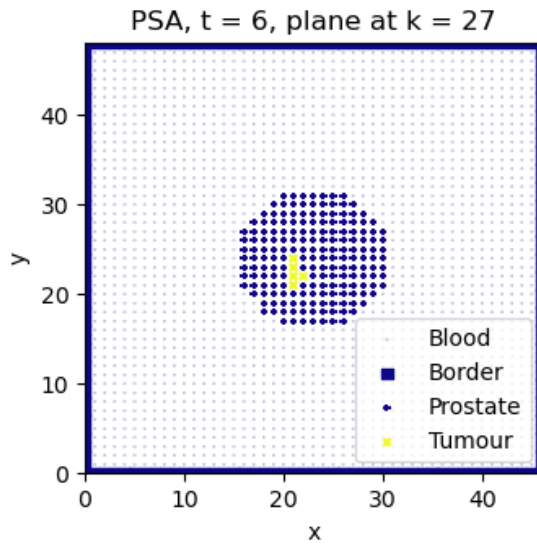
Time 9

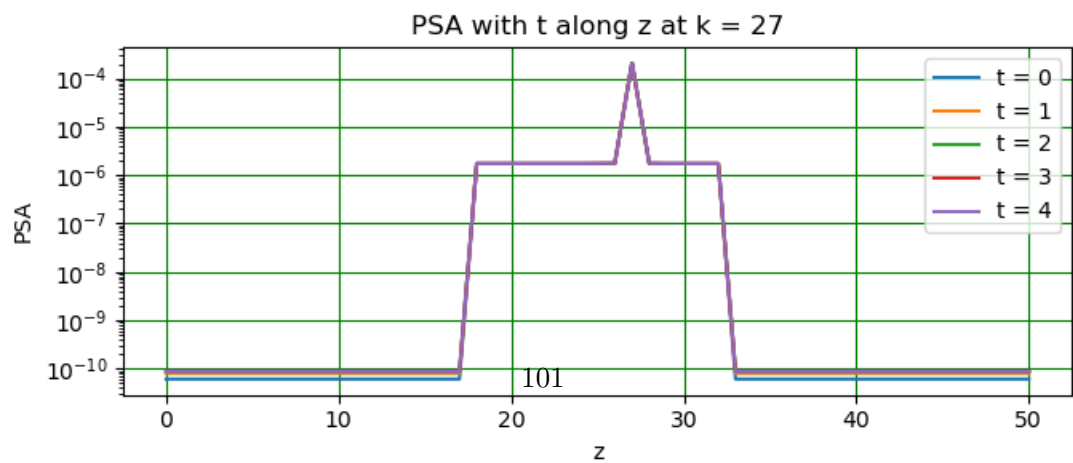
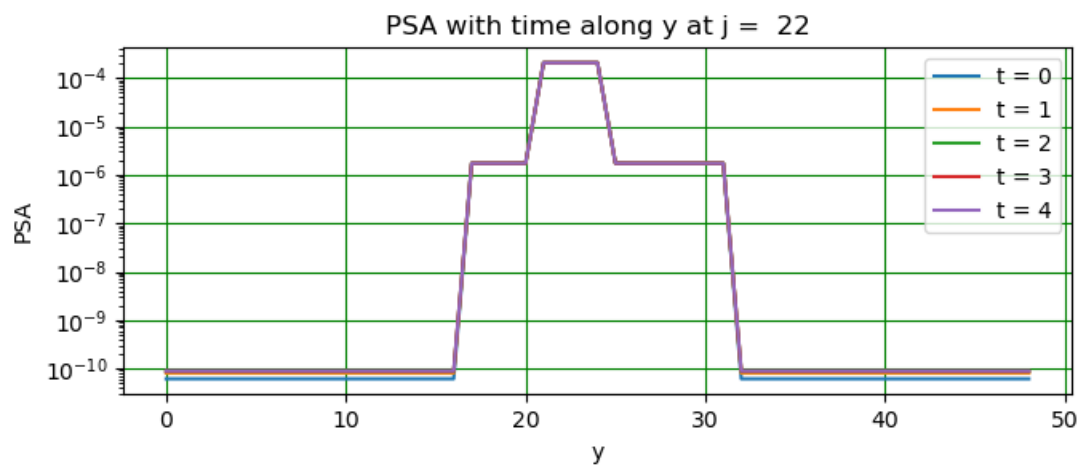
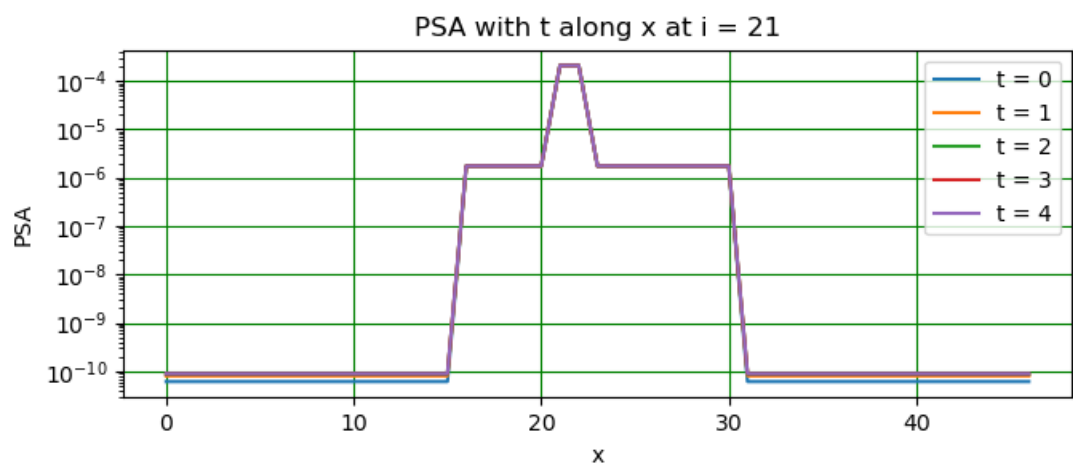
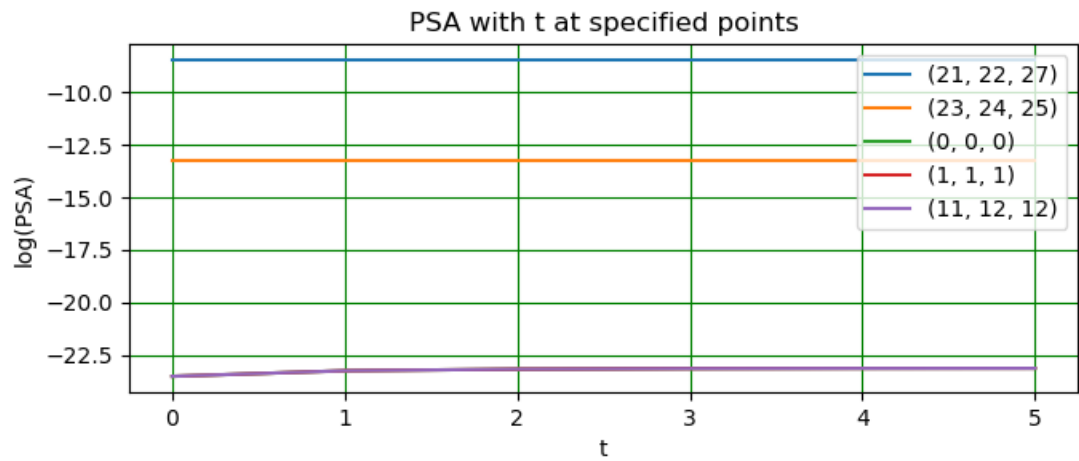
Diffusion PSA_top, with tumour

Diffusion converged, nt = 6, ext_test = 8.638301e-04, prostate_test = 8.724802e-04

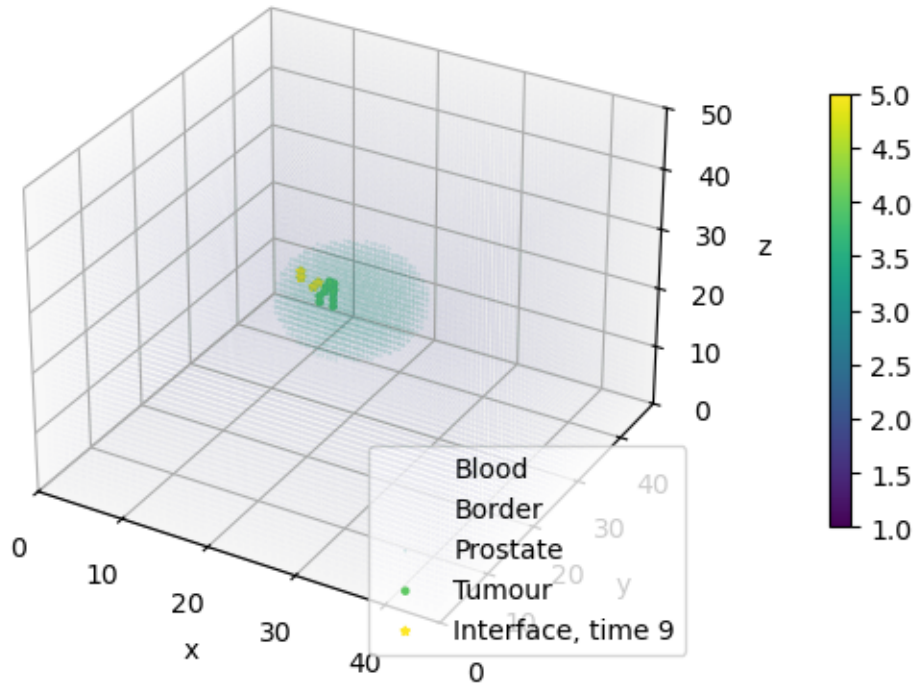
PSA, $t = 6$, xyz







Interface, time 9, xyz



At time 9:

No. tumour cells 16, prostate cells 2102, blood cells 101517

PSA_top_level 8.965983e-11

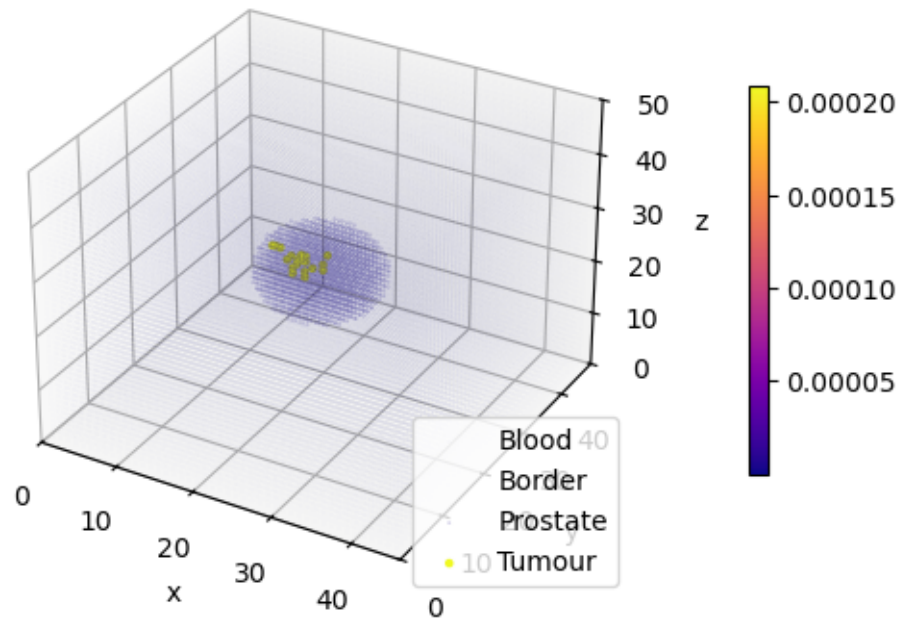
Time 10

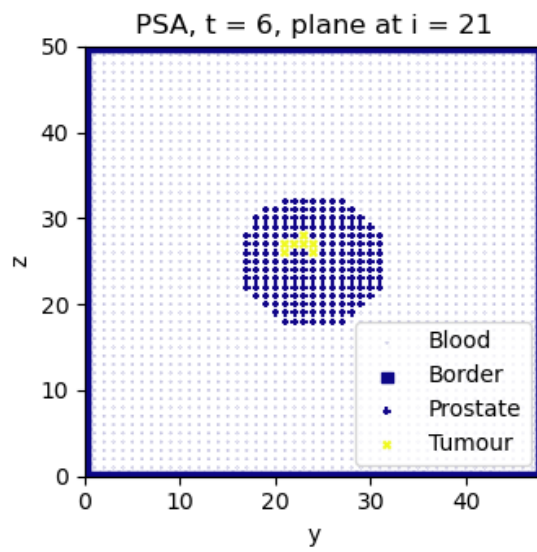
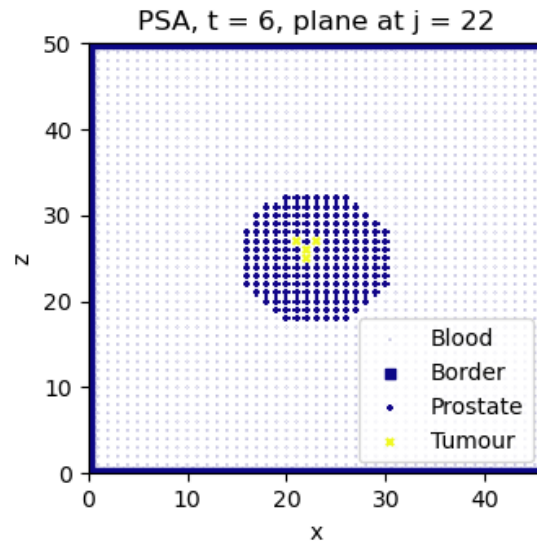
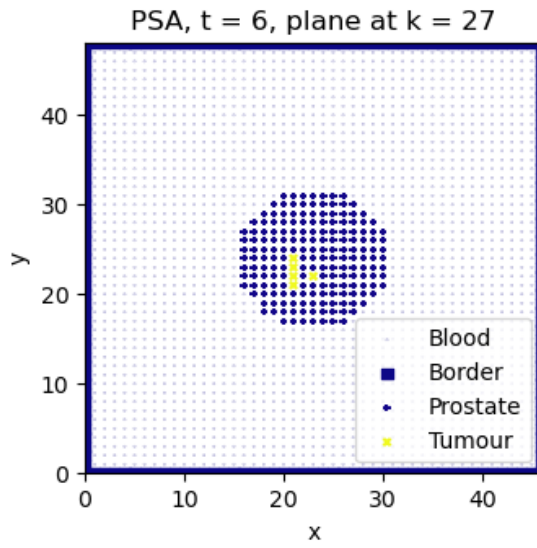
Diffusion PSA_top, with tumour

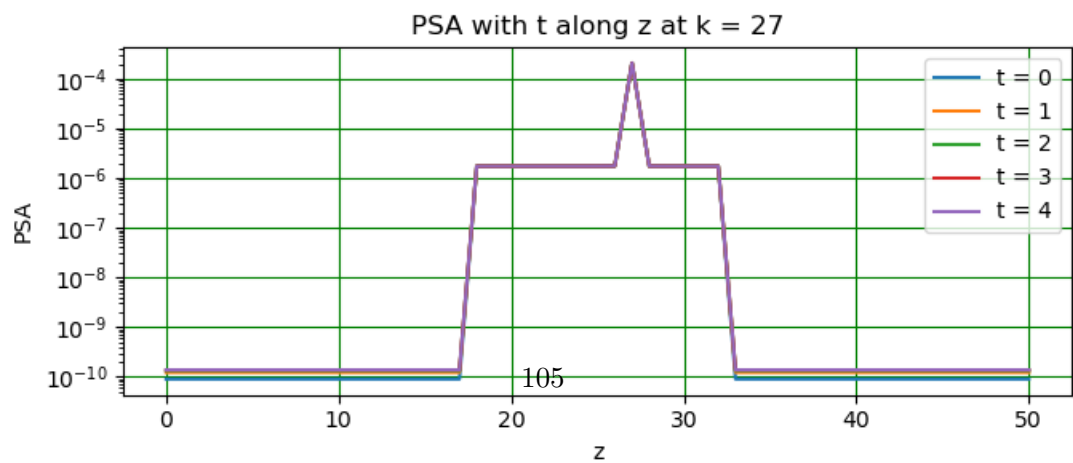
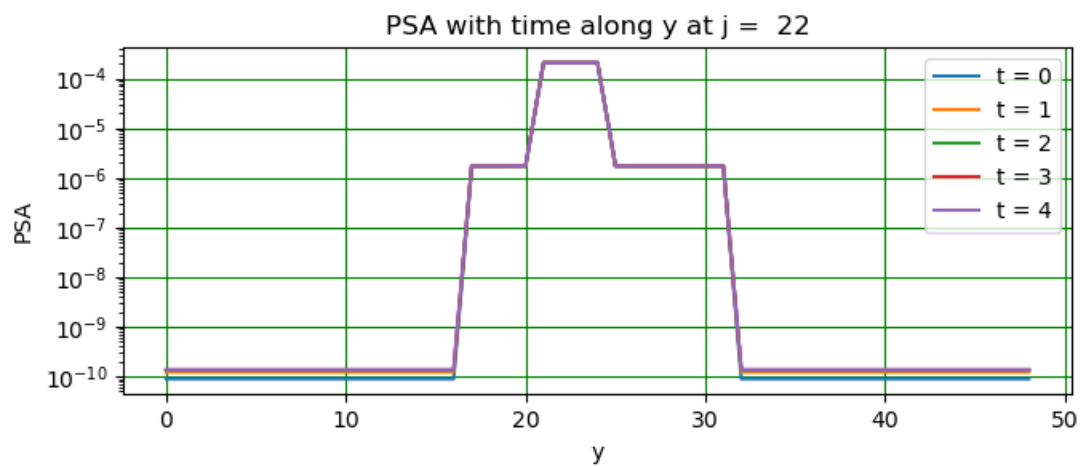
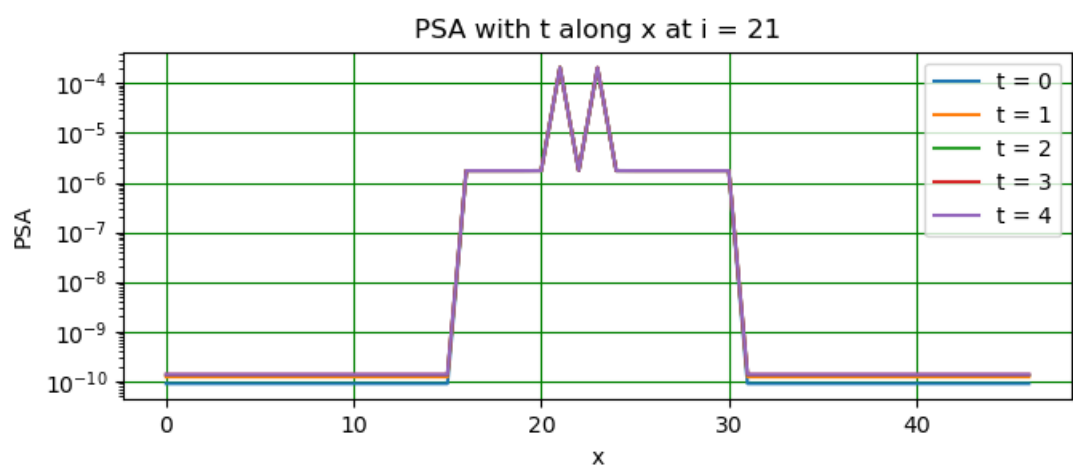
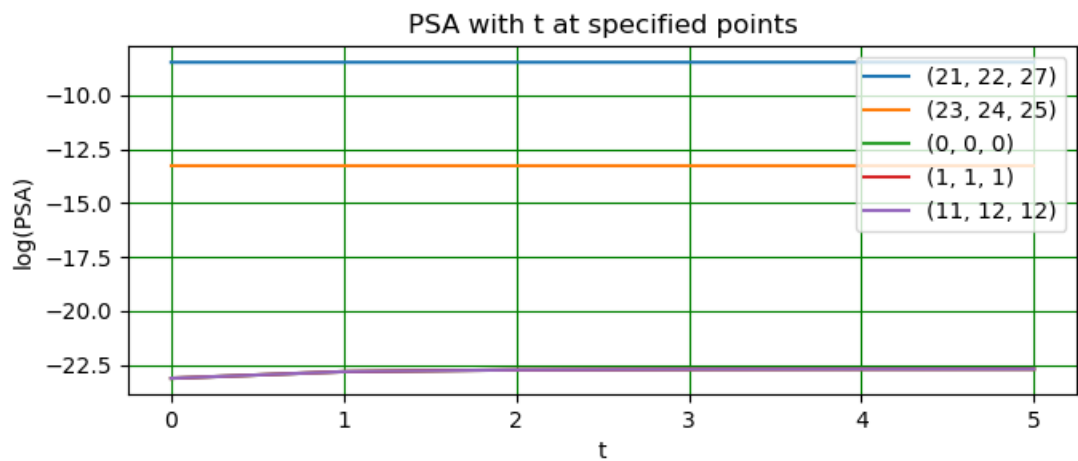
Diffusion converged, nt = 6, ext_test = 5.402198e-04, prostate_test =

6.684431e-04

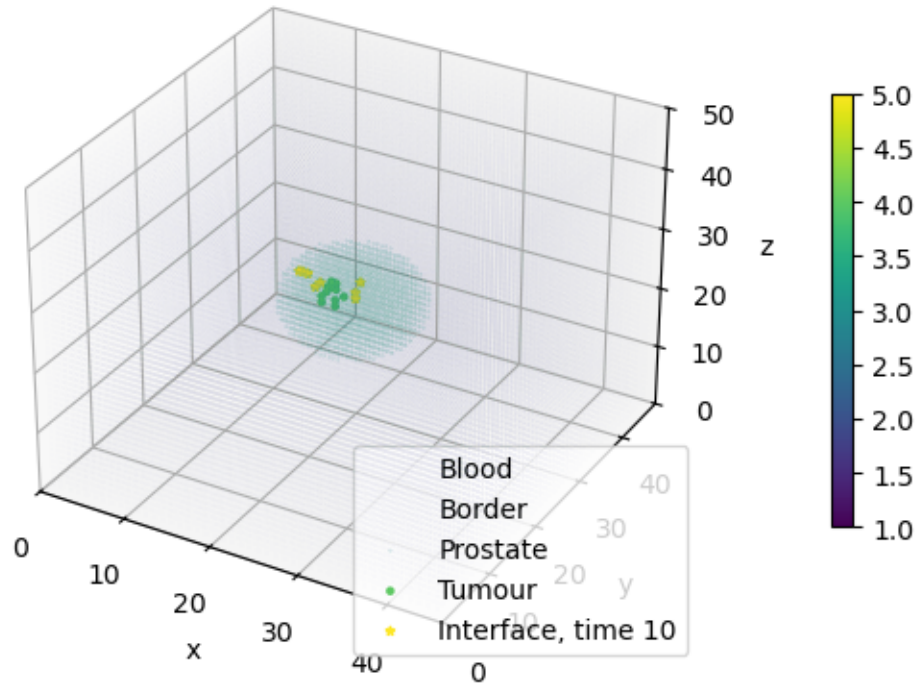
PSA, $t = 6$, xyz







Interface, time 10, xyz



At time 10:

No. tumour cells 20, prostate cells 2102, blood cells 101513

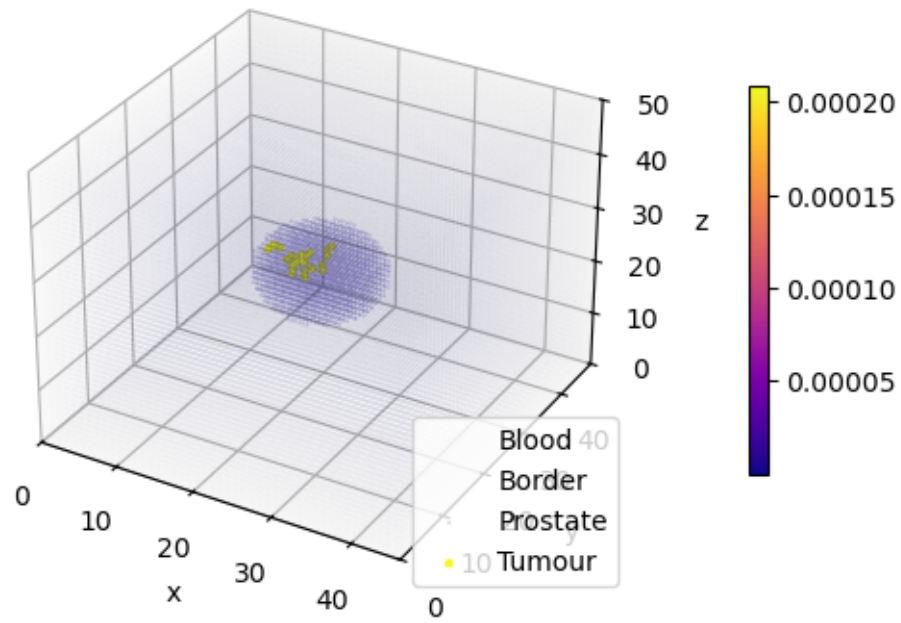
PSA_top_level 1.381568e-10

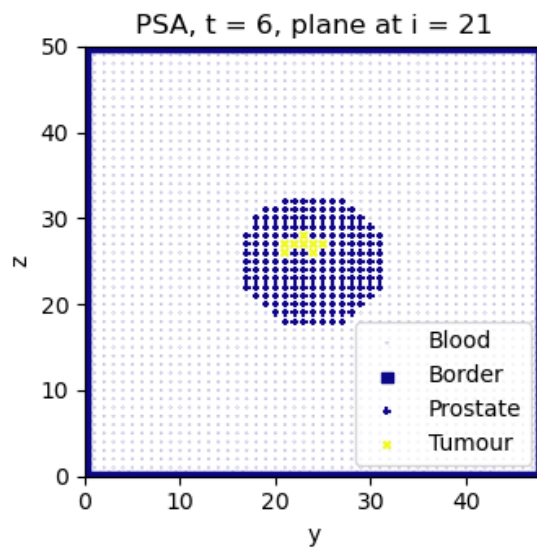
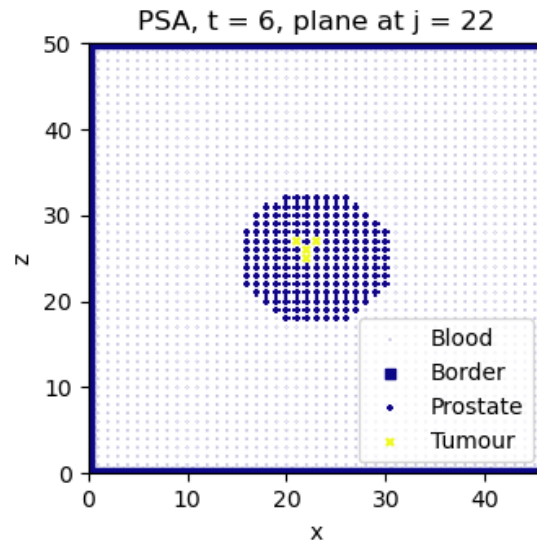
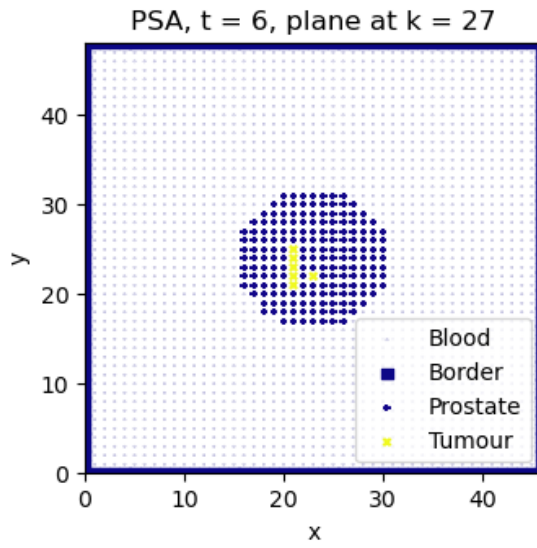
Time 11

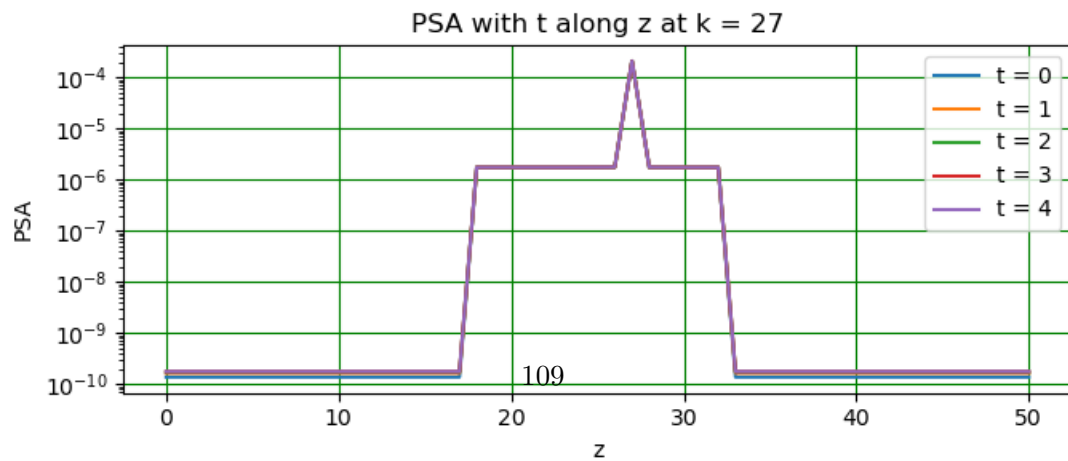
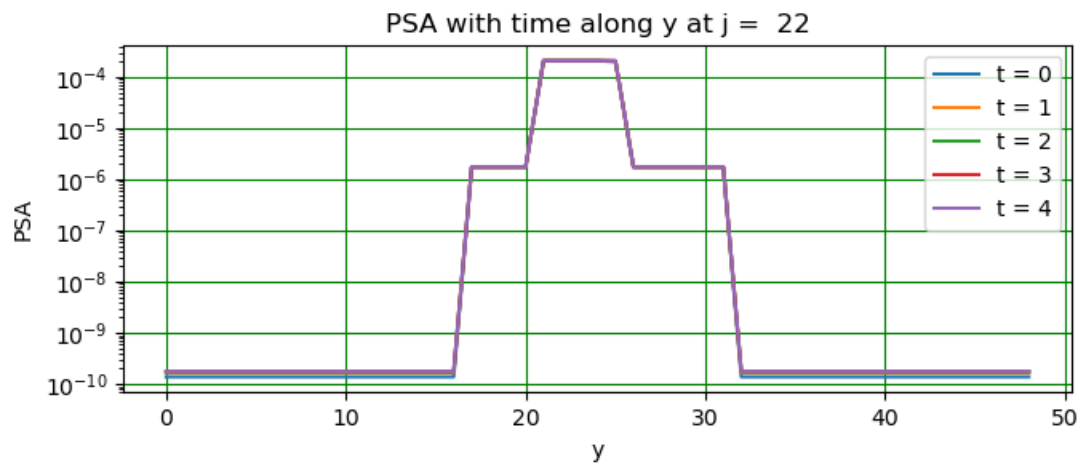
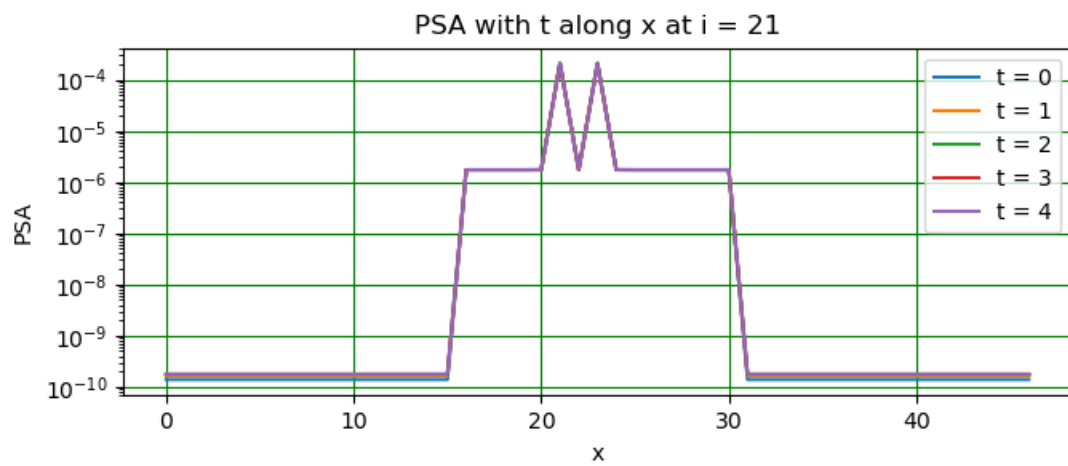
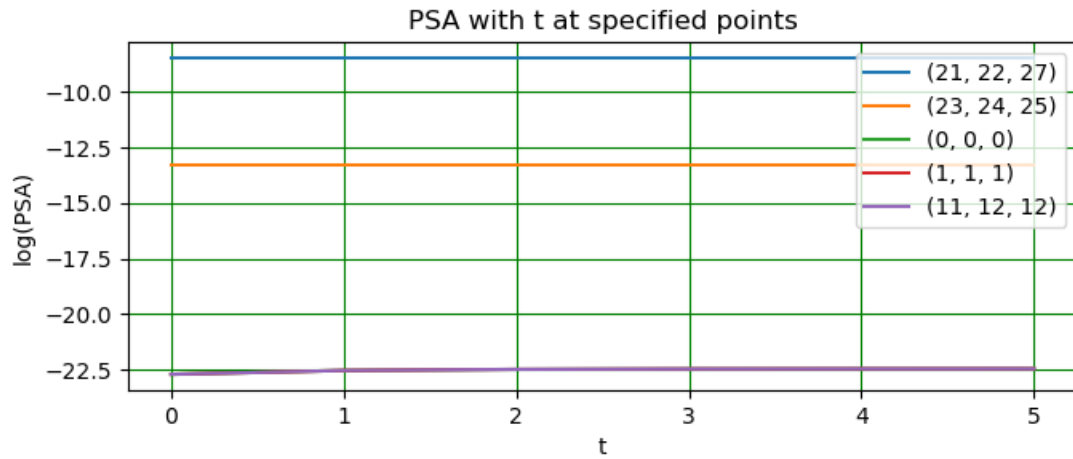
Diffusion PSA_top, with tumour

Diffusion converged, nt = 6, ext_test = 5.494959e-04, prostate_test = 5.405287e-04

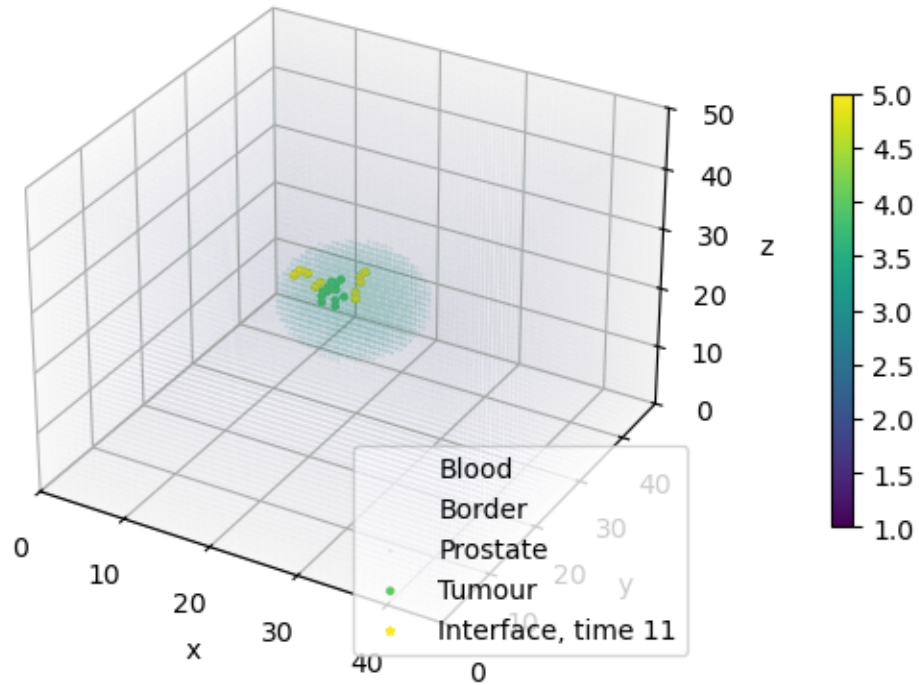
PSA, $t = 6$, xyz







Interface, time 11, xyz



At time 11:

No. tumour cells 26, prostate cells 2102, blood cells 101507

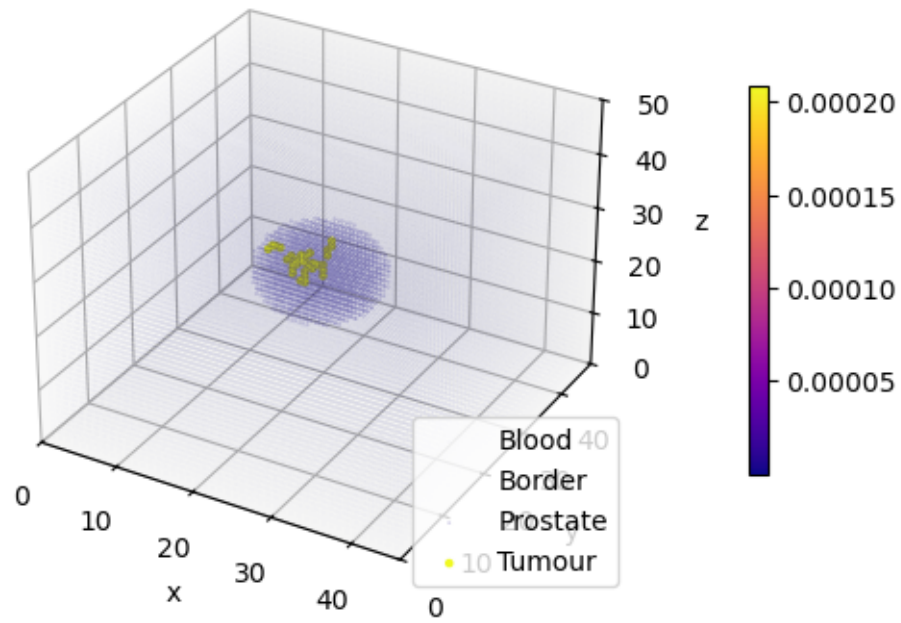
PSA_top_level 1.778203e-10

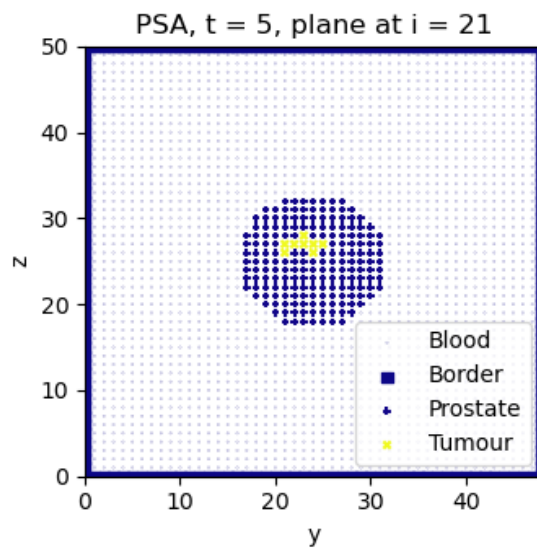
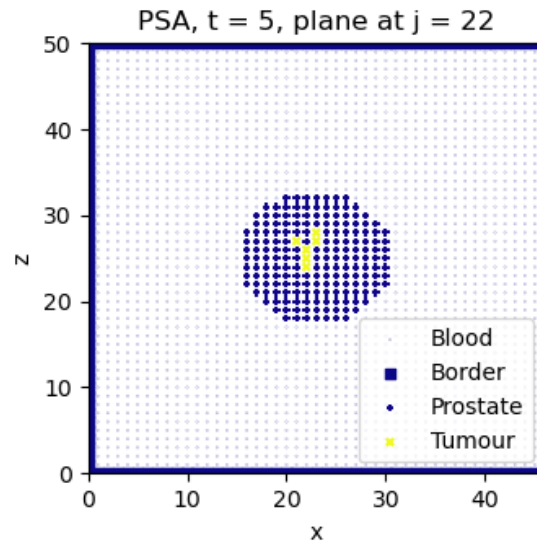
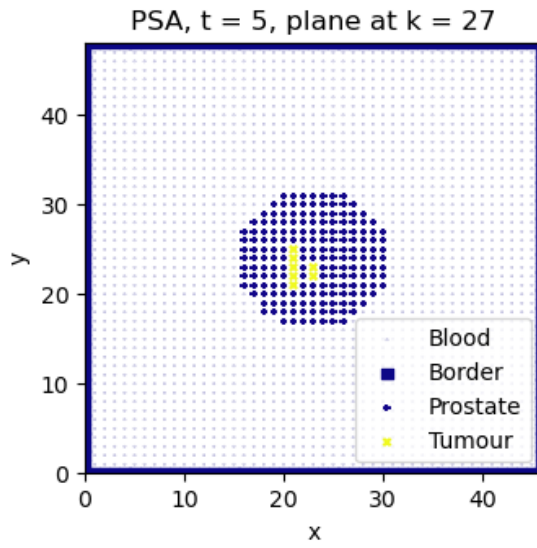
Time 12

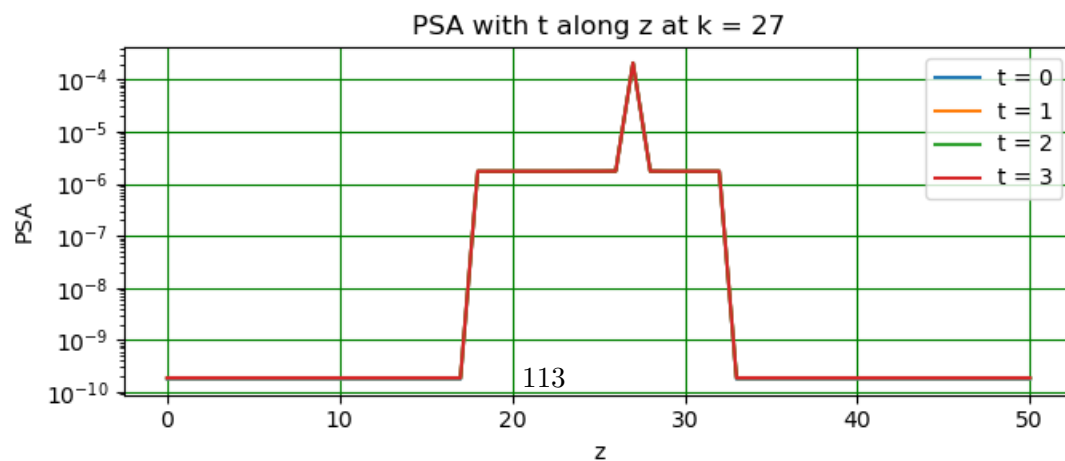
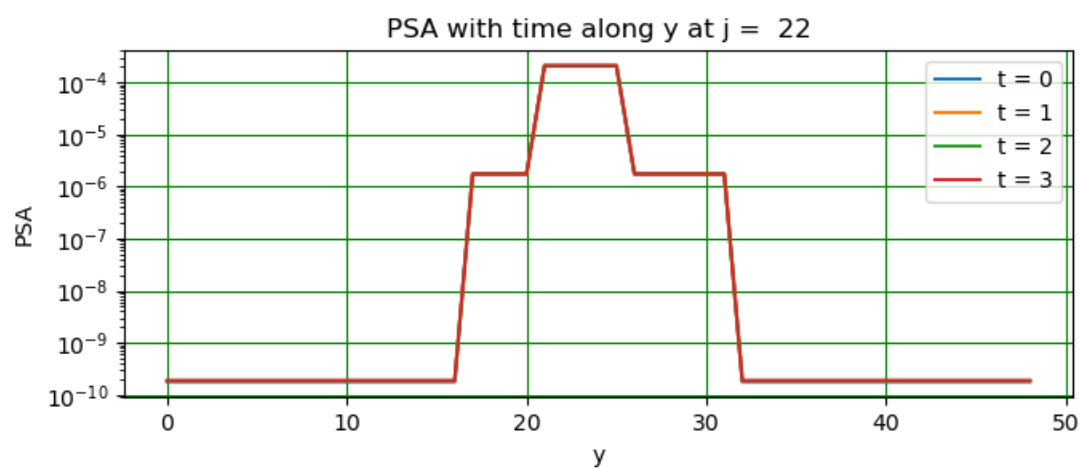
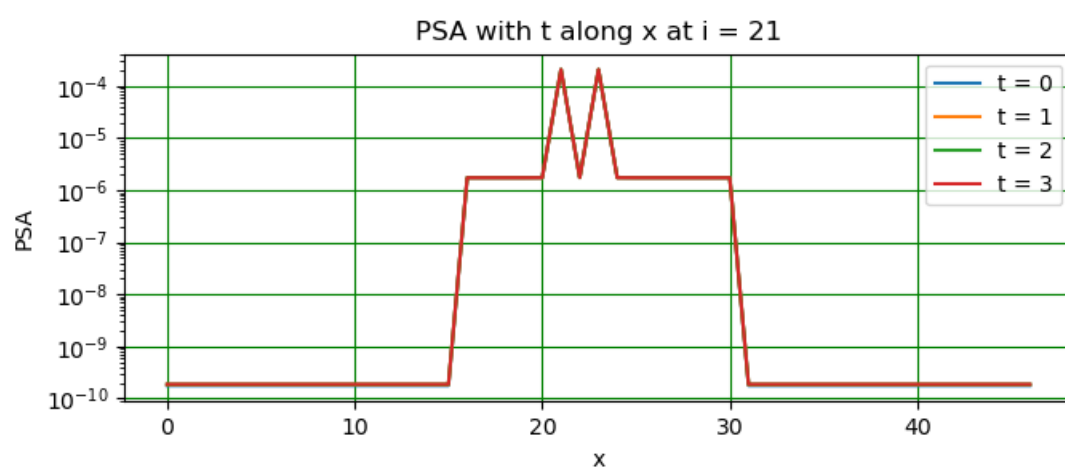
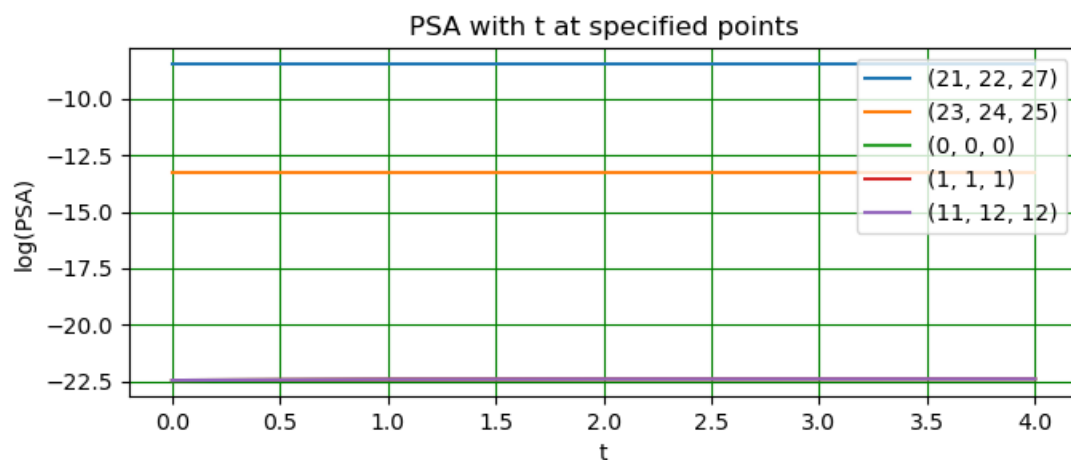
Diffusion PSA_top, with tumour

Diffusion converged, nt = 5, ext_test = 3.455097e-04, prostate_test = 7.808609e-04

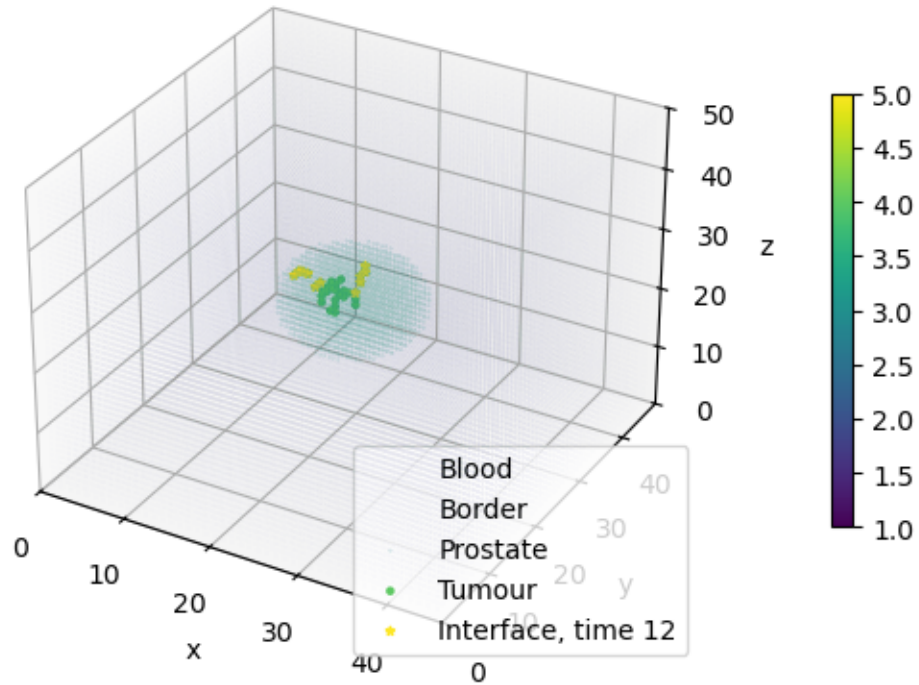
PSA, $t = 5$, xyz







Interface, time 12, xyz



At time 12:

No. tumour cells 33, prostate cells 2102, blood cells 101500

PSA_top_level 1.890371e-10

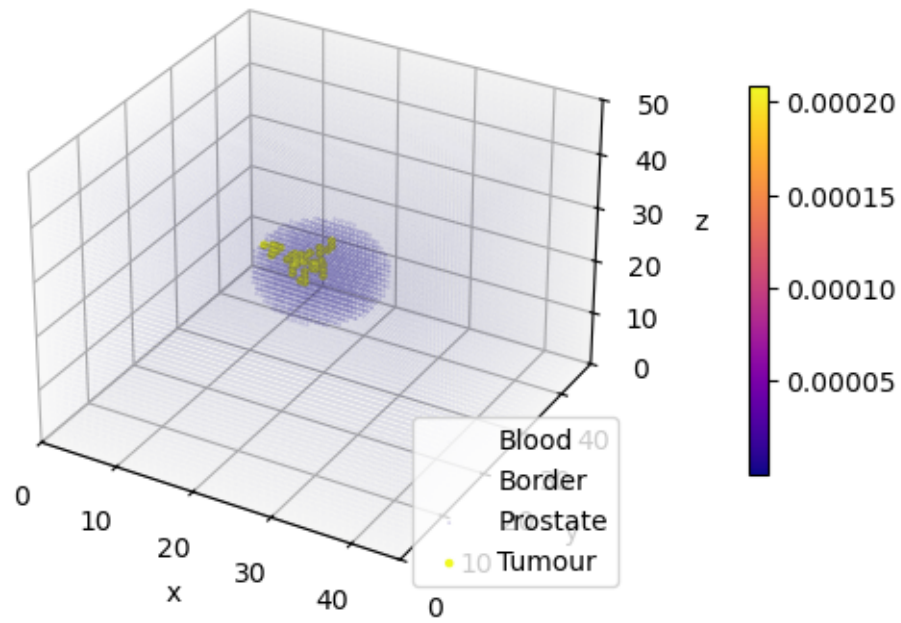
Time 13

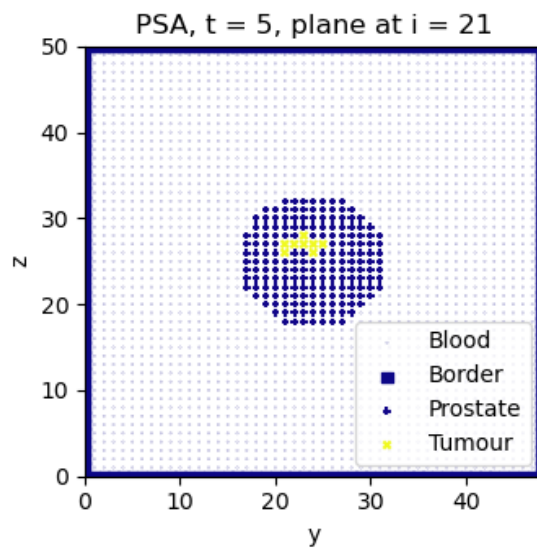
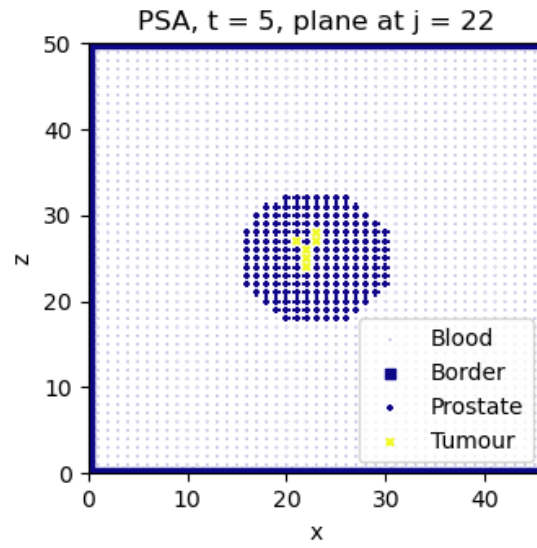
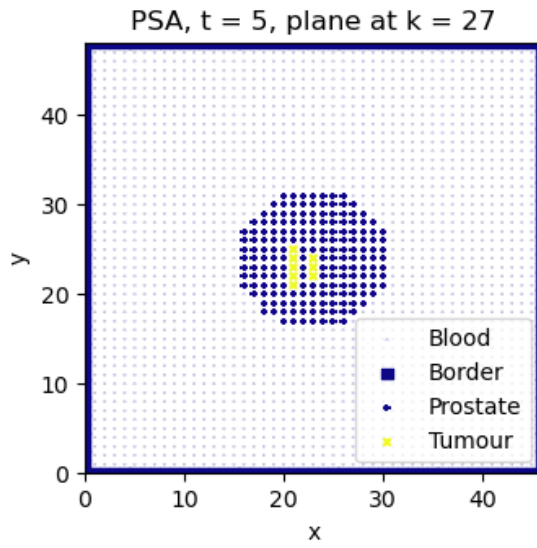
Diffusion PSA_top, with tumour

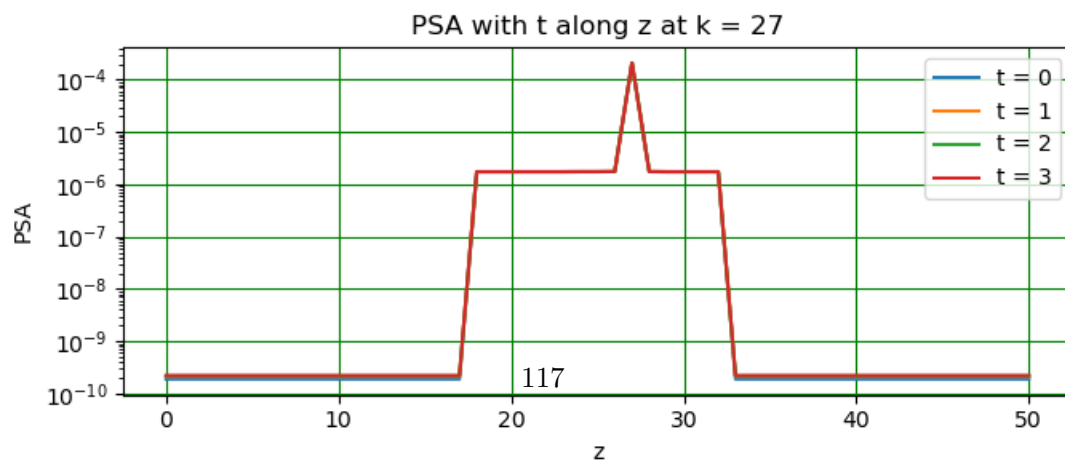
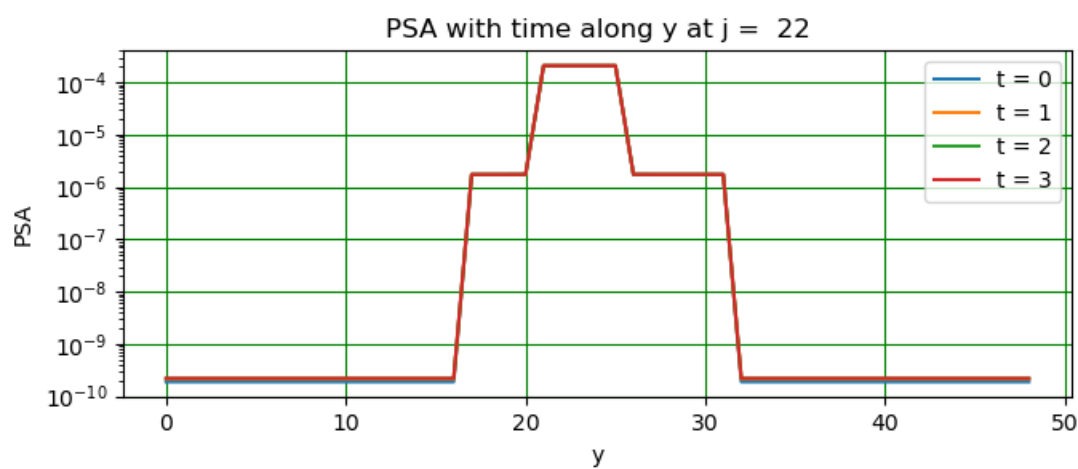
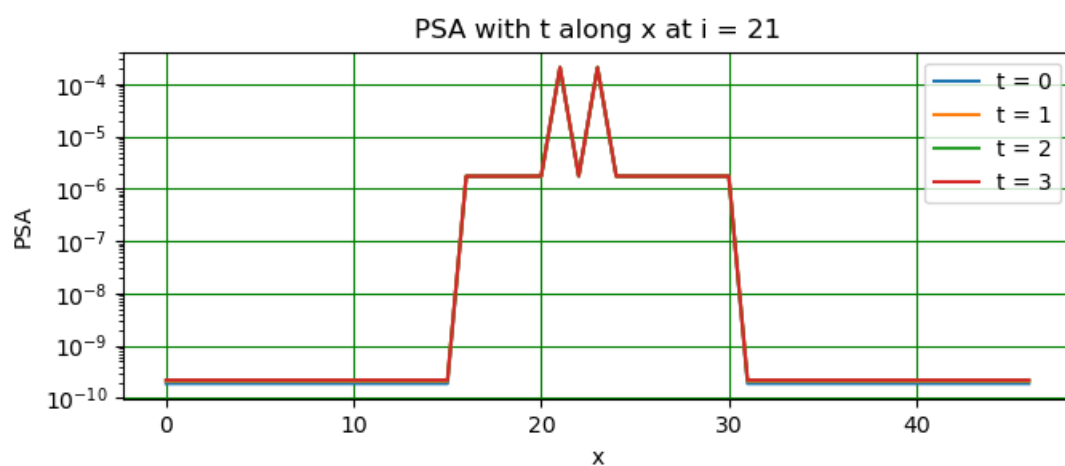
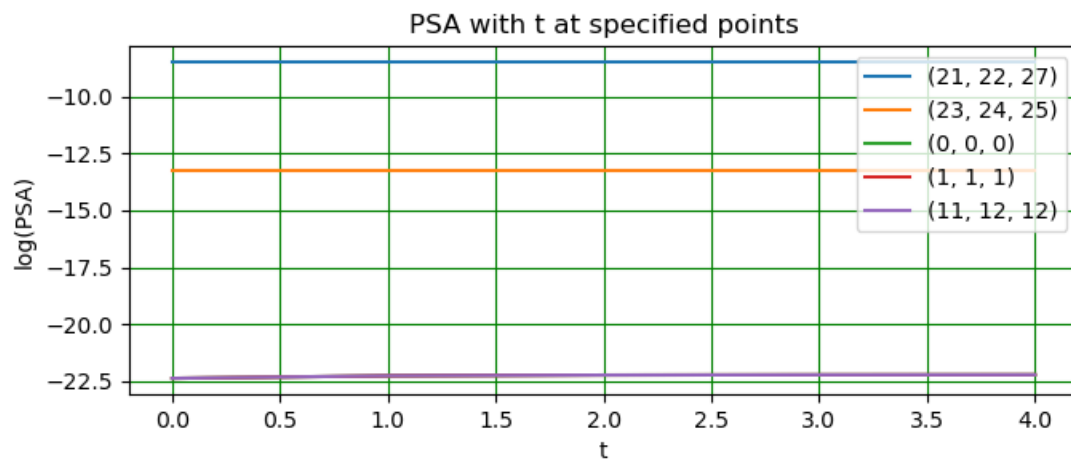
Diffusion converged, nt = 5, ext_test = 3.399391e-04, prostate_test =

6.207370e-04

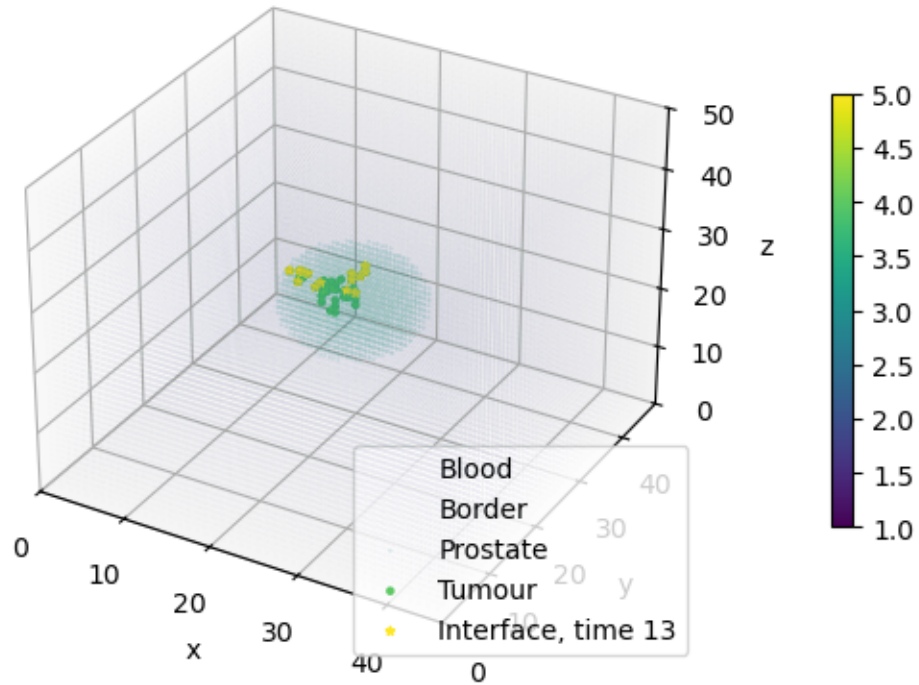
PSA, $t = 5$, xyz







Interface, time 13, xyz



At time 13:

No. tumour cells 42, prostate cells 2102, blood cells 101491

PSA_top_level 2.215085e-10

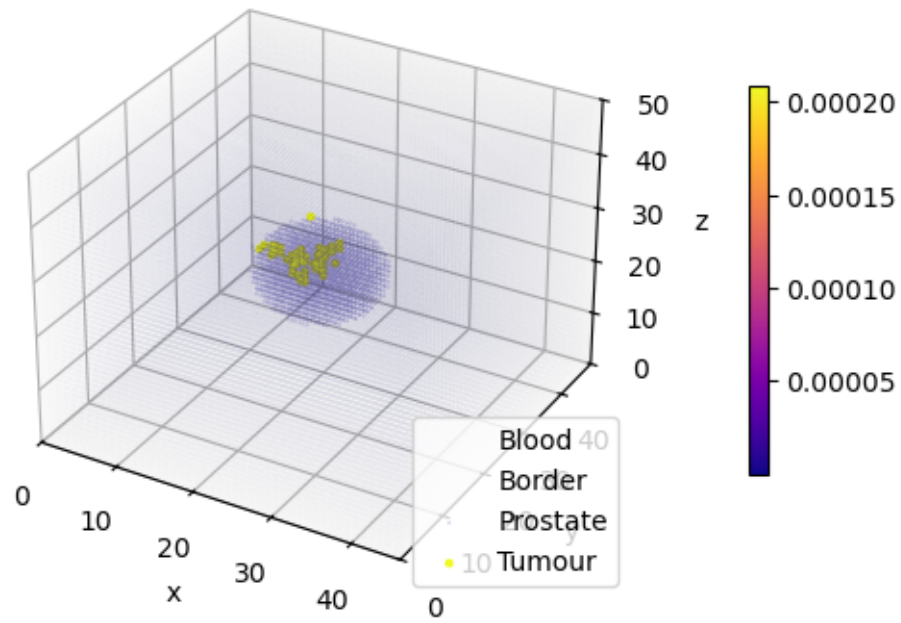
Time 14

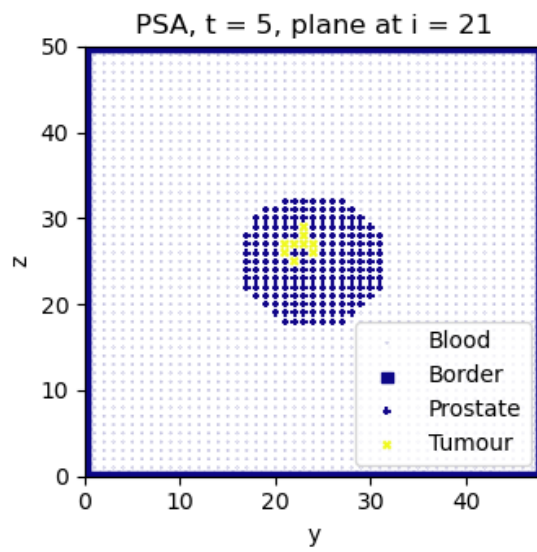
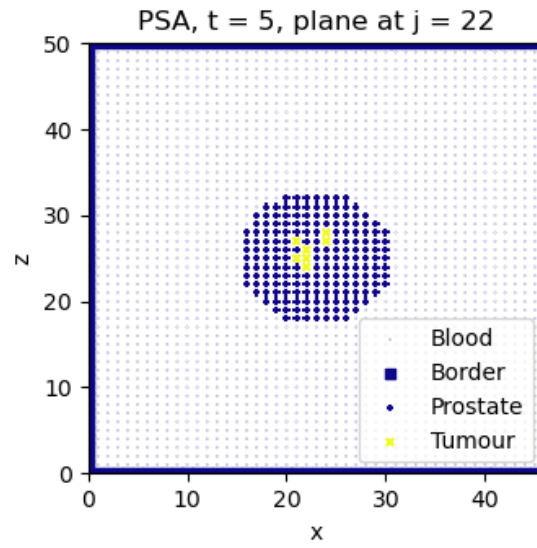
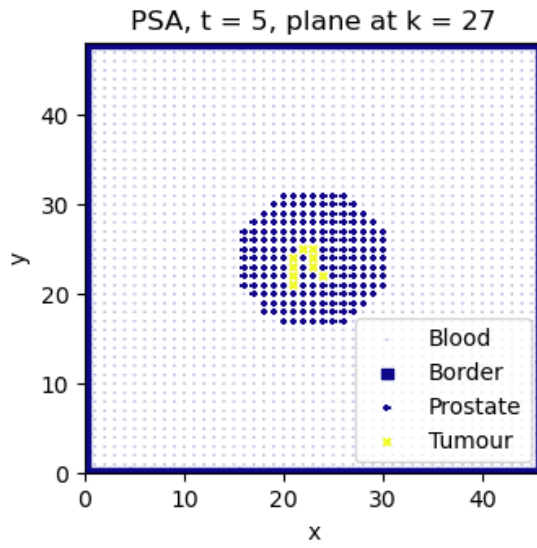
Diffusion PSA_top, with tumour

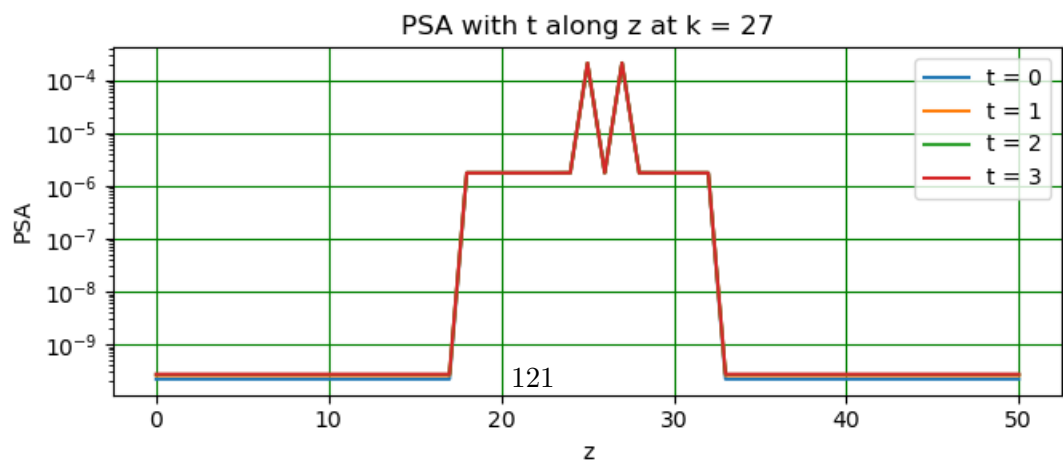
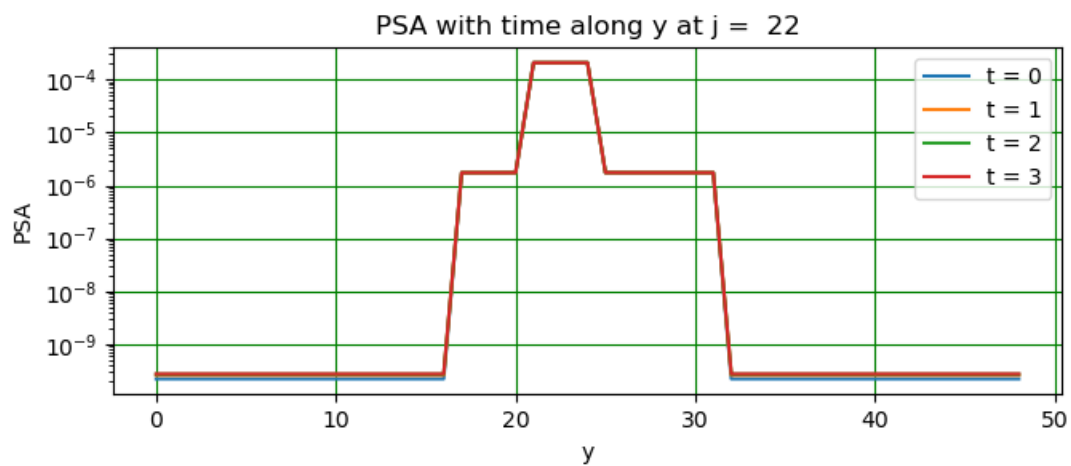
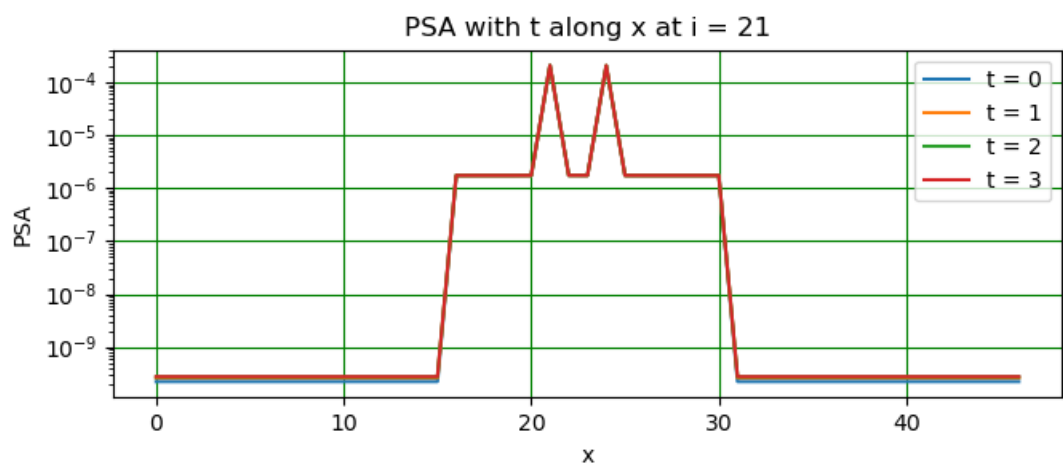
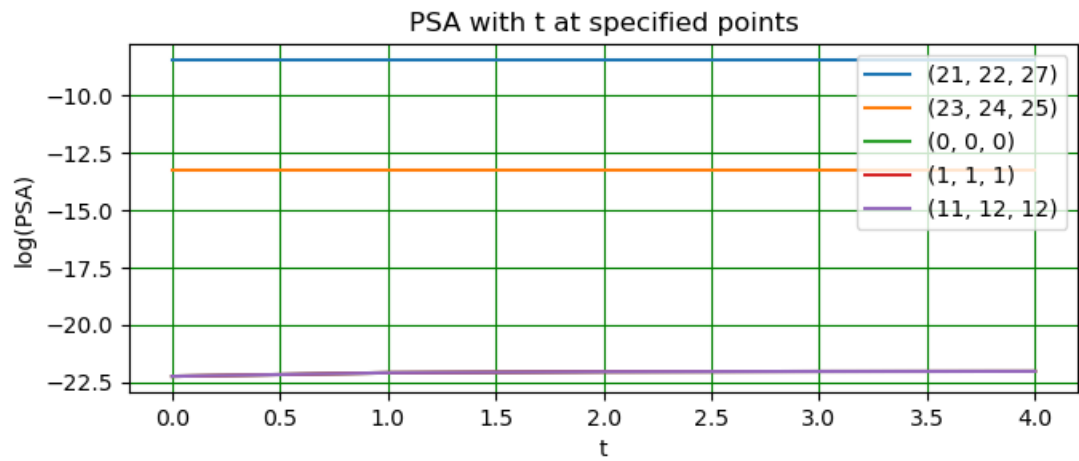
Diffusion converged, nt = 5, ext_test = 5.999320e-04, prostate_test =

4.917555e-04

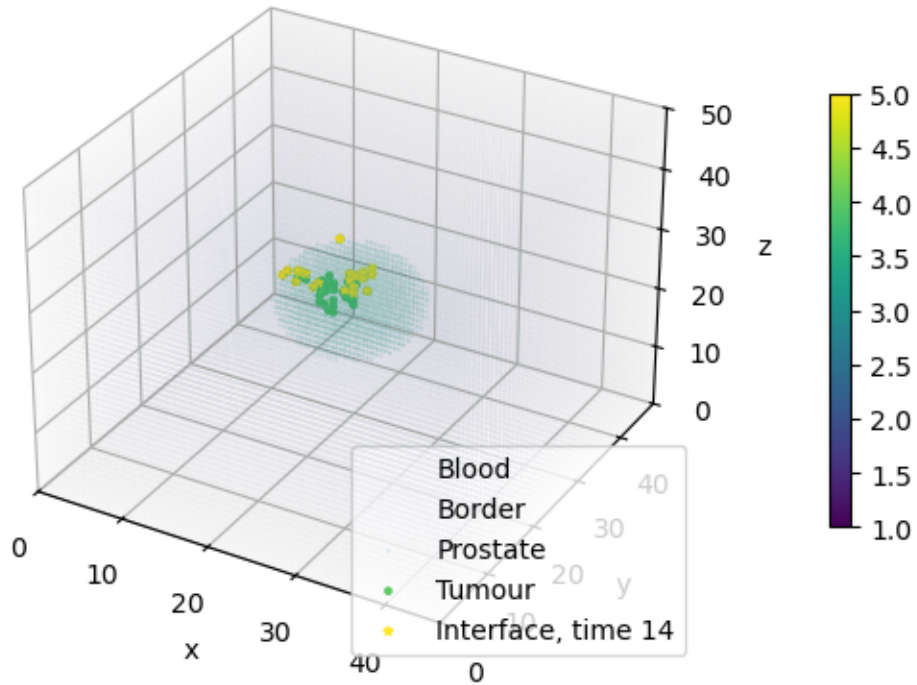
PSA, $t = 5$, xyz







Interface, time 14, xyz



At time 14:

No. tumour cells 53, prostate cells 2102, blood cells 101480

PSA_top_level 2.761012e-10

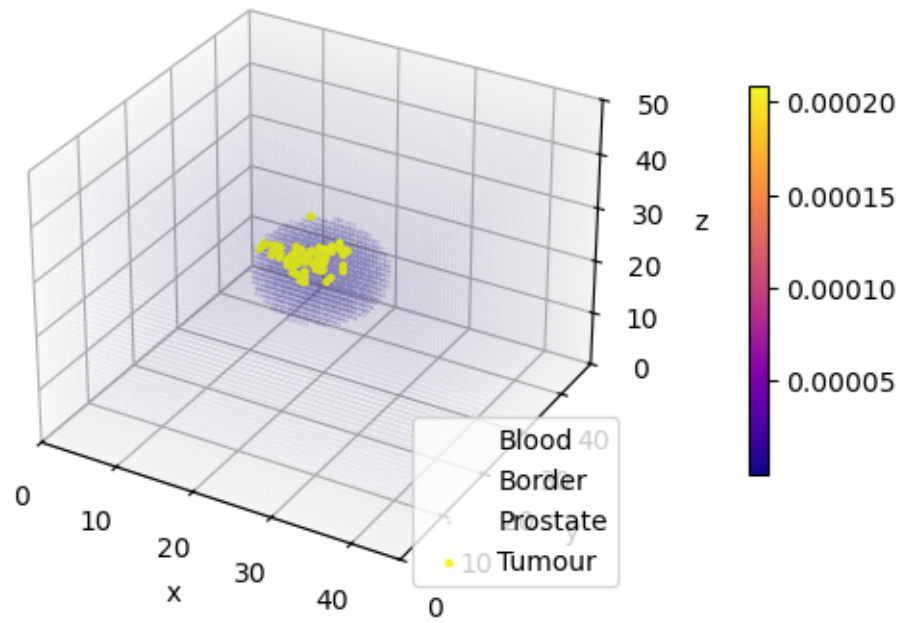
Time 15

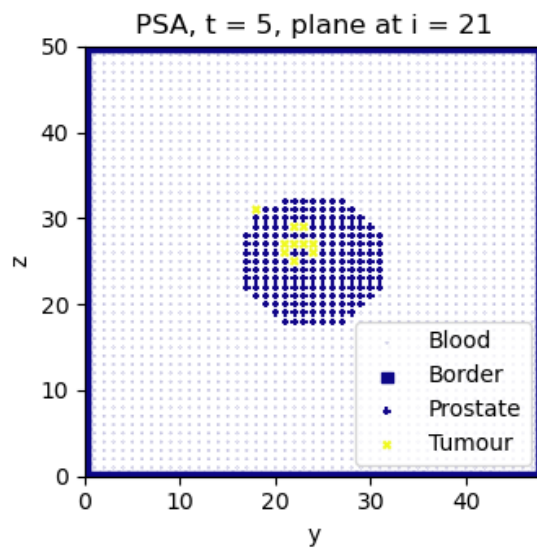
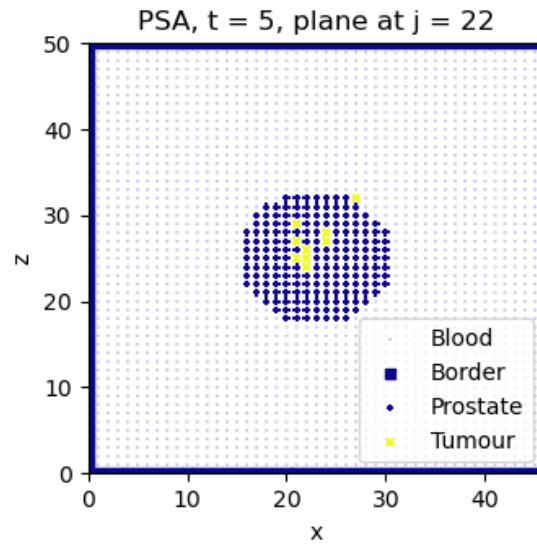
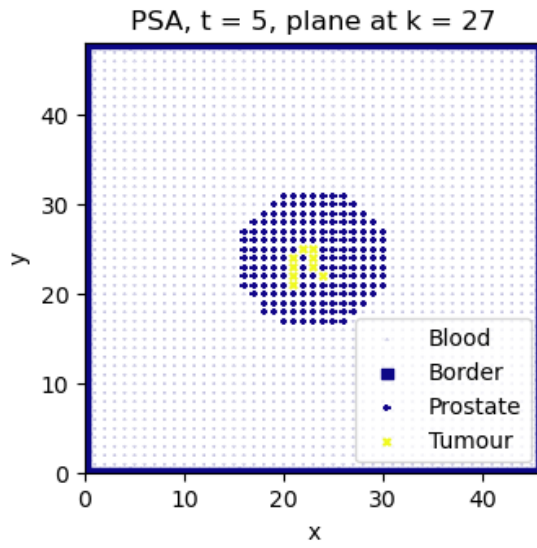
Diffusion PSA_top, with tumour

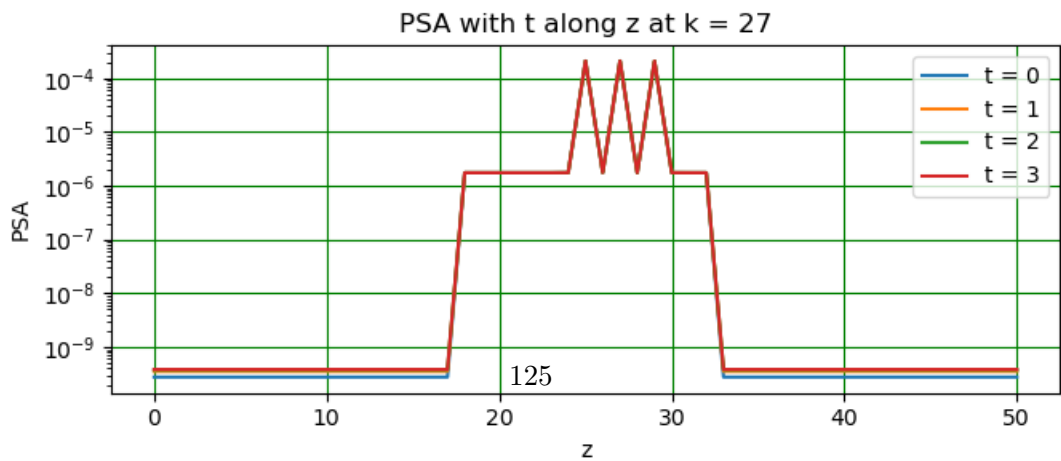
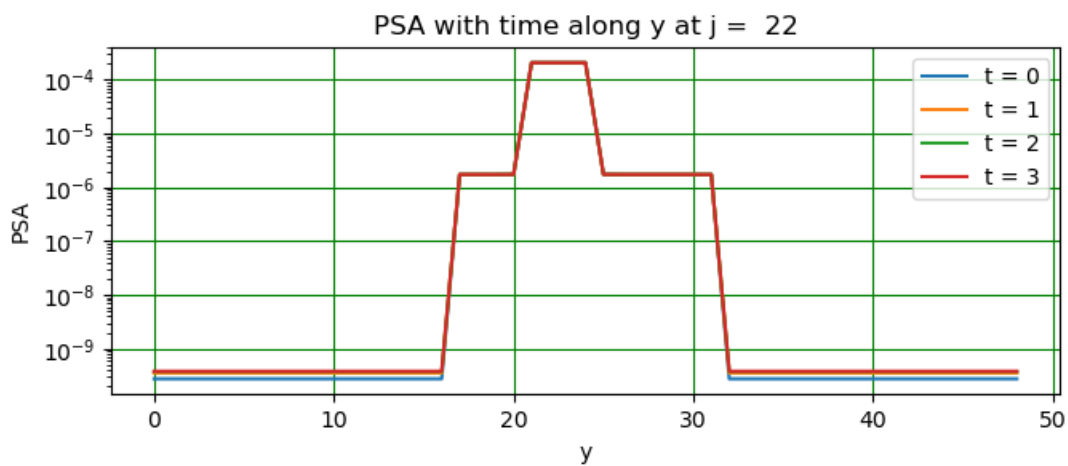
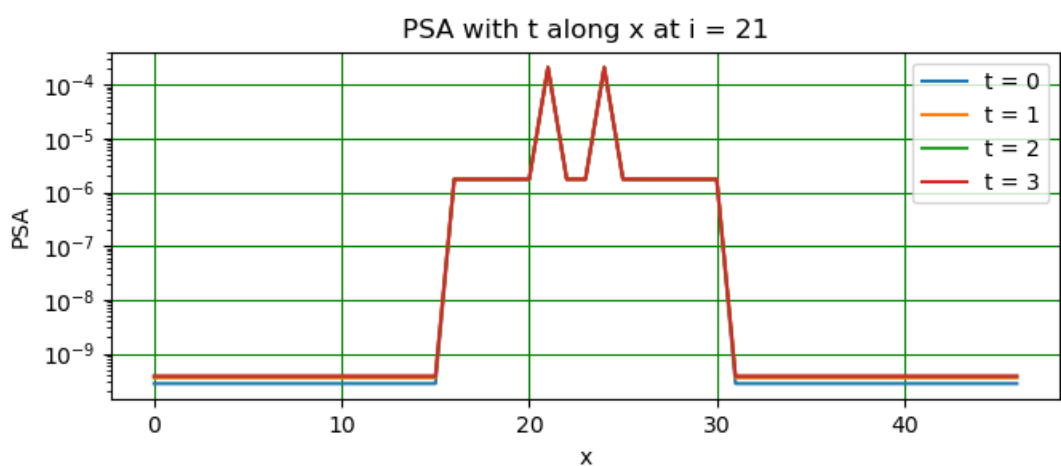
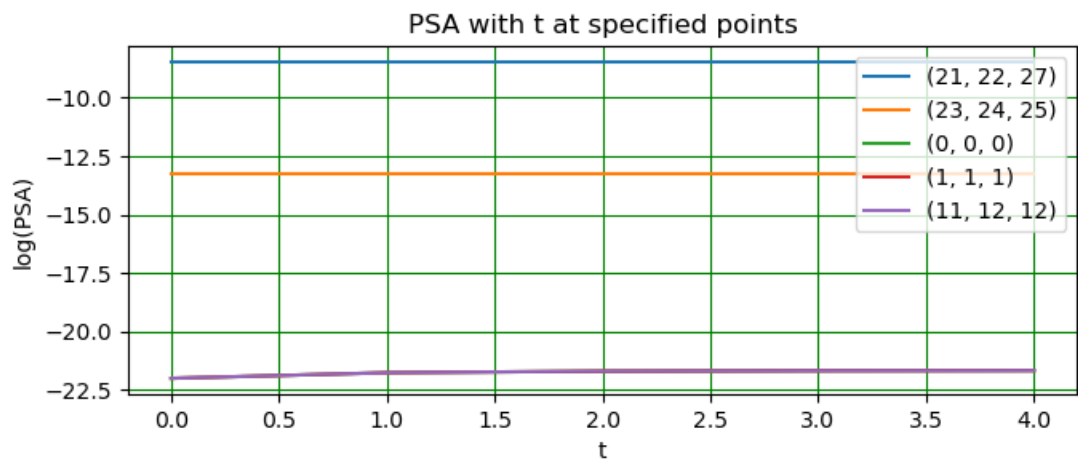
Diffusion converged, nt = 5, ext_test = 8.037903e-04, prostate_test =

3.916501e-04

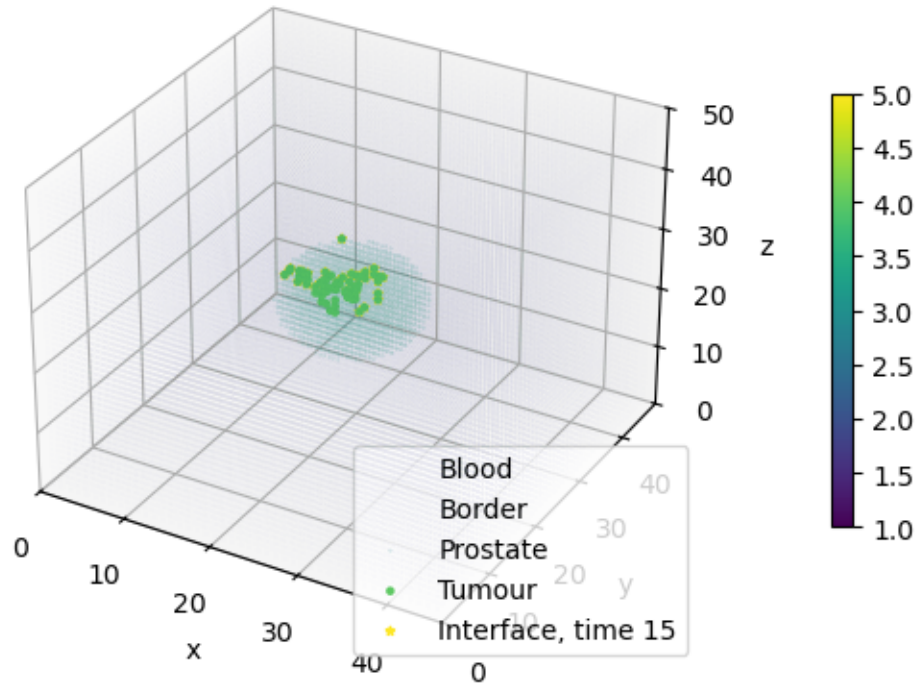
PSA, $t = 5$, xyz







Interface, time 15, xyz



At time 15:

No. tumour cells 66, prostate cells 2102, blood cells 101467

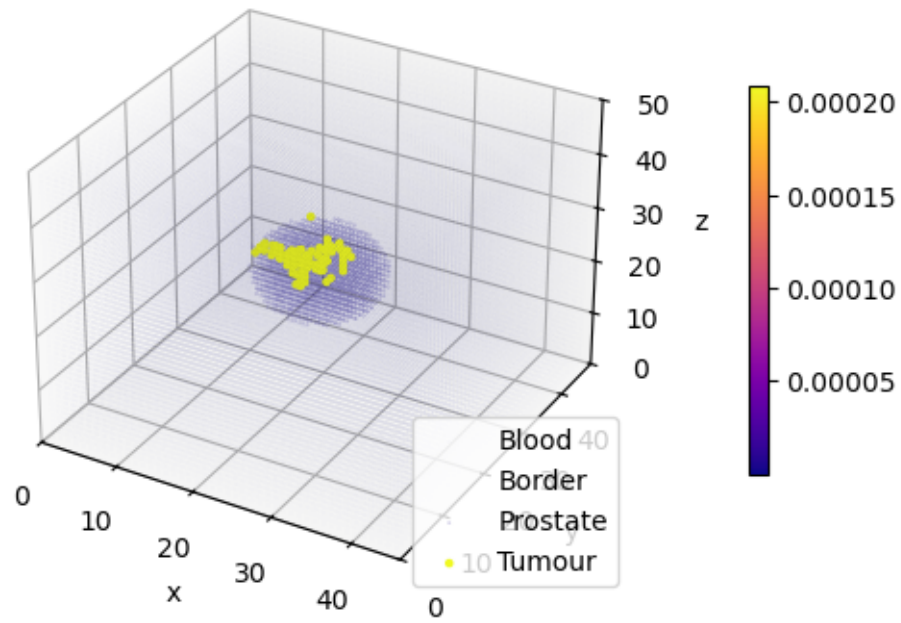
PSA_top_level 3.861554e-10

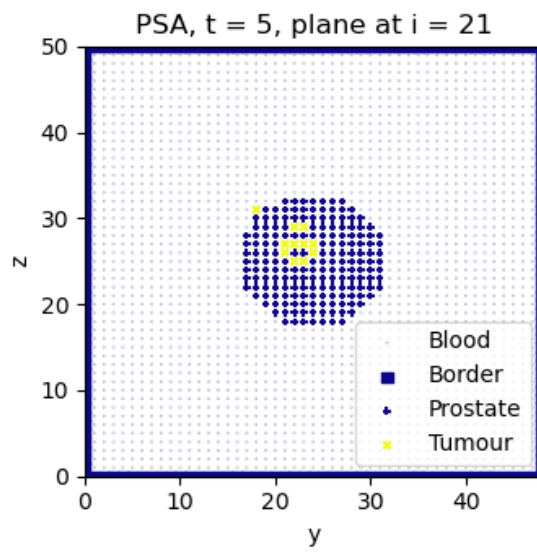
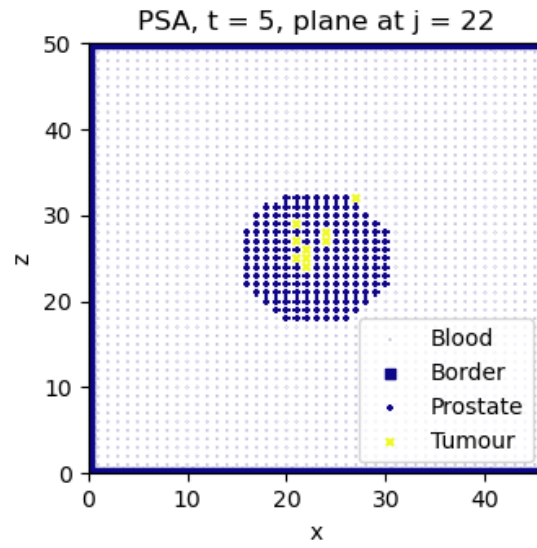
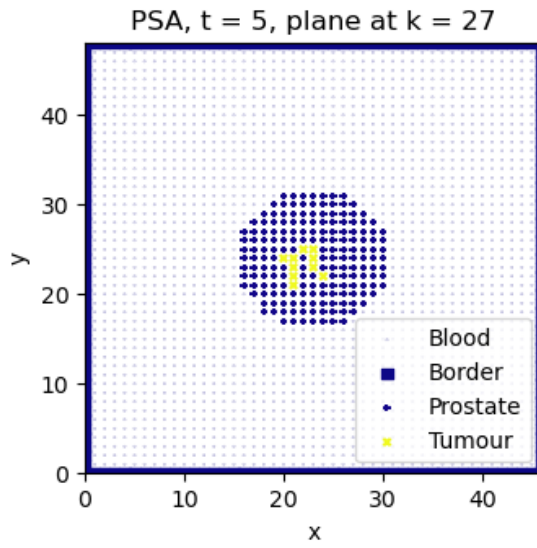
Time 16

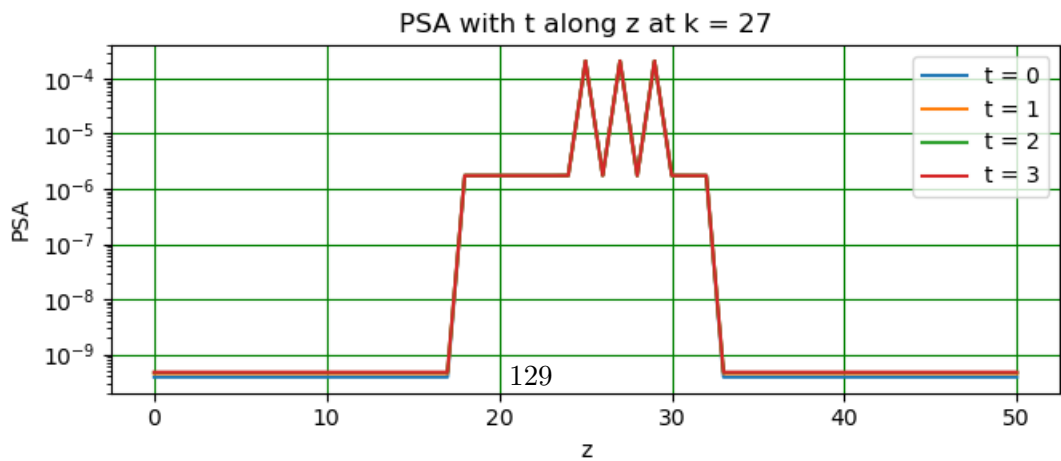
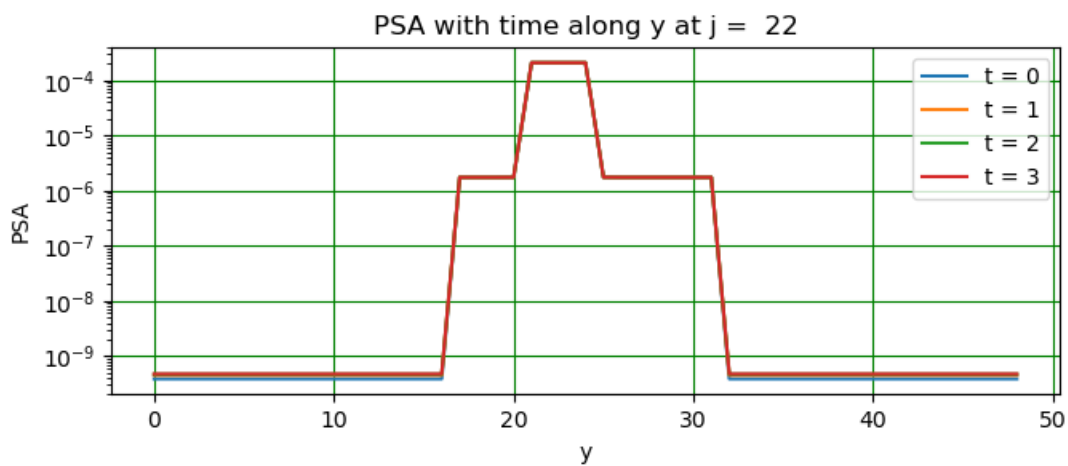
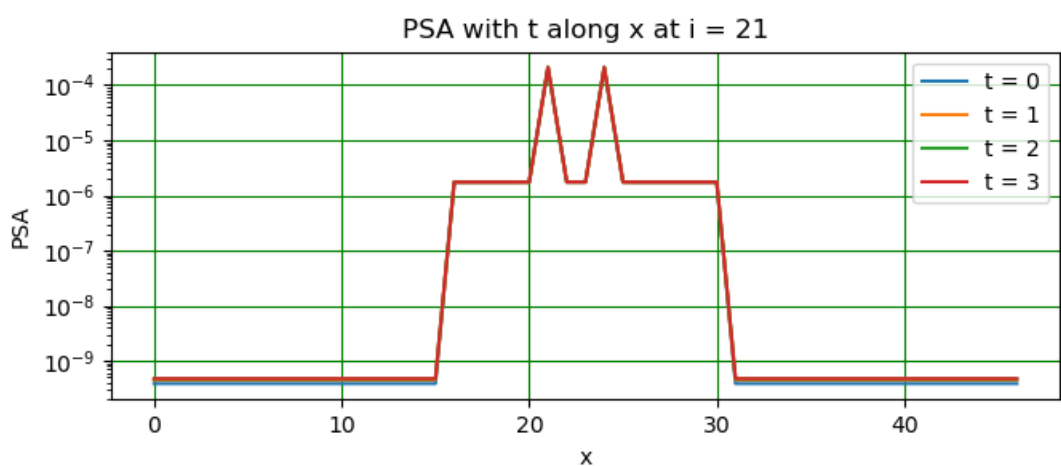
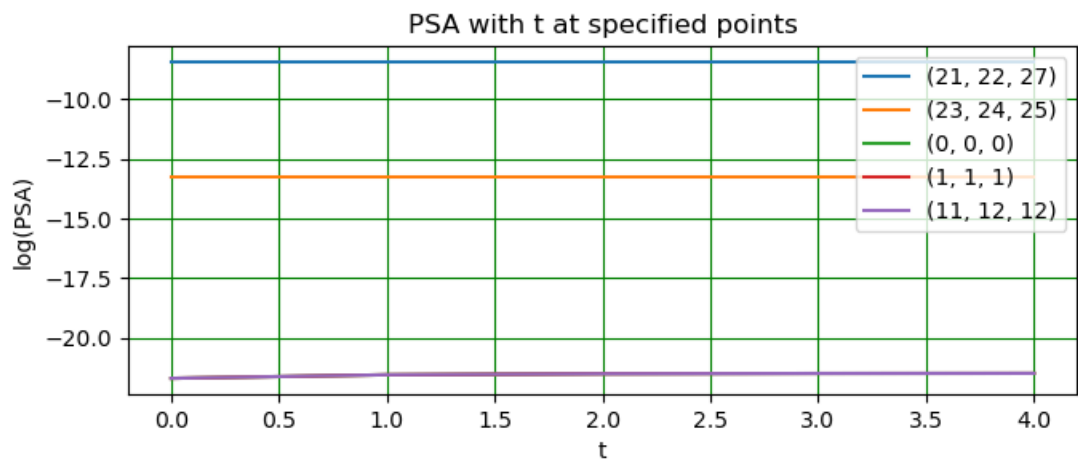
Diffusion PSA_top, with tumour

Diffusion converged, nt = 5, ext_test = 5.718902e-04, prostate_test = 3.153793e-04

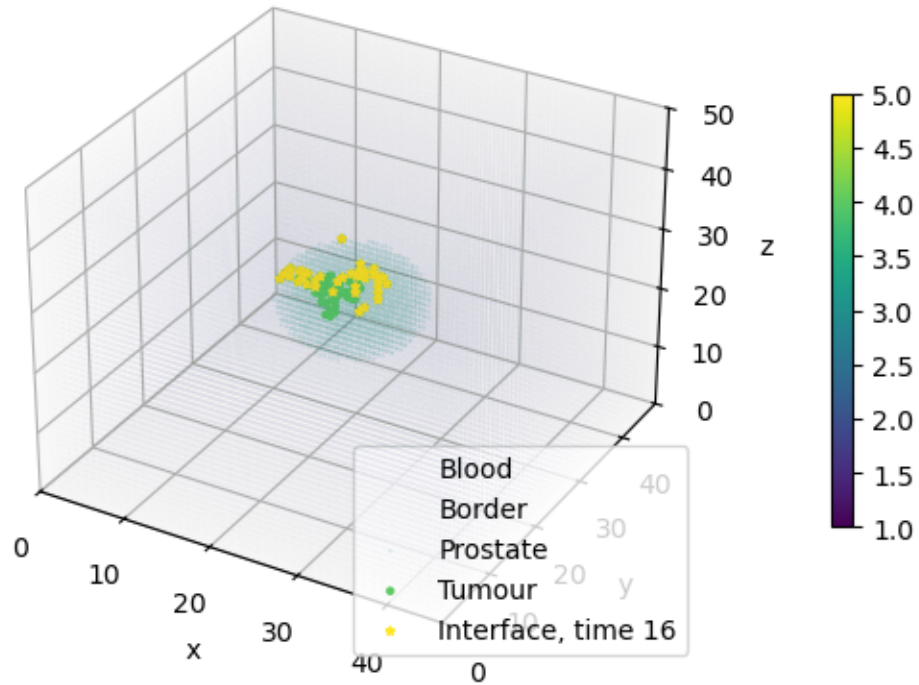
PSA, $t = 5$, xyz







Interface, time 16, xyz



At time 16:

No. tumour cells 82, prostate cells 2102, blood cells 101451

PSA_top_level 4.765947e-10

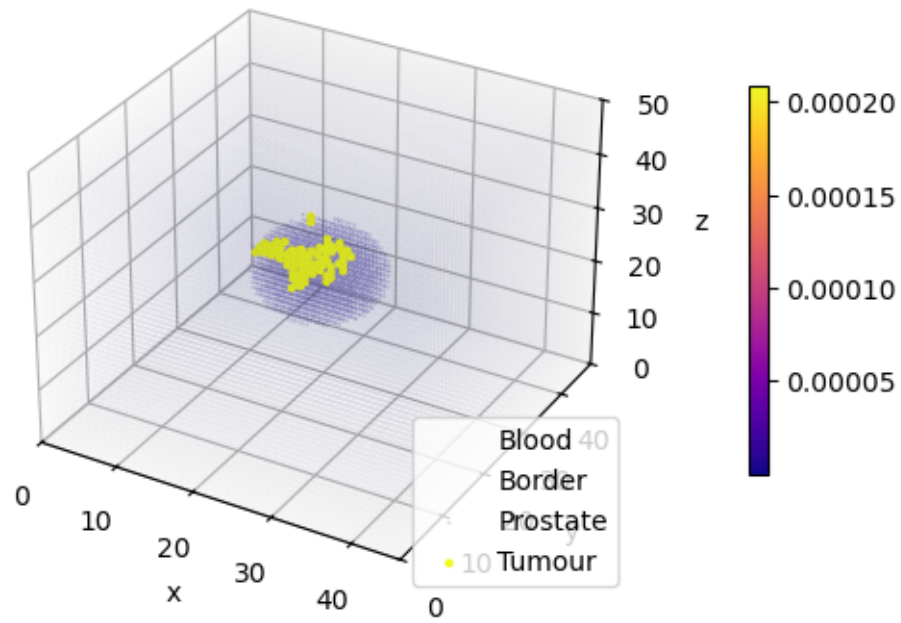
Time 17

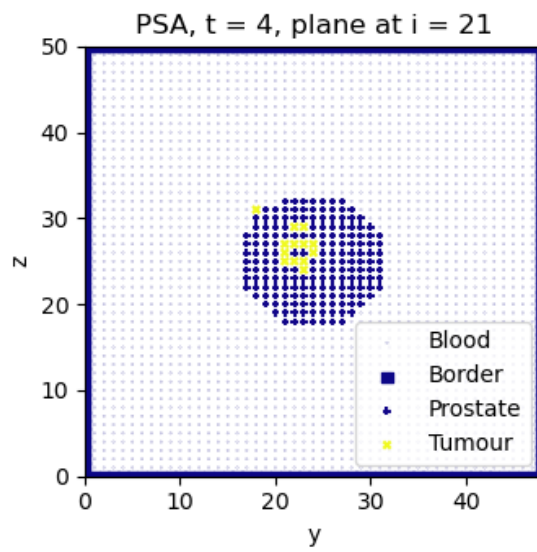
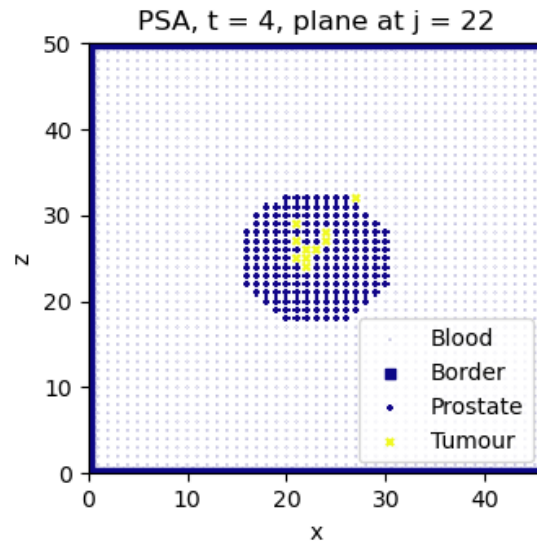
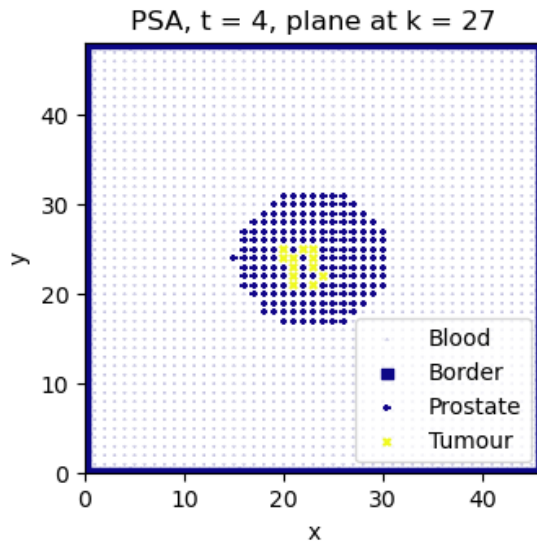
Diffusion PSA_top, with tumour

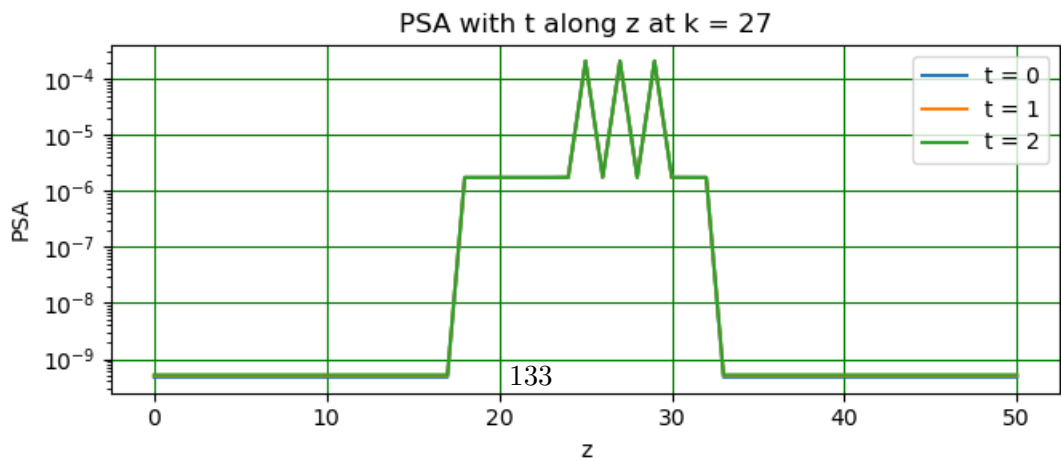
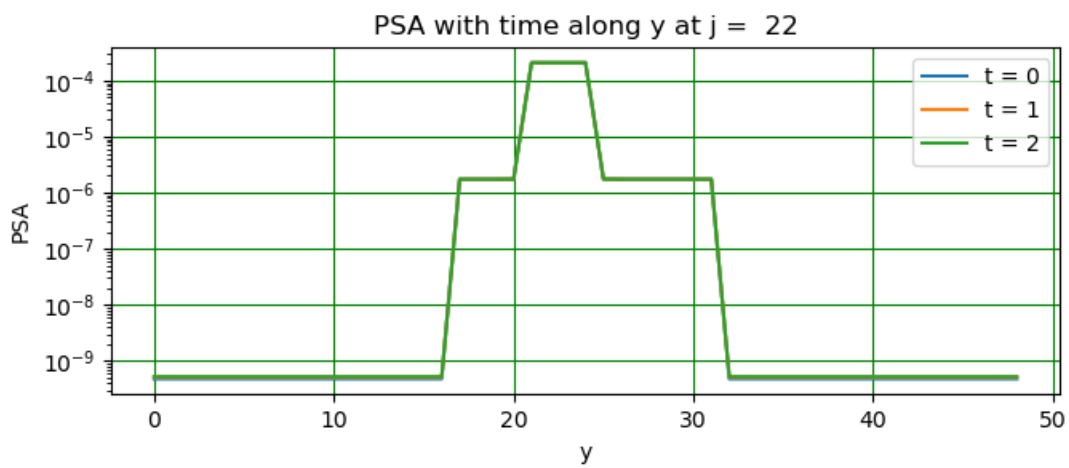
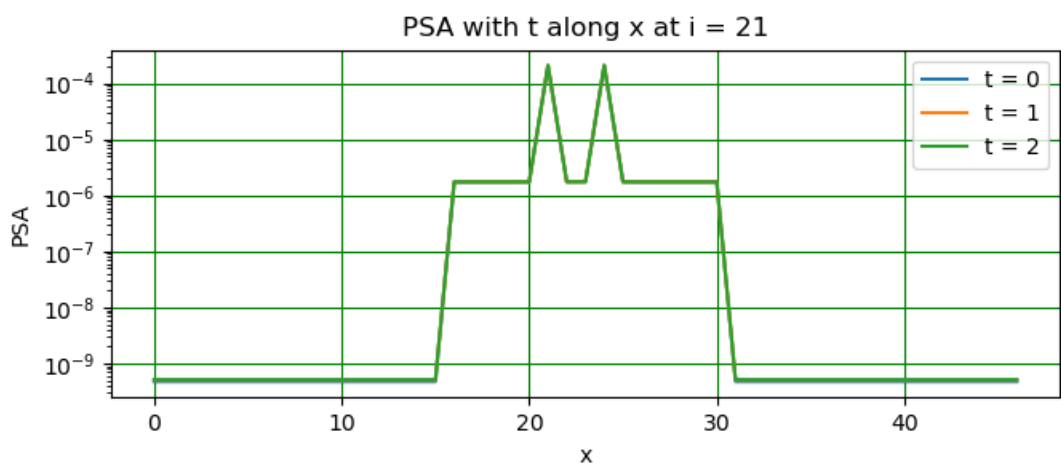
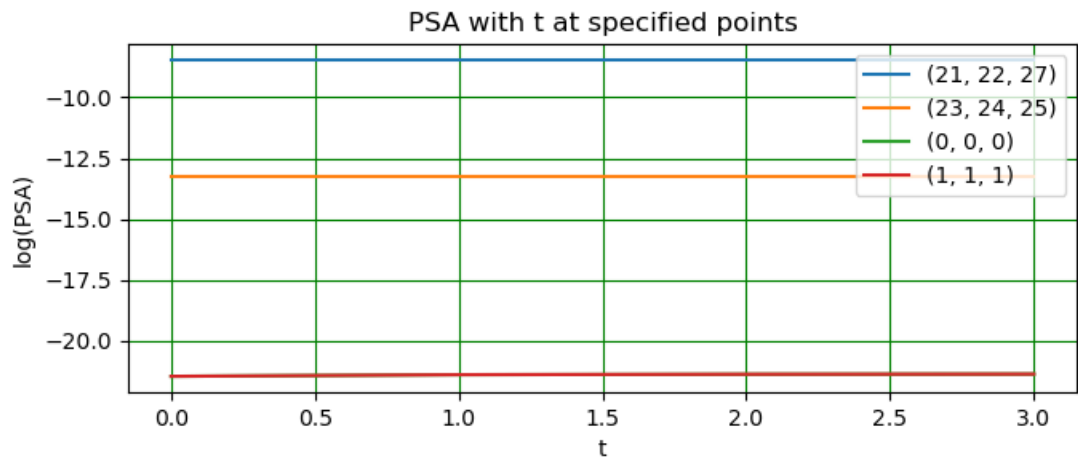
Diffusion converged, nt = 4, ext_test = 7.495524e-04, prostate_test =

4.720078e-04

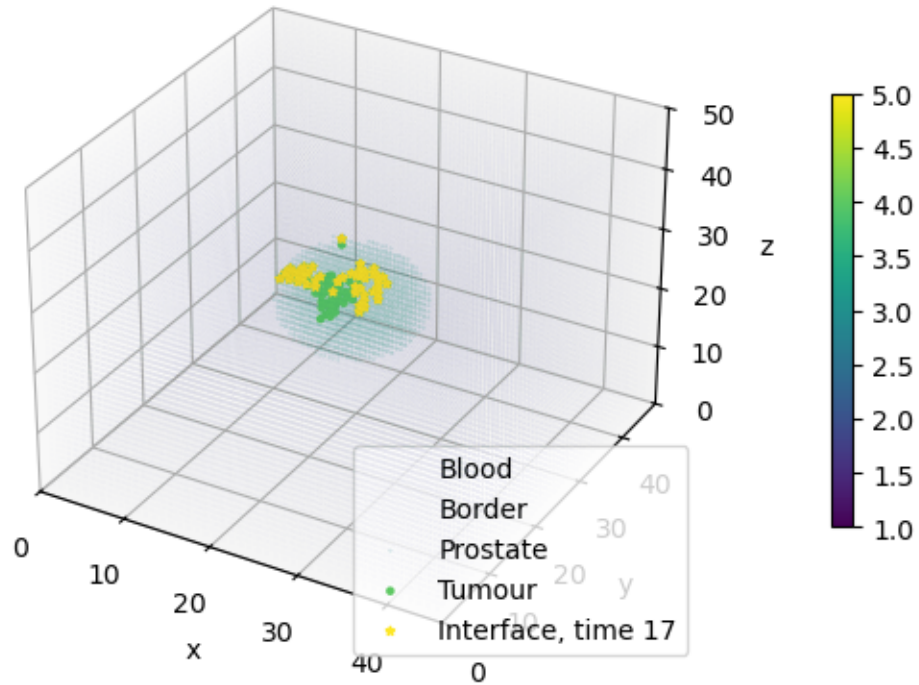
PSA, $t = 4$, xyz







Interface, time 17, xyz



At time 17:

No. tumour cells 102, prostate cells 2102, blood cells 101431

PSA_top_level 5.248792e-10

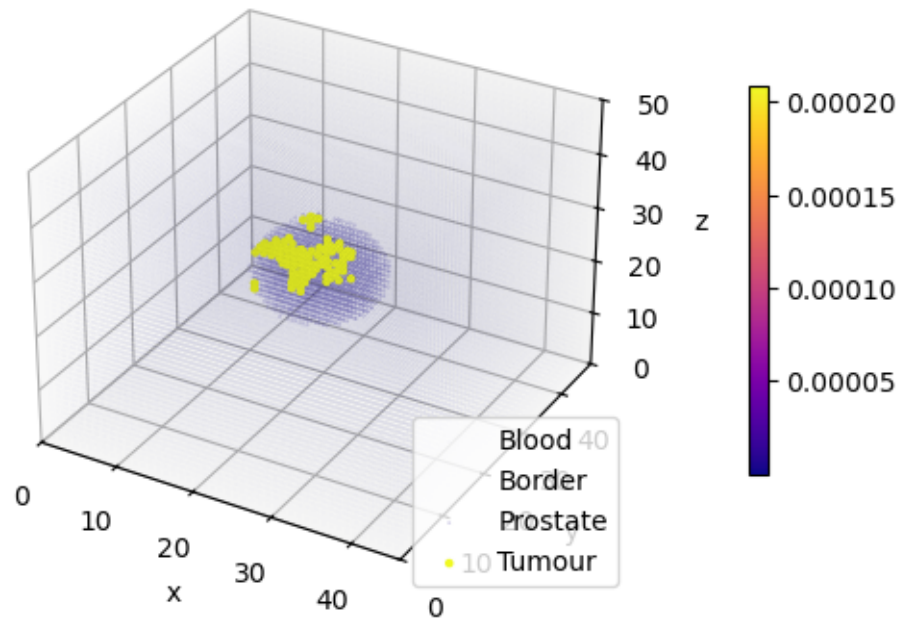
Time 18

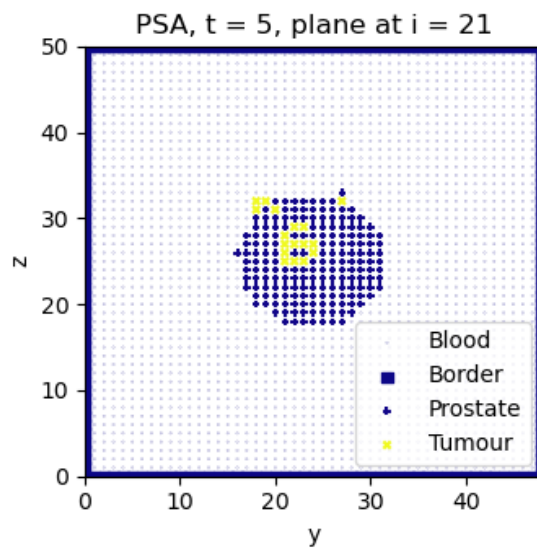
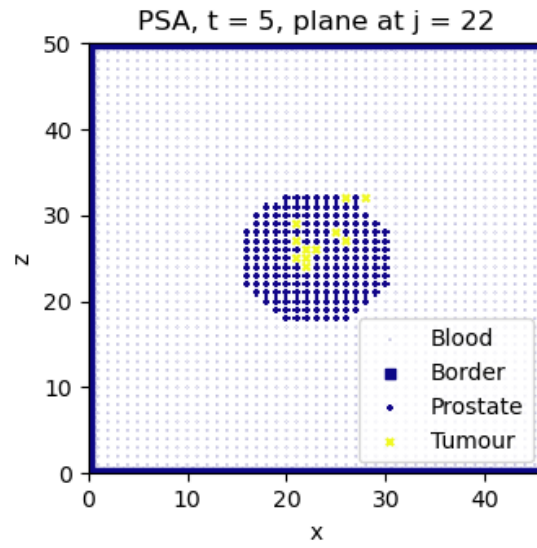
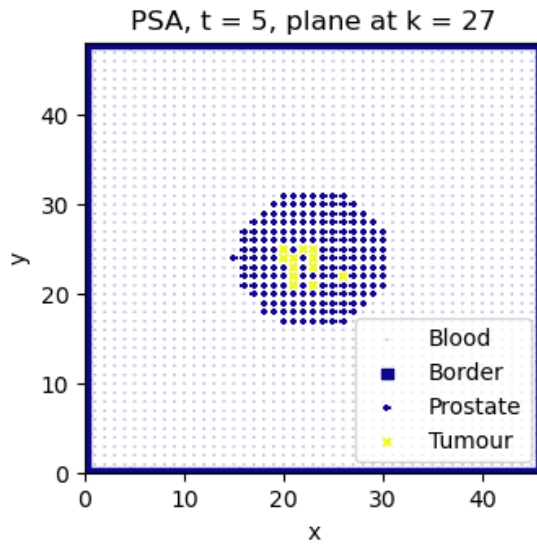
Diffusion PSA_top, with tumour

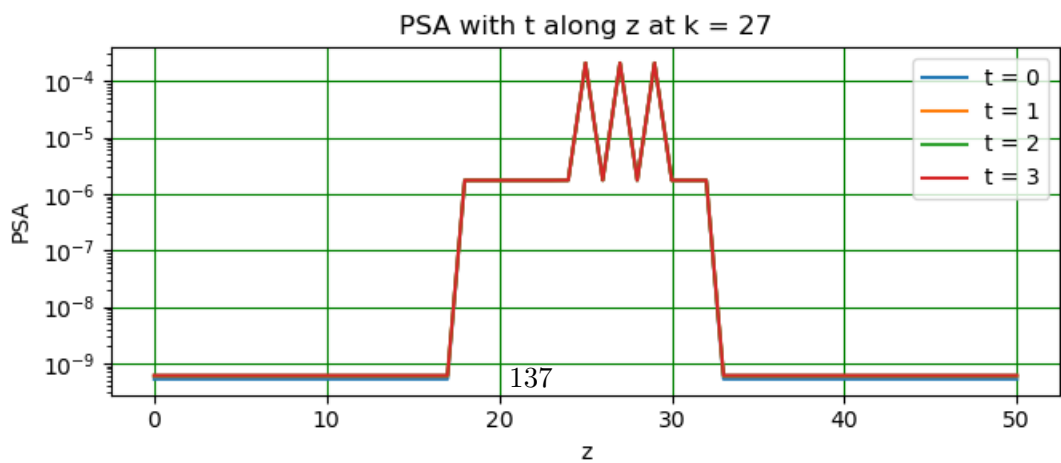
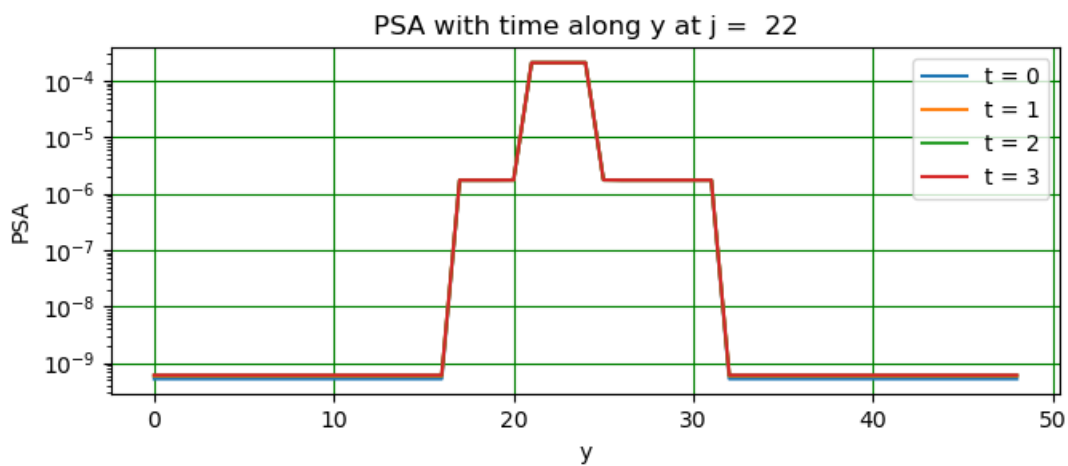
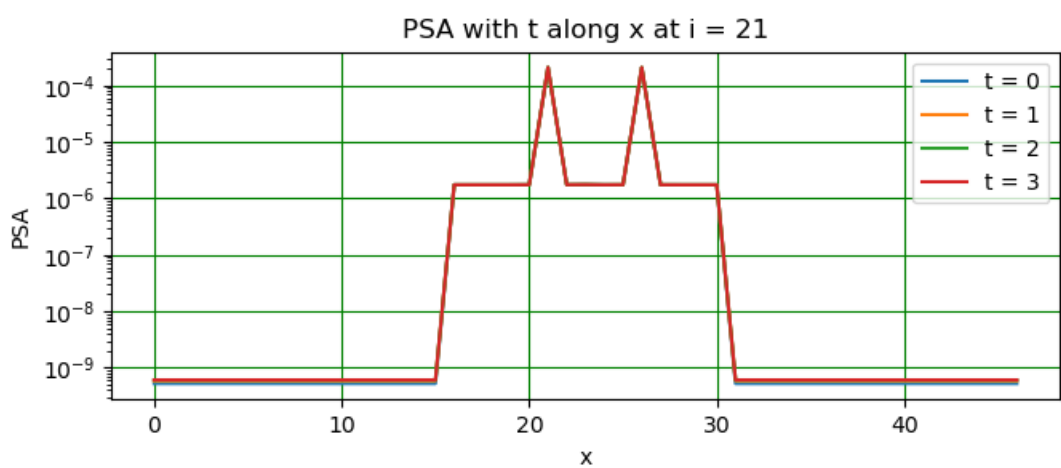
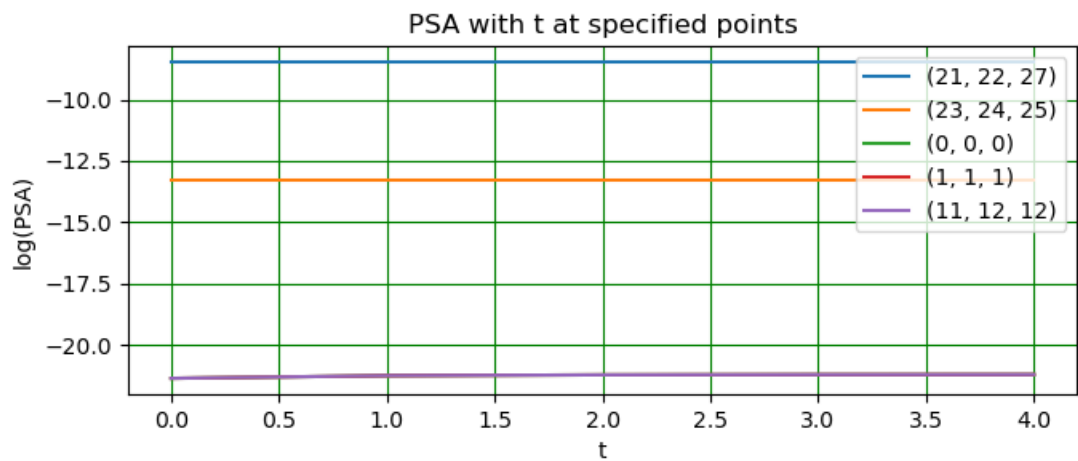
Diffusion converged, nt = 5, ext_test = 3.819538e-04, prostate_test =

2.066113e-04

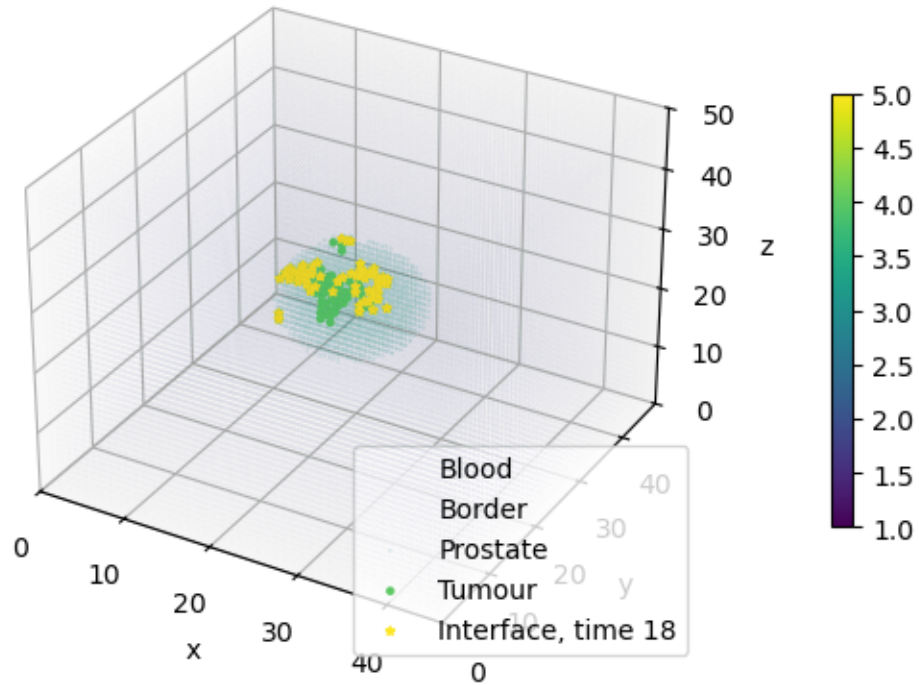
PSA, $t = 5$, xyz







Interface, time 18, xyz



At time 18:

No. tumour cells 126, prostate cells 2102, blood cells 101407

PSA_top_level 6.131118e-10

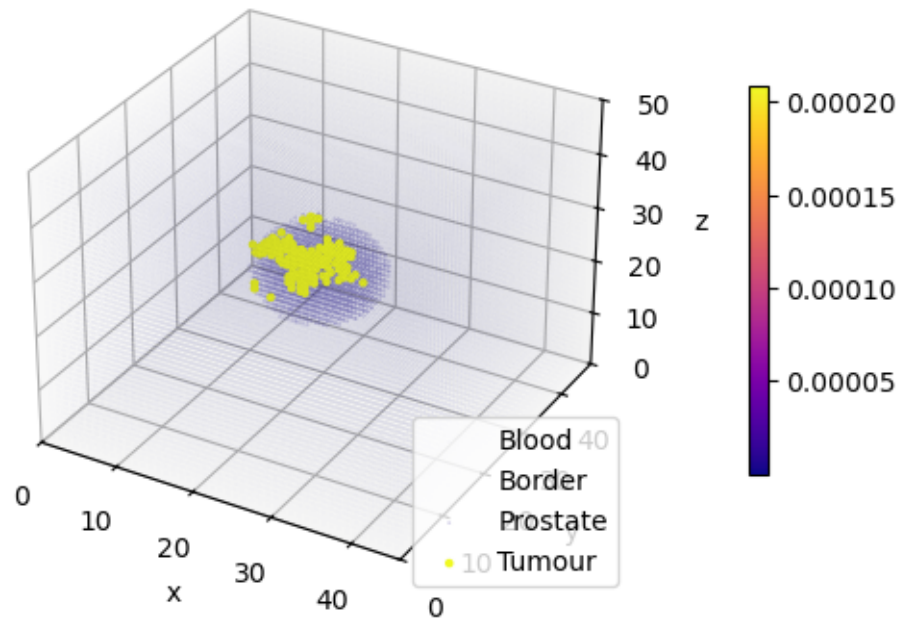
Time 19

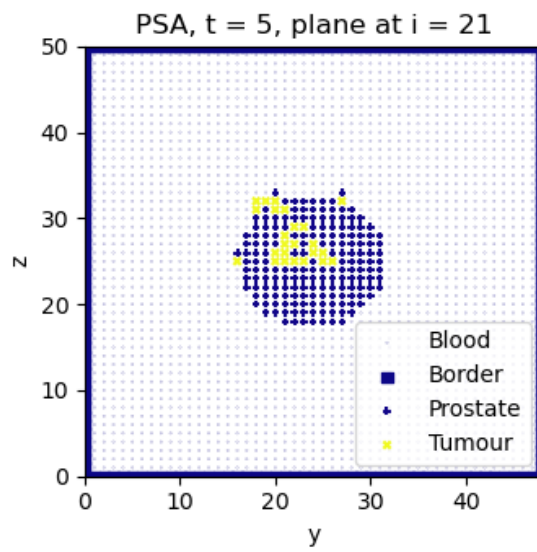
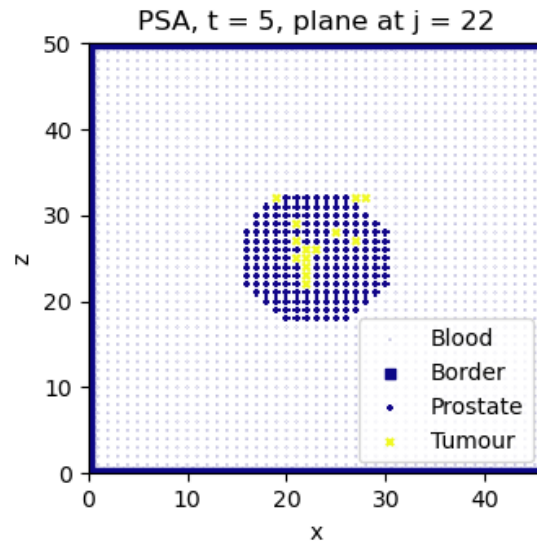
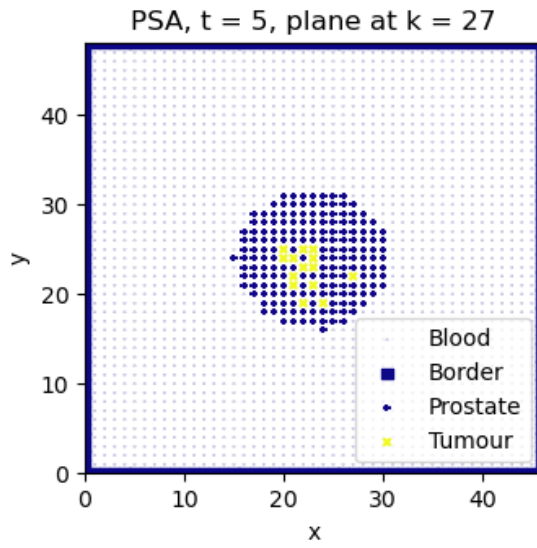
Diffusion PSA_top, with tumour

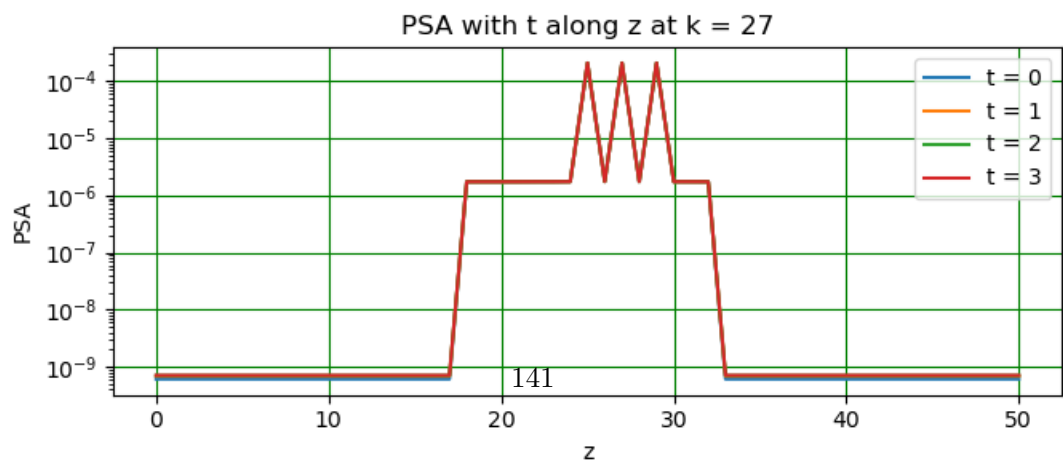
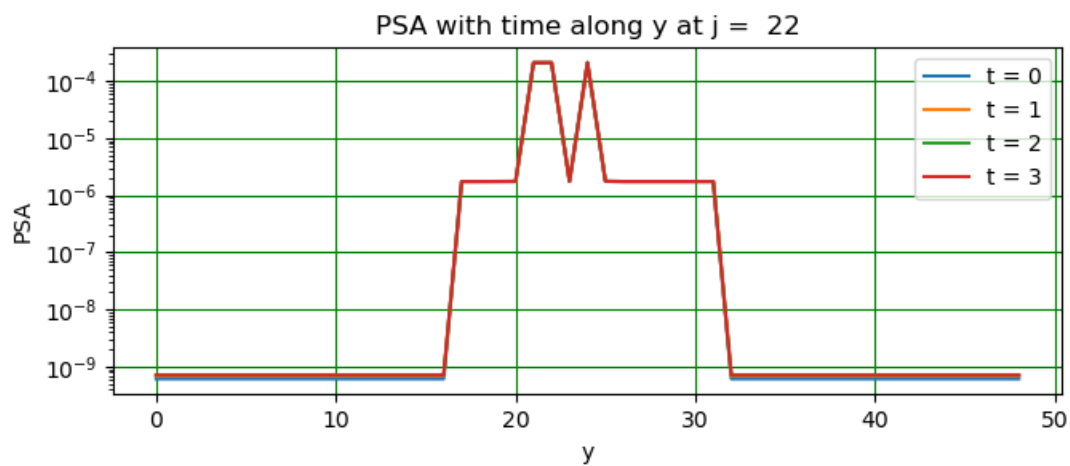
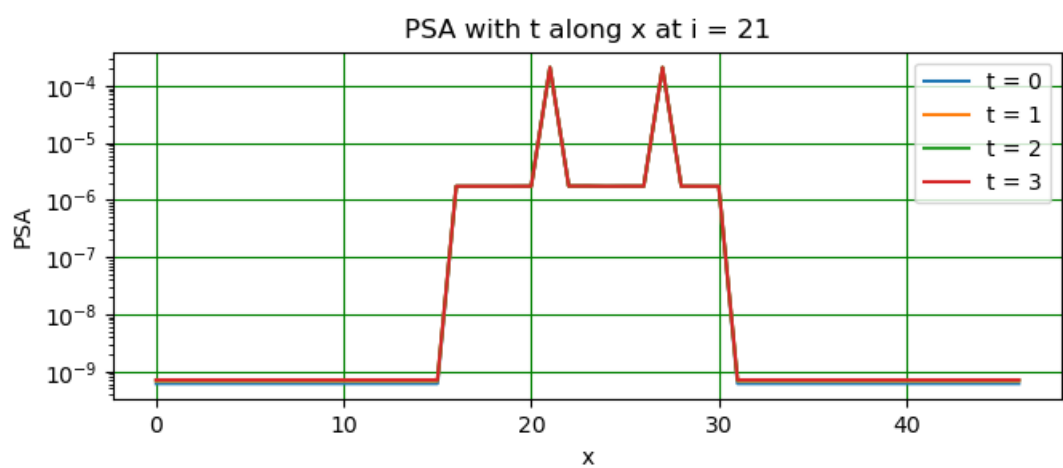
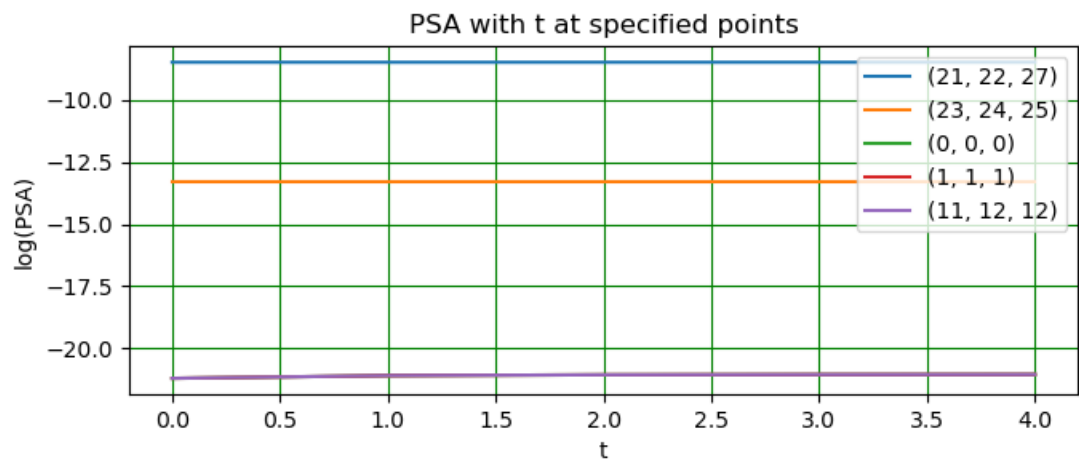
Diffusion converged, nt = 5, ext_test = 3.452989e-04, prostate_test =

2.149000e-04

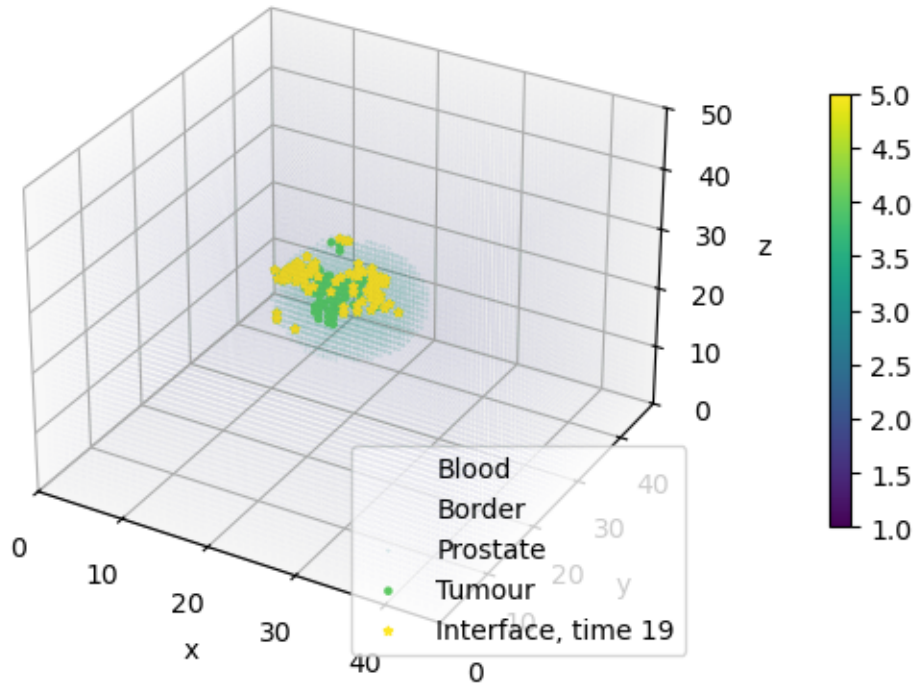
PSA, $t = 5$, xyz







Interface, time 19, xyz



At time 19:

No. tumour cells 155, prostate cells 2102, blood cells 101378

PSA_top_level 7.166570e-10

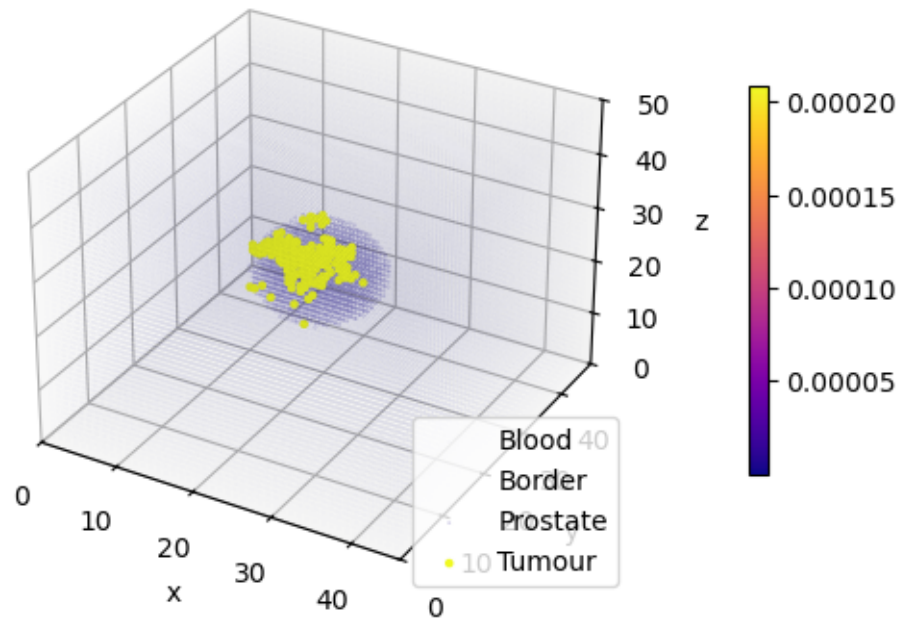
Time 20

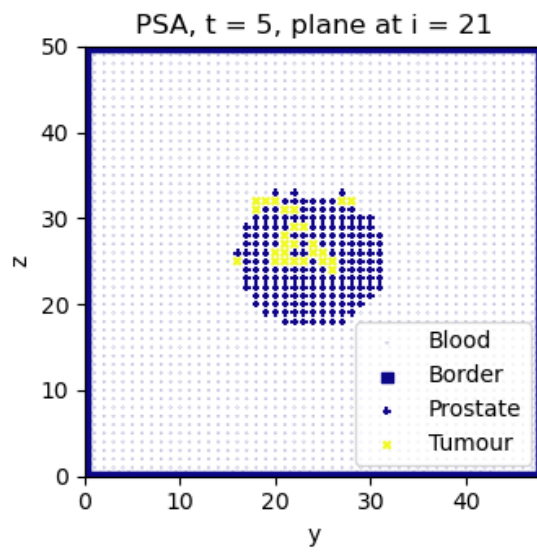
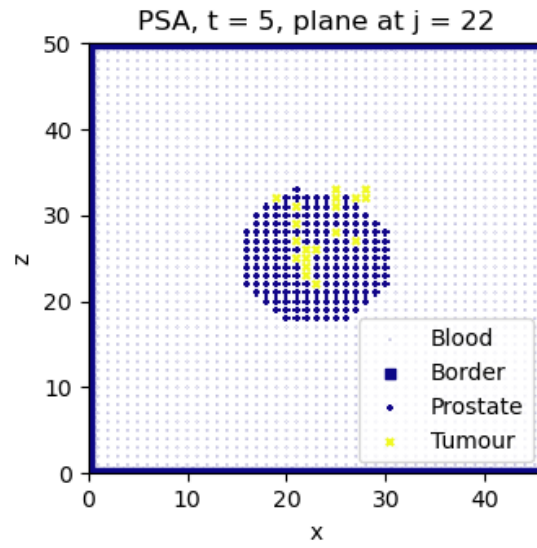
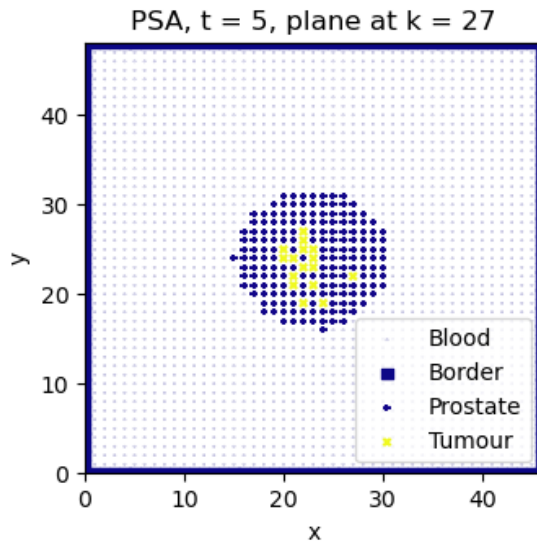
Diffusion PSA_top, with tumour

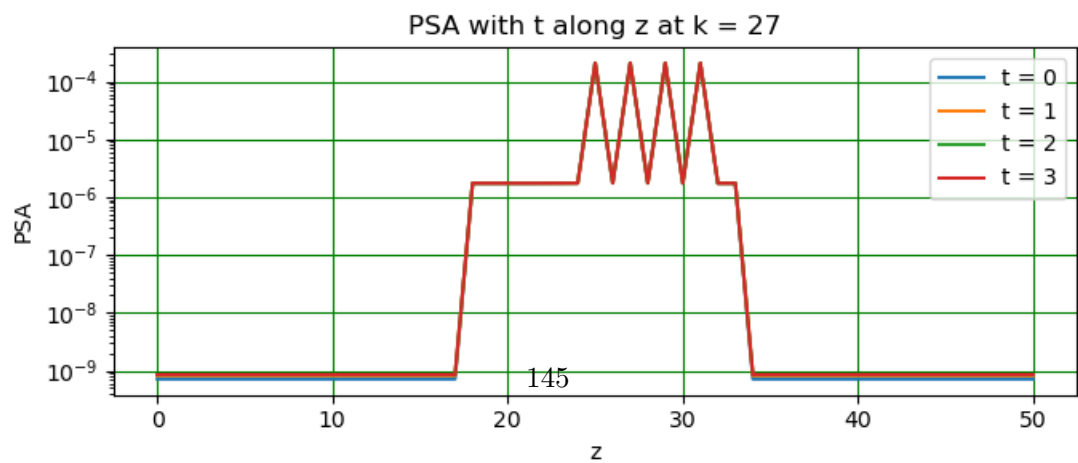
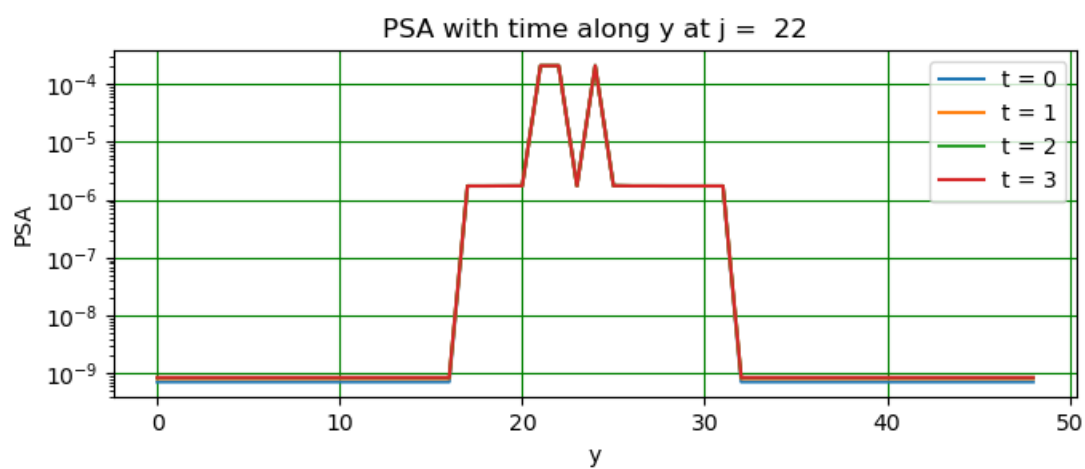
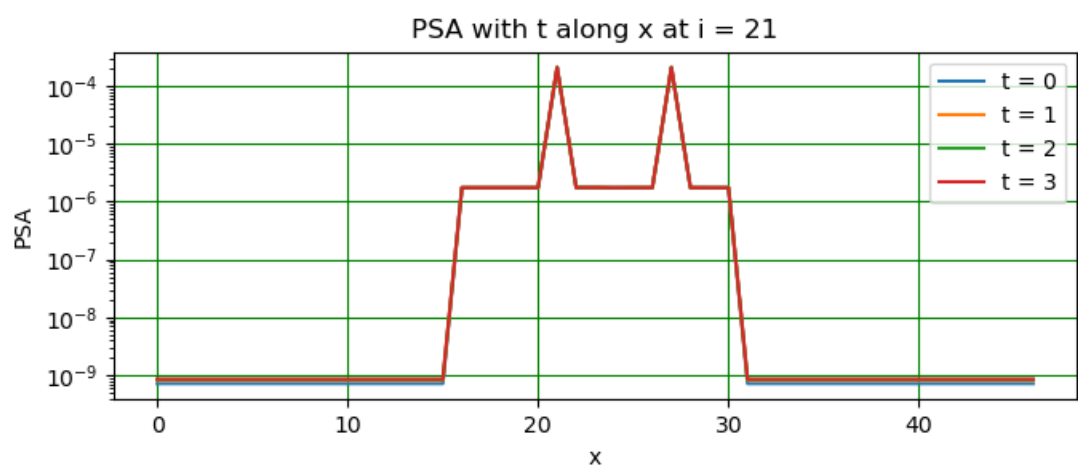
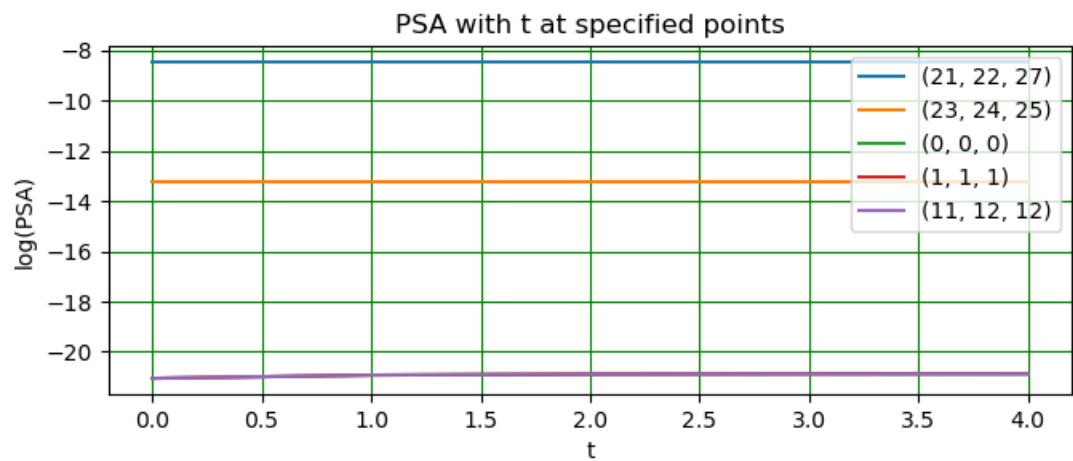
Diffusion converged, nt = 5, ext_test = 3.815732e-04, prostate_test =

2.123355e-04

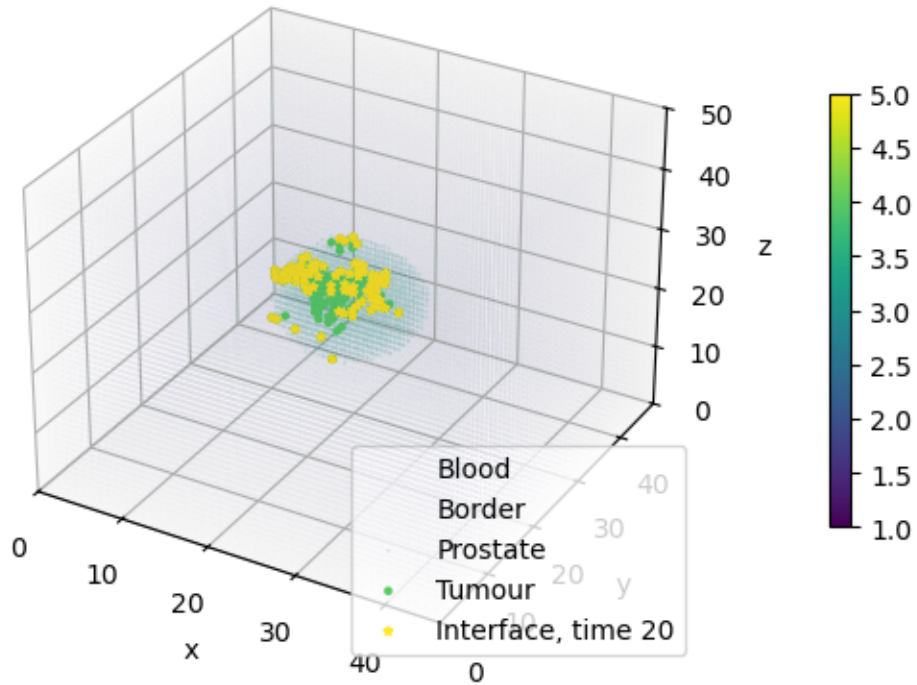
PSA, $t = 5$, xyz







Interface, time 20, xyz



At time 20:

No. tumour cells 191, prostate cells 2102, blood cells 101342

PSA_top_level 8.596791e-10

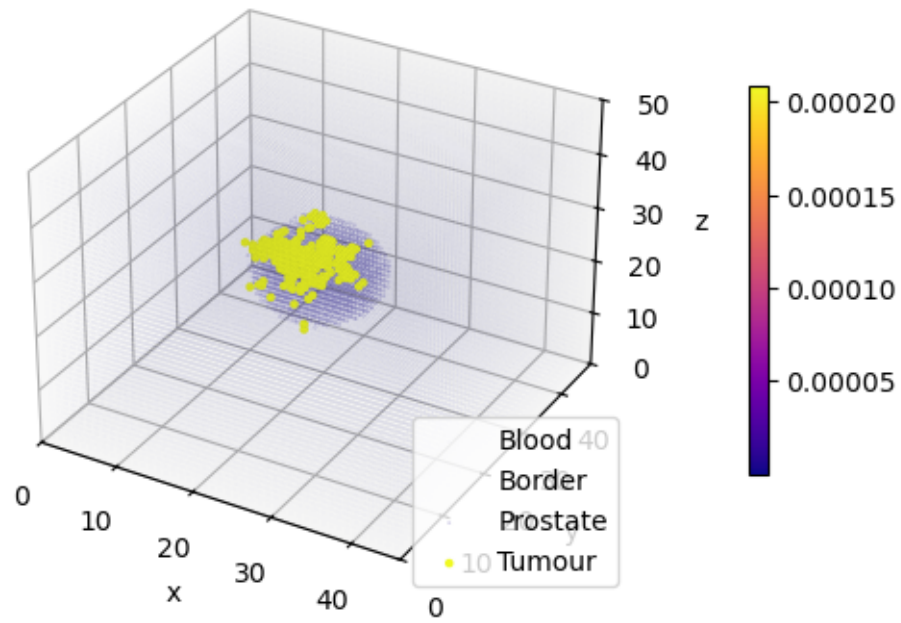
Time 21

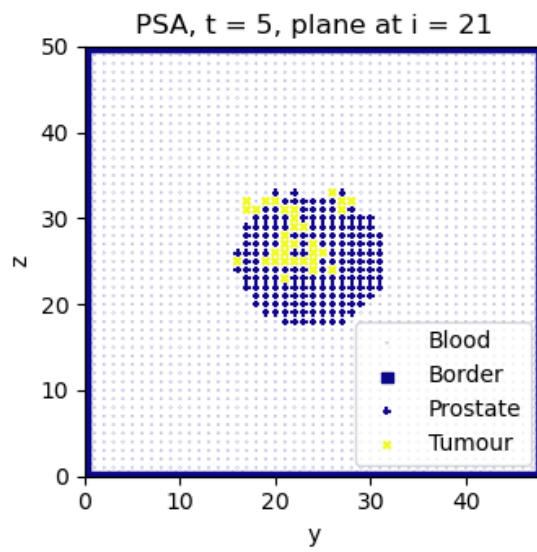
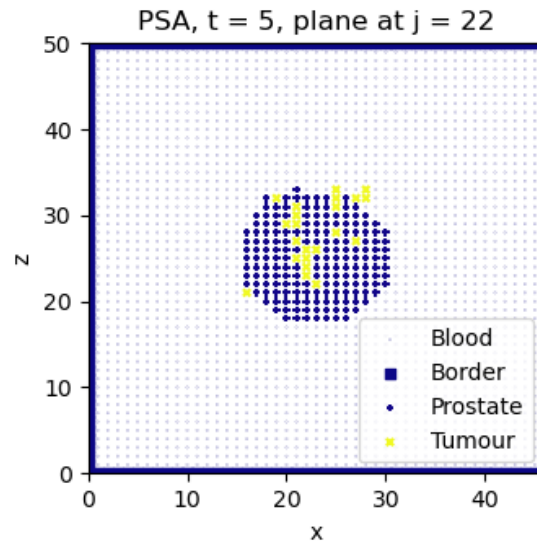
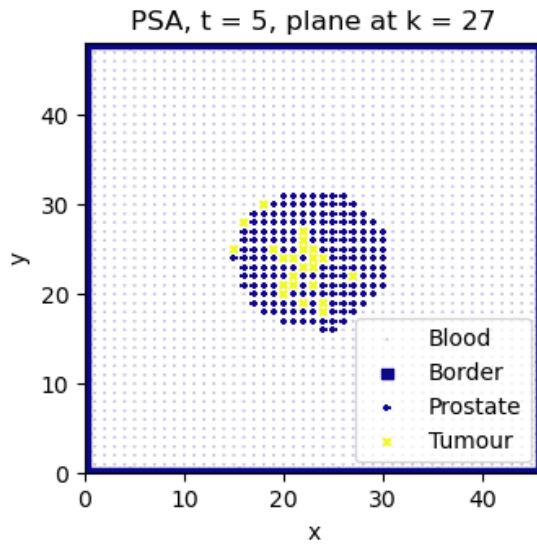
Diffusion PSA_top, with tumour

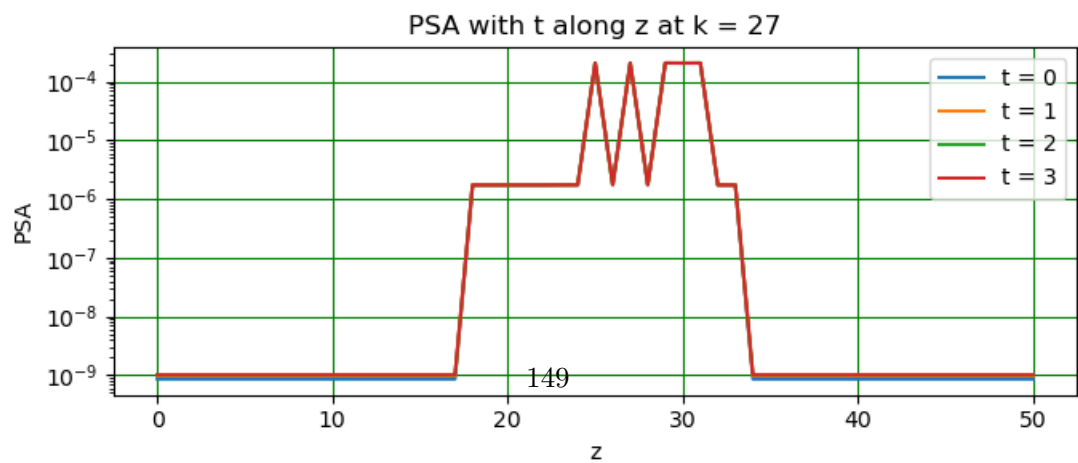
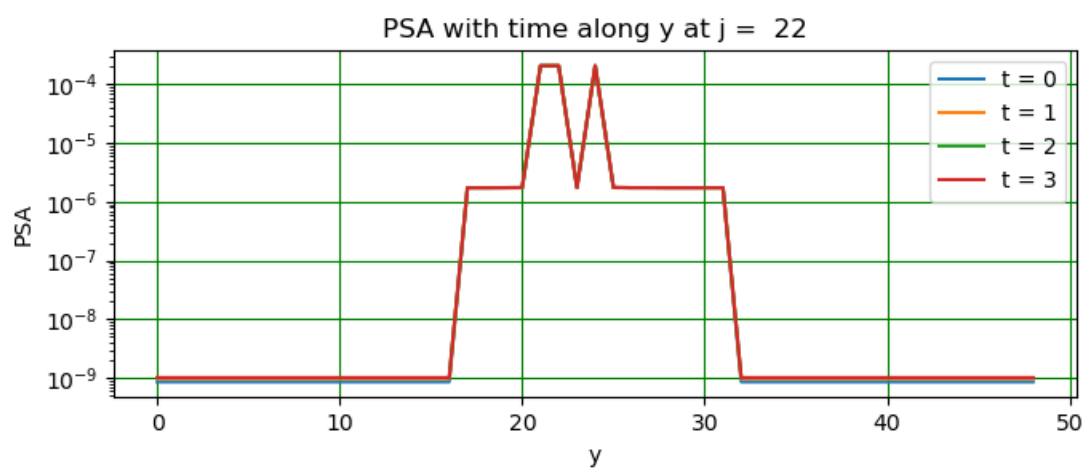
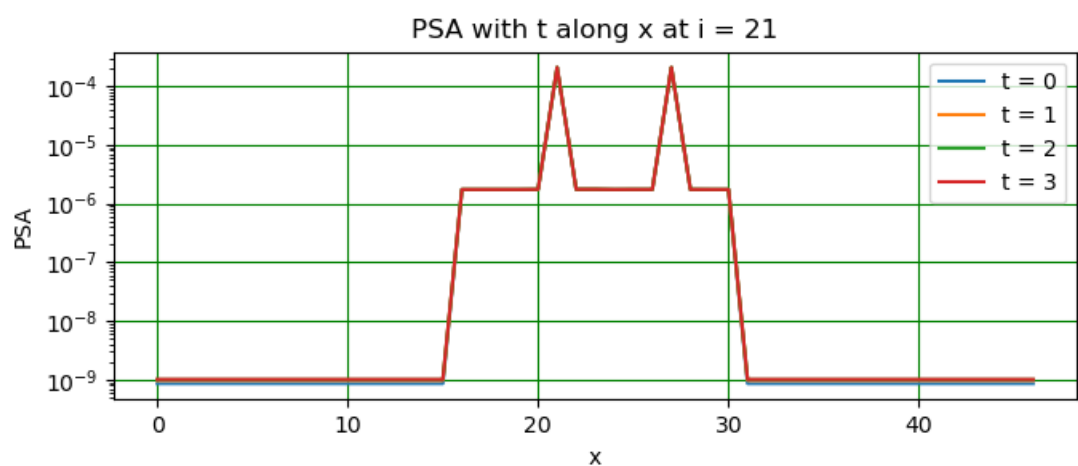
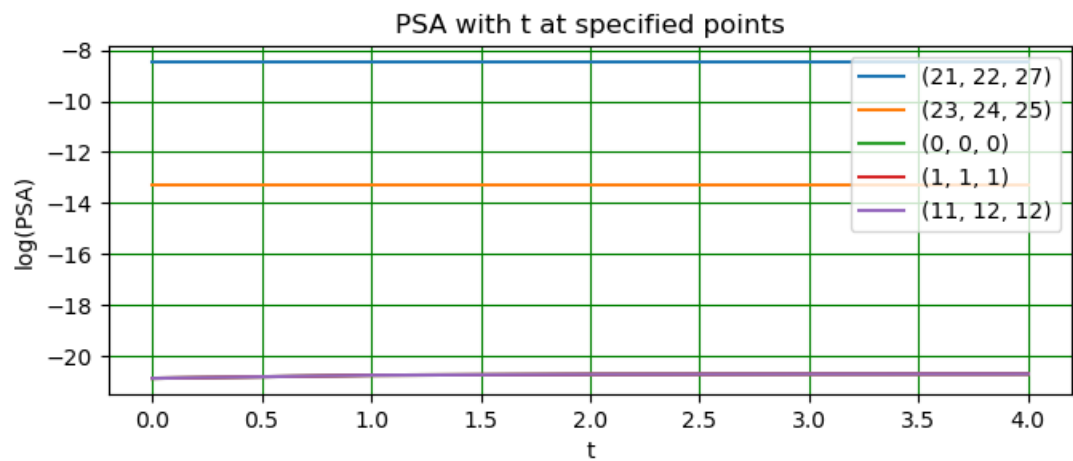
Diffusion converged, nt = 5, ext_test = 3.464936e-04, prostate_test =

1.636775e-04

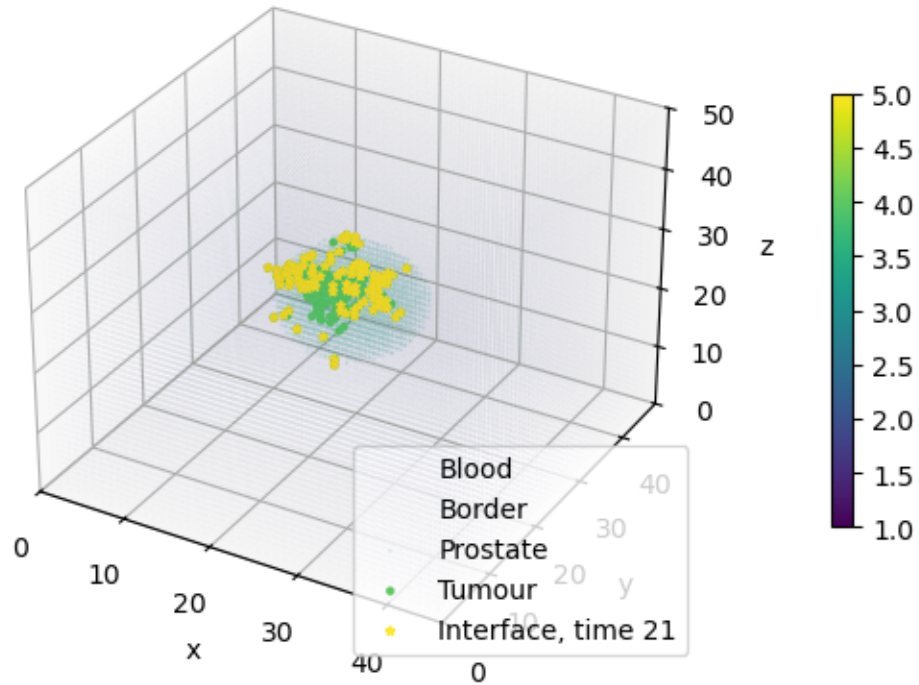
PSA, $t = 5$, xyz







Interface, time 21, xyz



At time 21:

No. tumour cells 235, prostate cells 2102, blood cells 101298

PSA_top_level 1.021112e-09

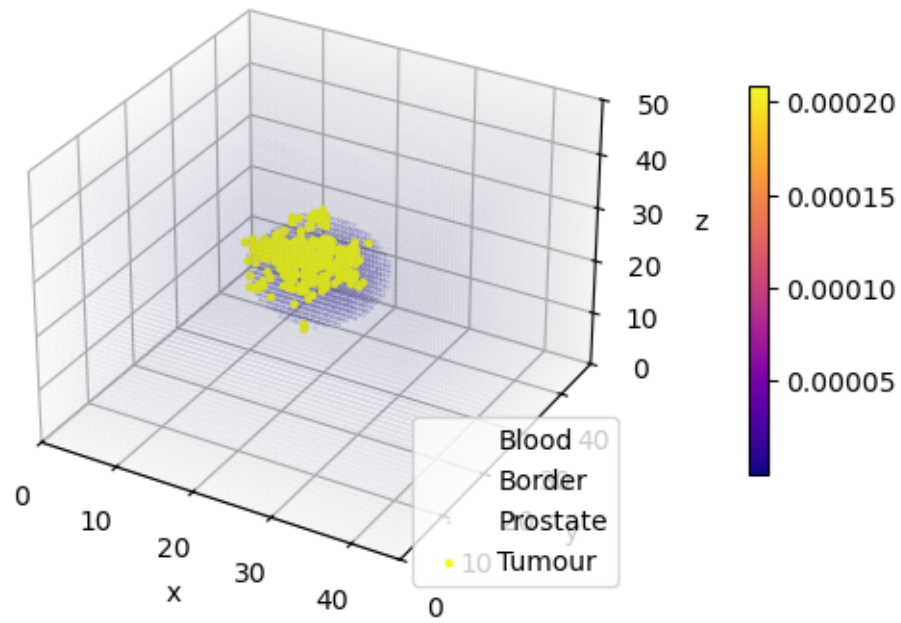
Time 22

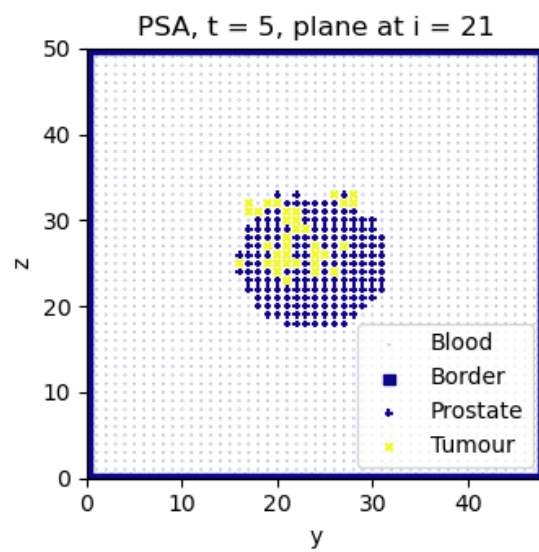
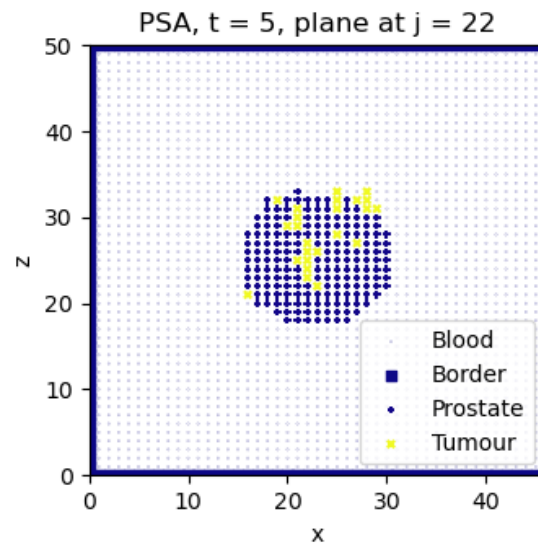
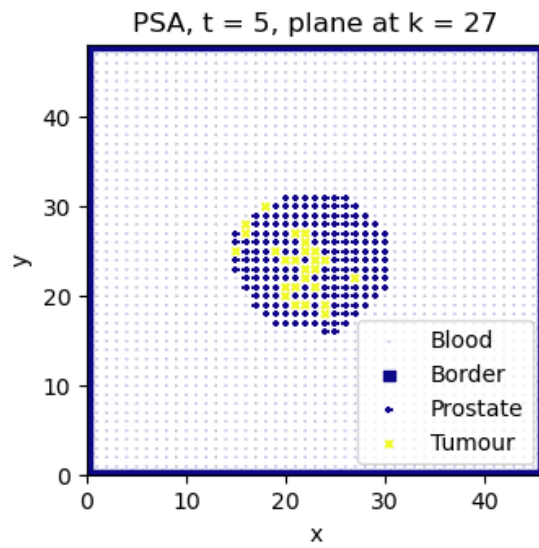
Diffusion PSA_top, with tumour

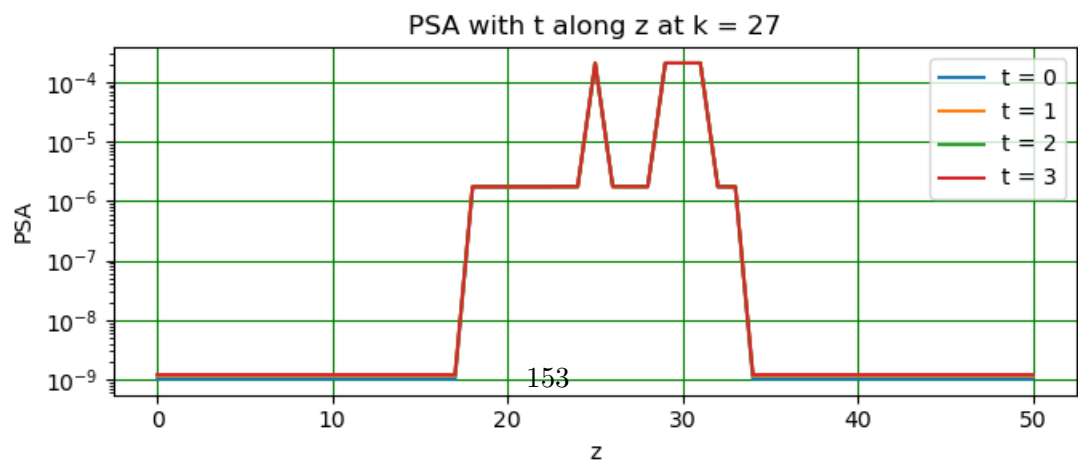
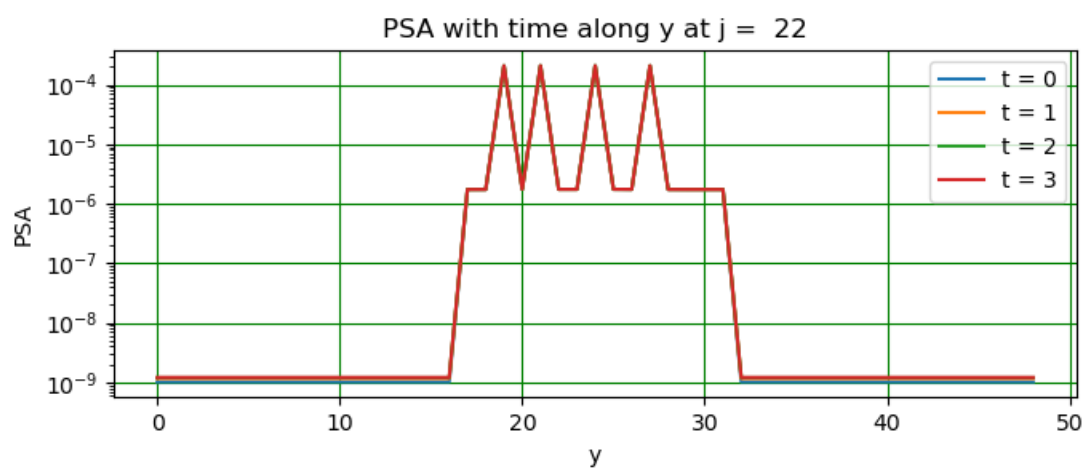
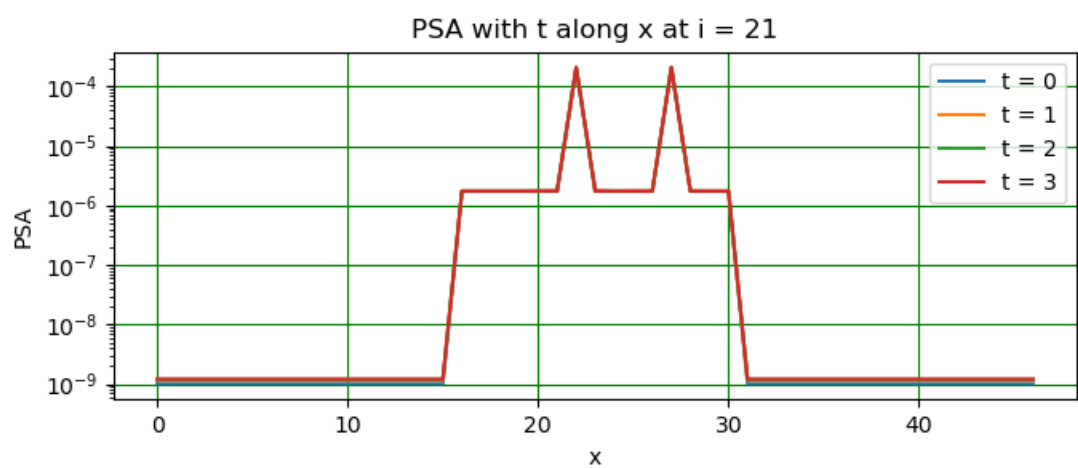
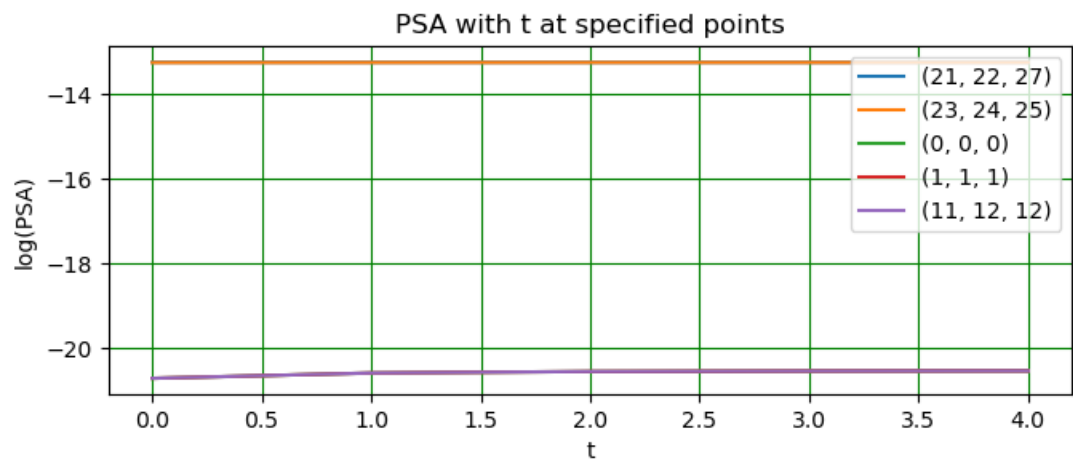
Diffusion converged, nt = 5, ext_test = 3.539279e-04, prostate_test =

1.624184e-04

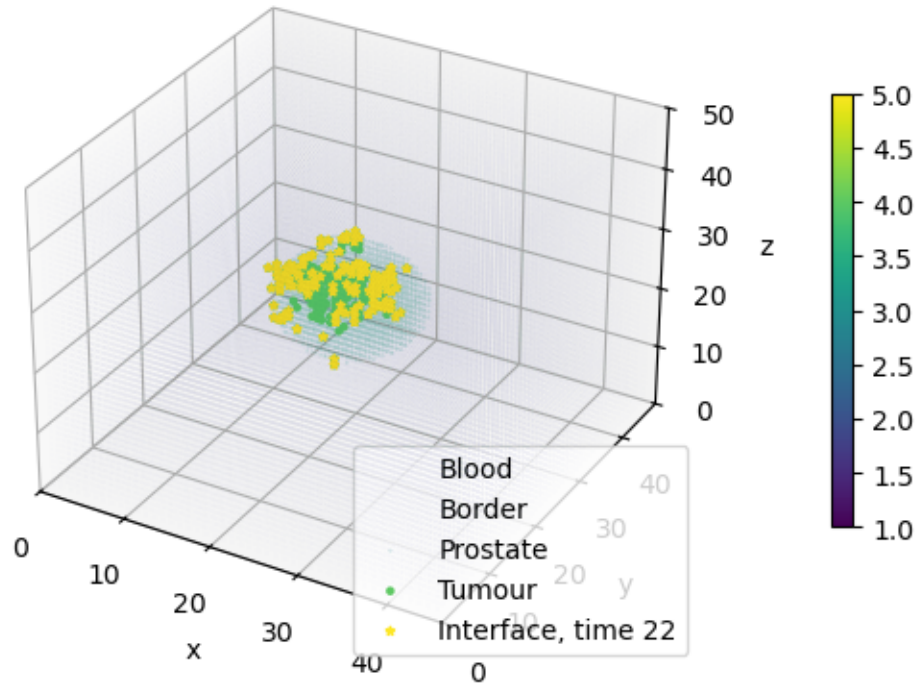
PSA, $t = 5$, xyz







Interface, time 22, xyz



At time 22:

No. tumour cells 289, prostate cells 2102, blood cells 101244

PSA_top_level 1.218494e-09

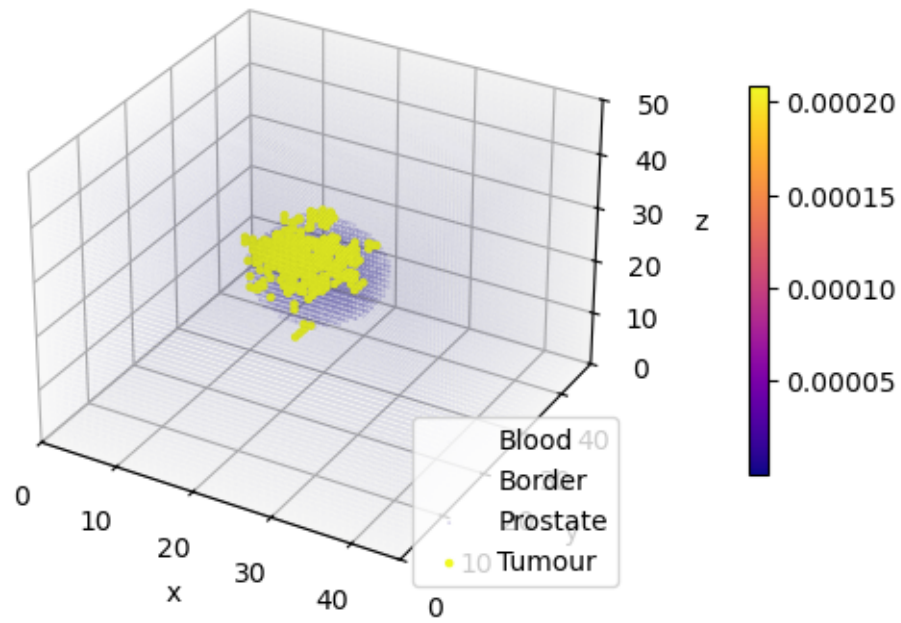
Time 23

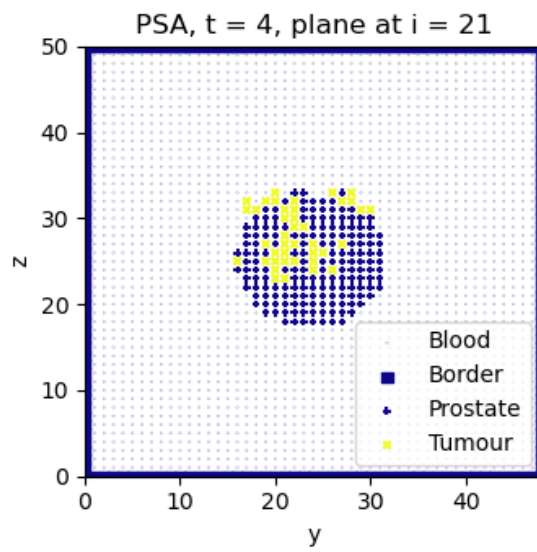
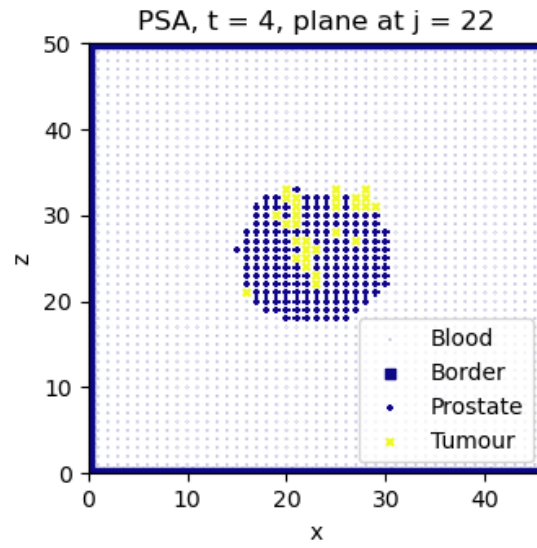
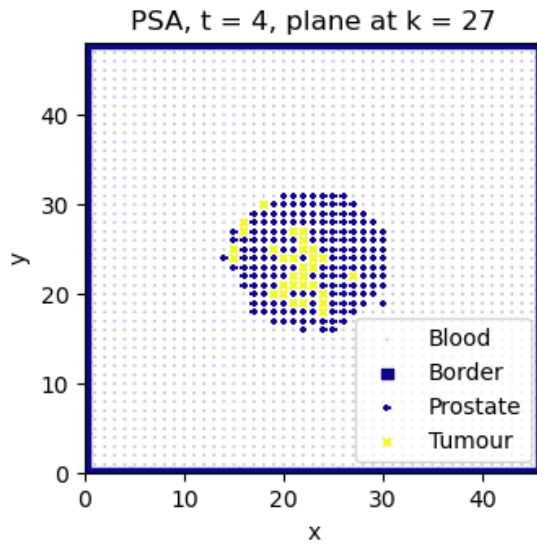
Diffusion PSA_top, with tumour

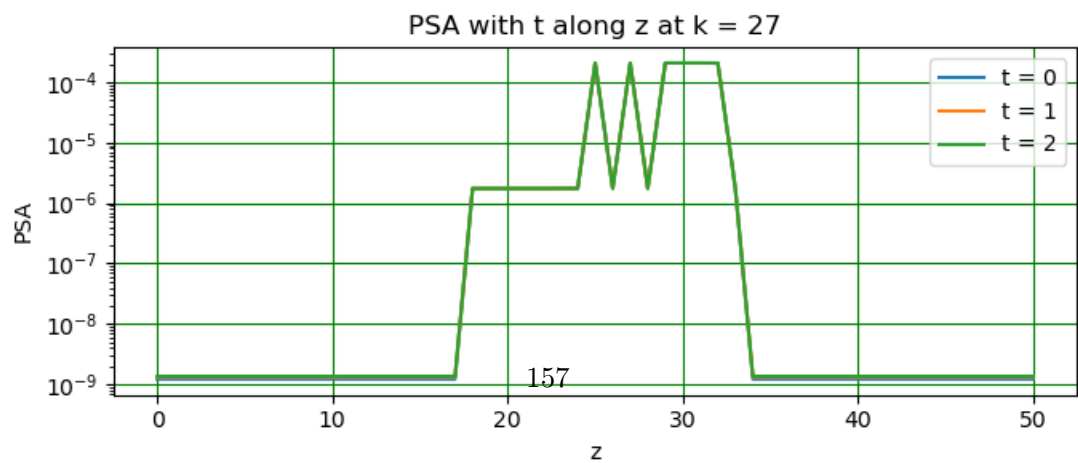
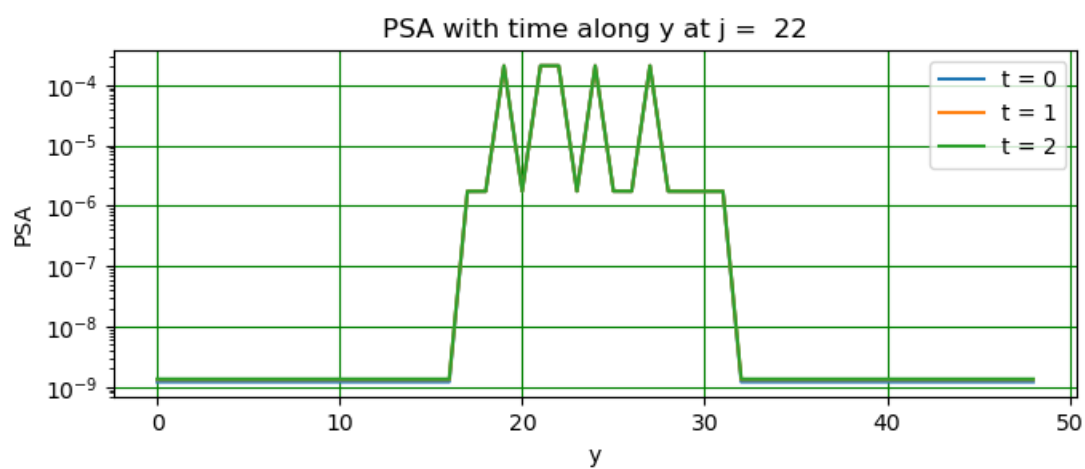
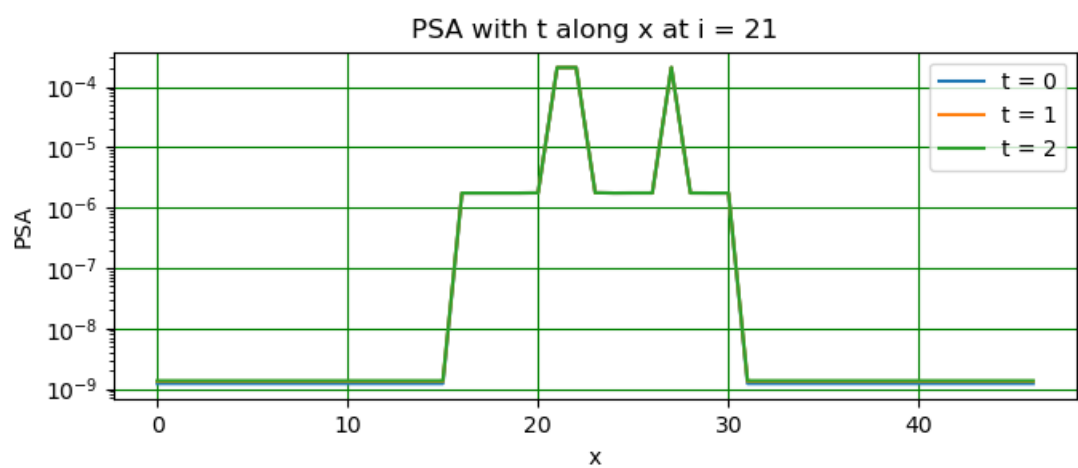
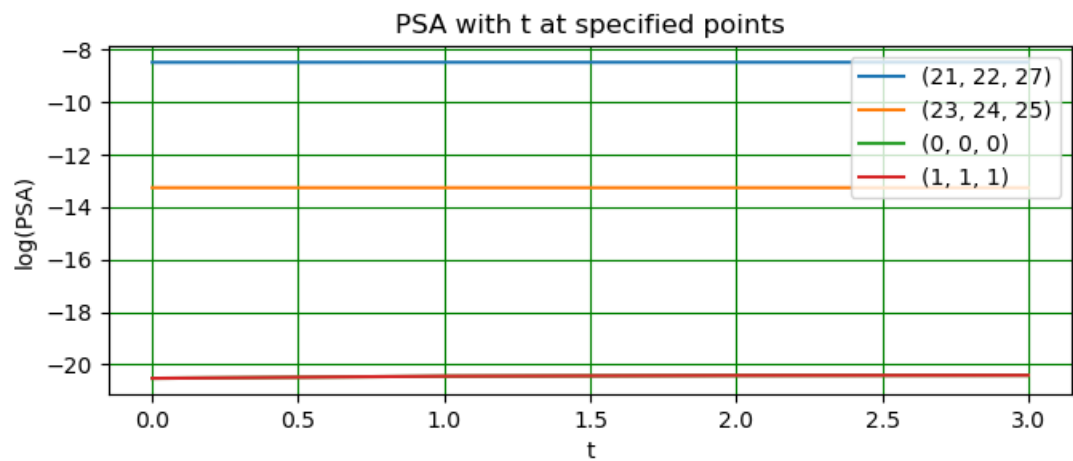
Diffusion converged, nt = 4, ext_test = 7.593402e-04, prostate_test =

3.003397e-04

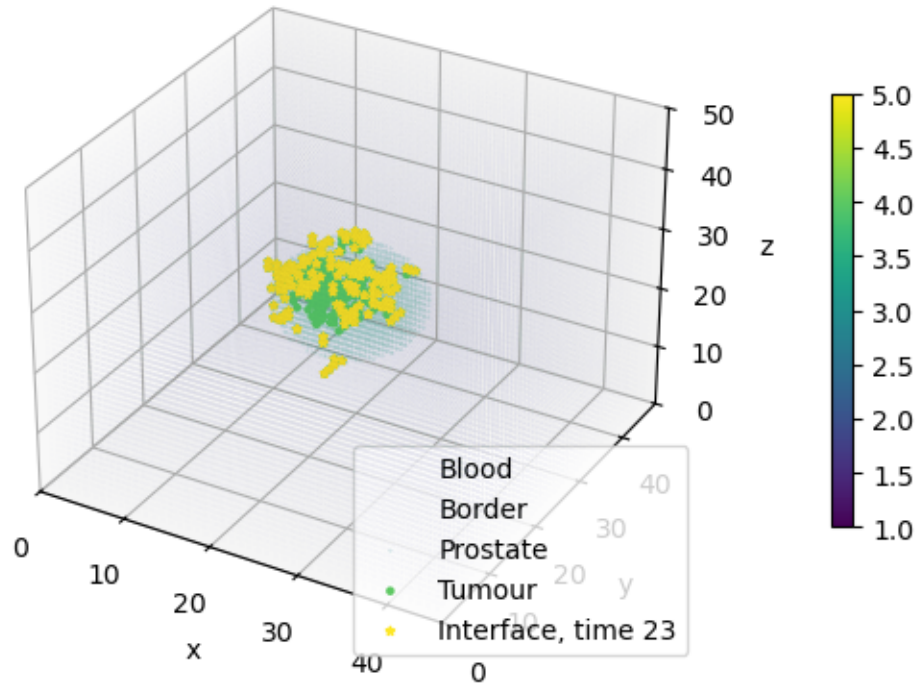
PSA, $t = 4$, xyz







Interface, time 23, xyz



At time 23:

No. tumour cells 355, prostate cells 2102, blood cells 101178

PSA_top_level 1.372078e-09

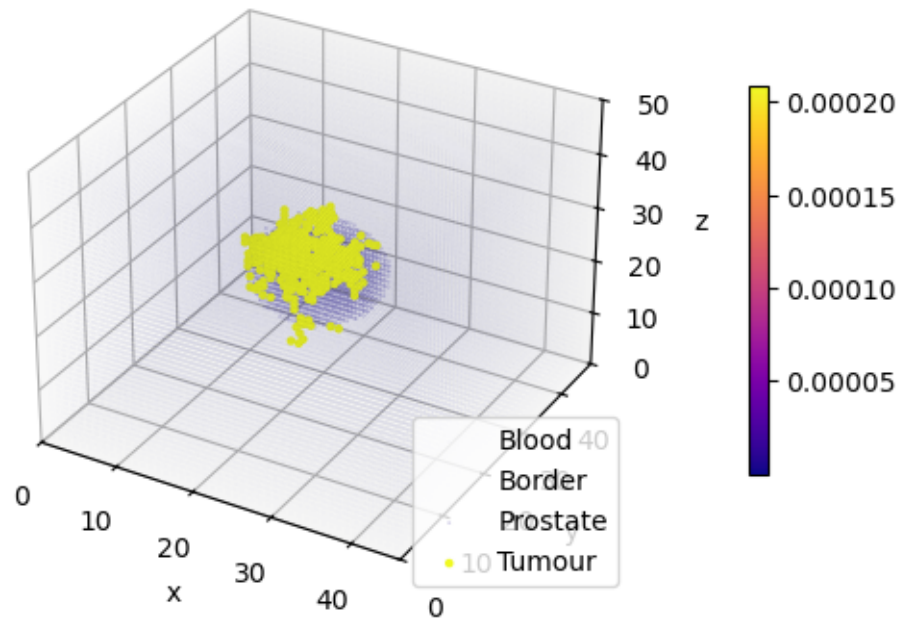
Time 24

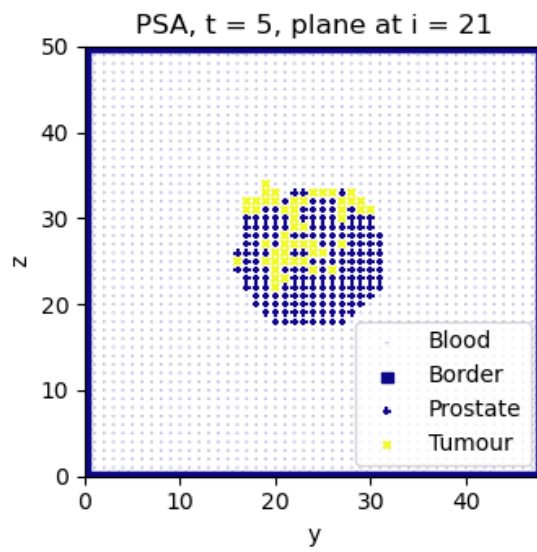
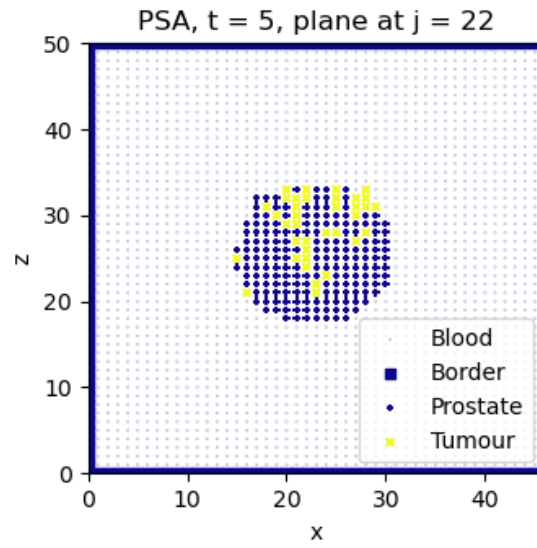
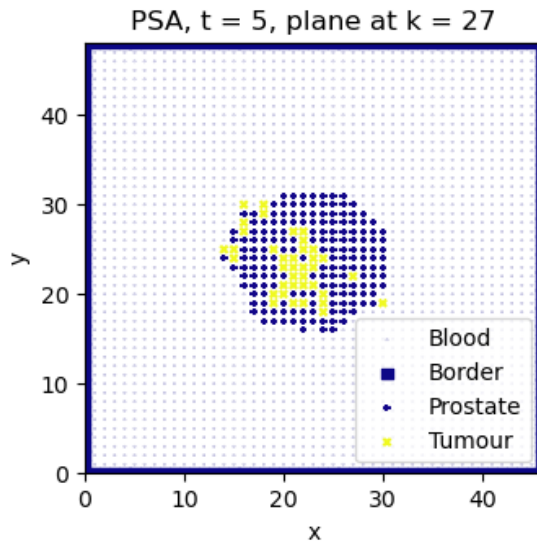
Diffusion PSA_top, with tumour

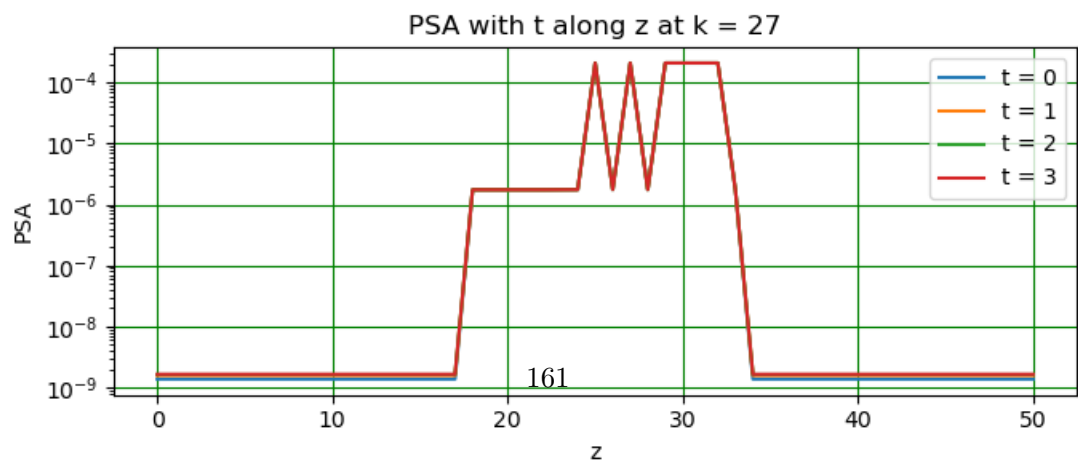
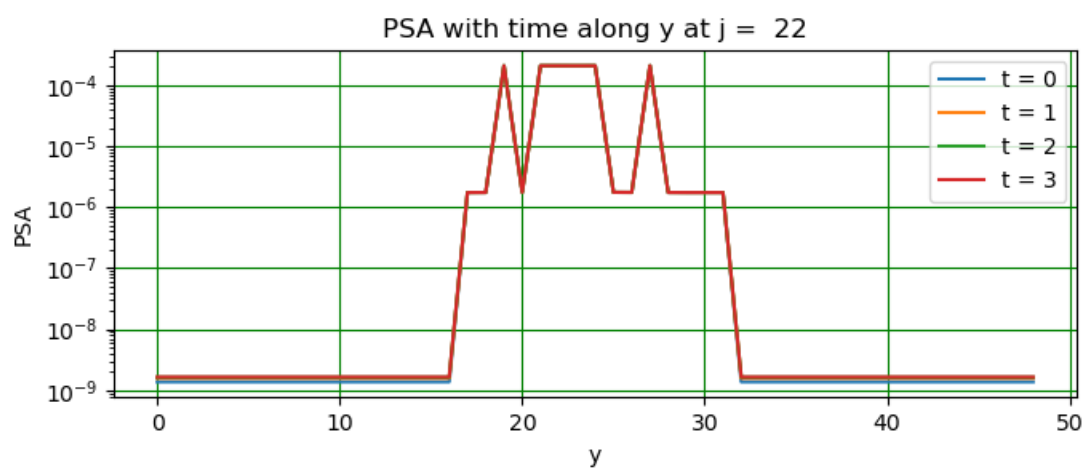
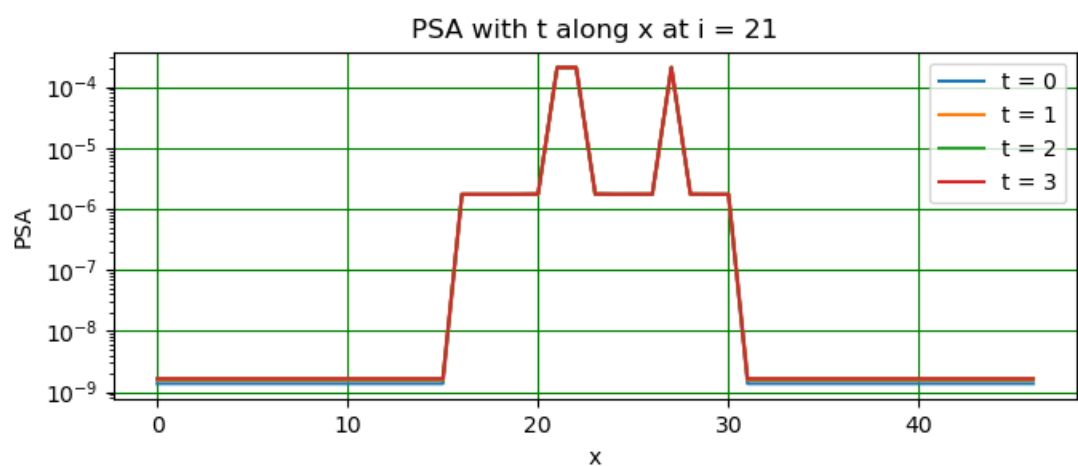
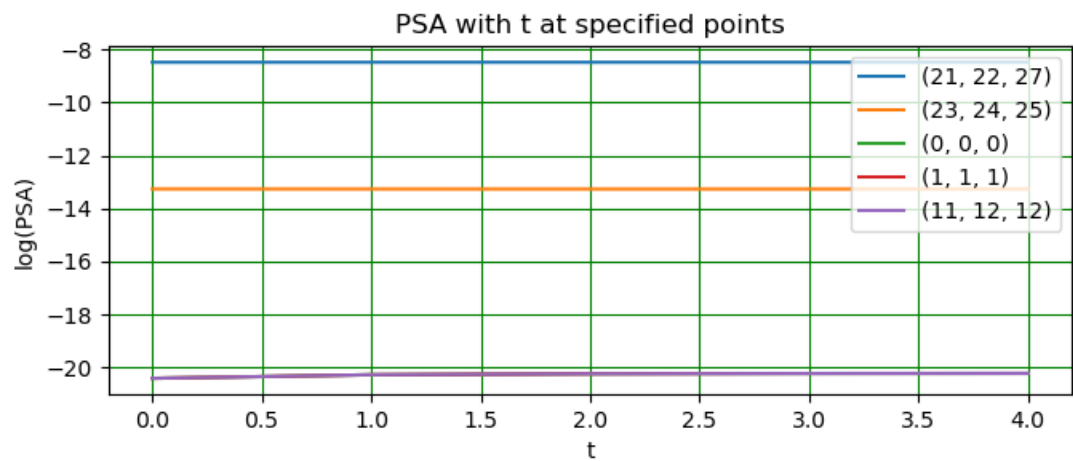
Diffusion converged, nt = 5, ext_test = 3.603722e-04, prostate_test =

2.131324e-04

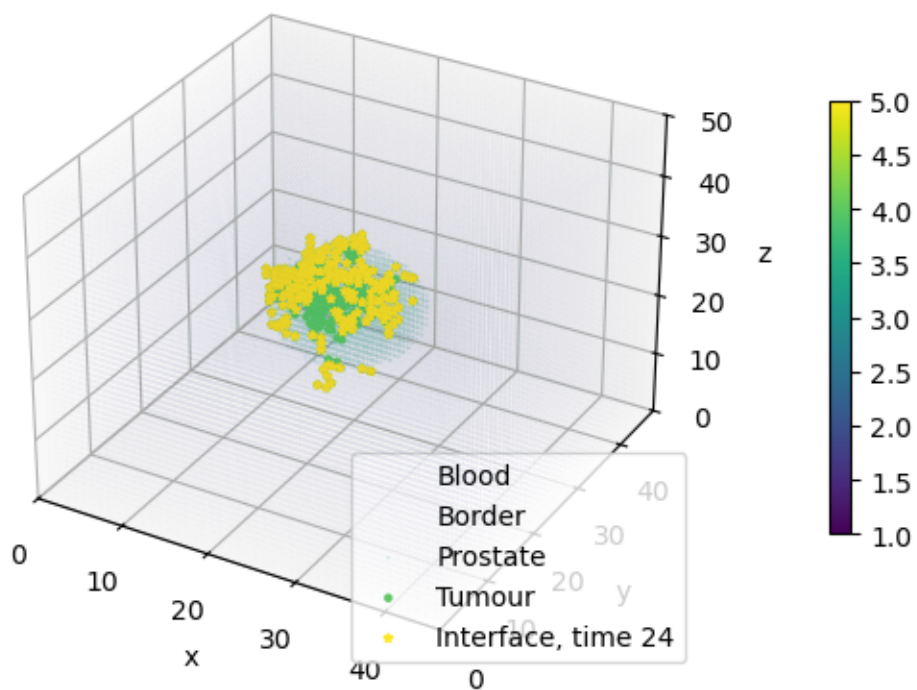
PSA, $t = 5$, xyz







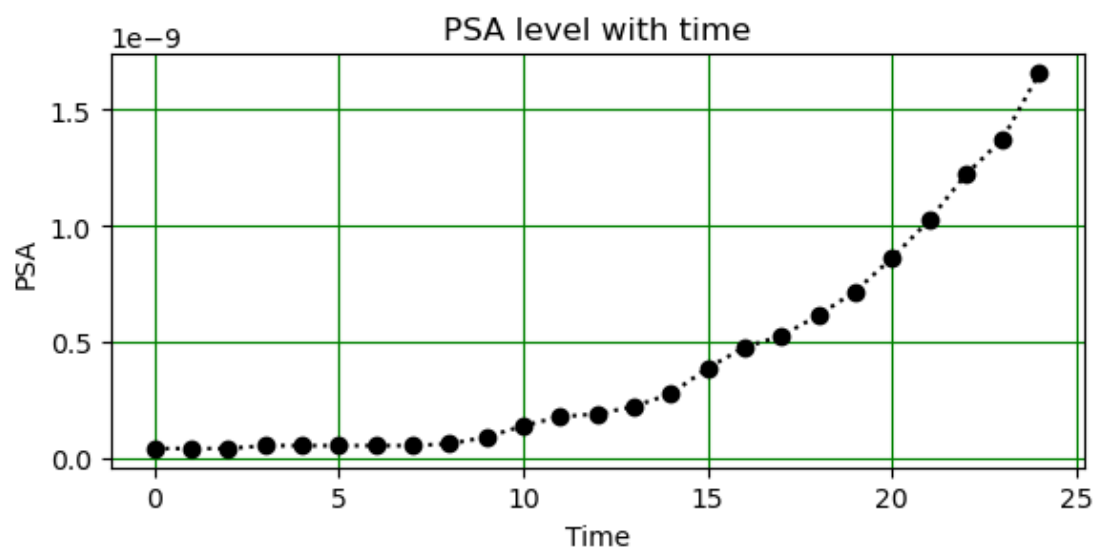
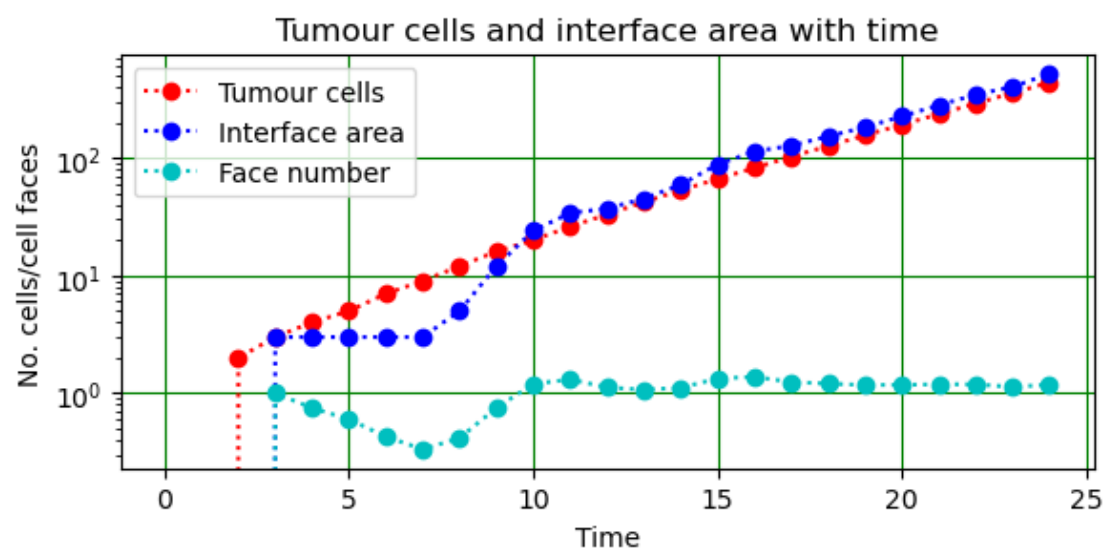
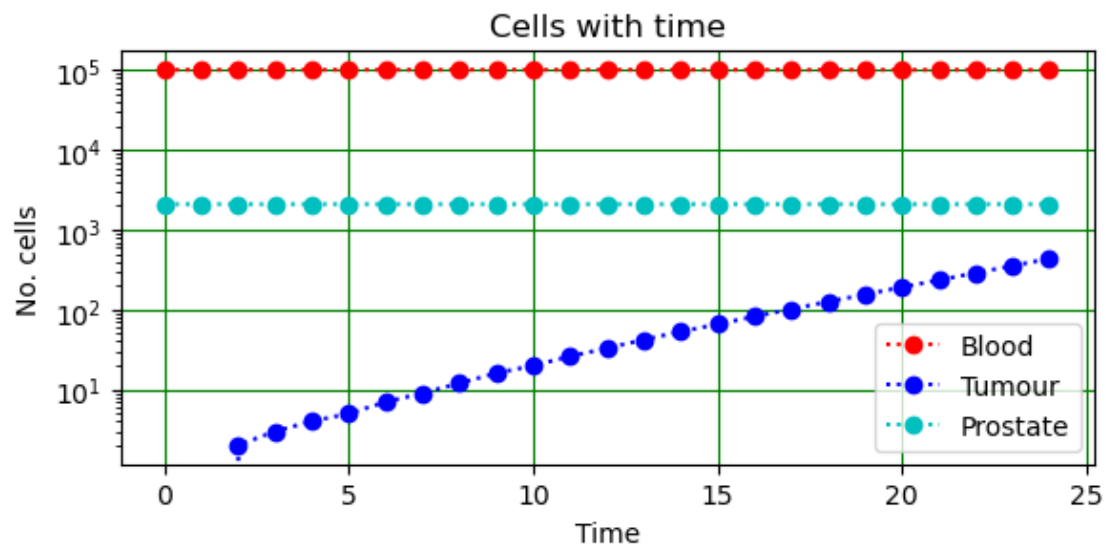
Interface, time 24, xyz

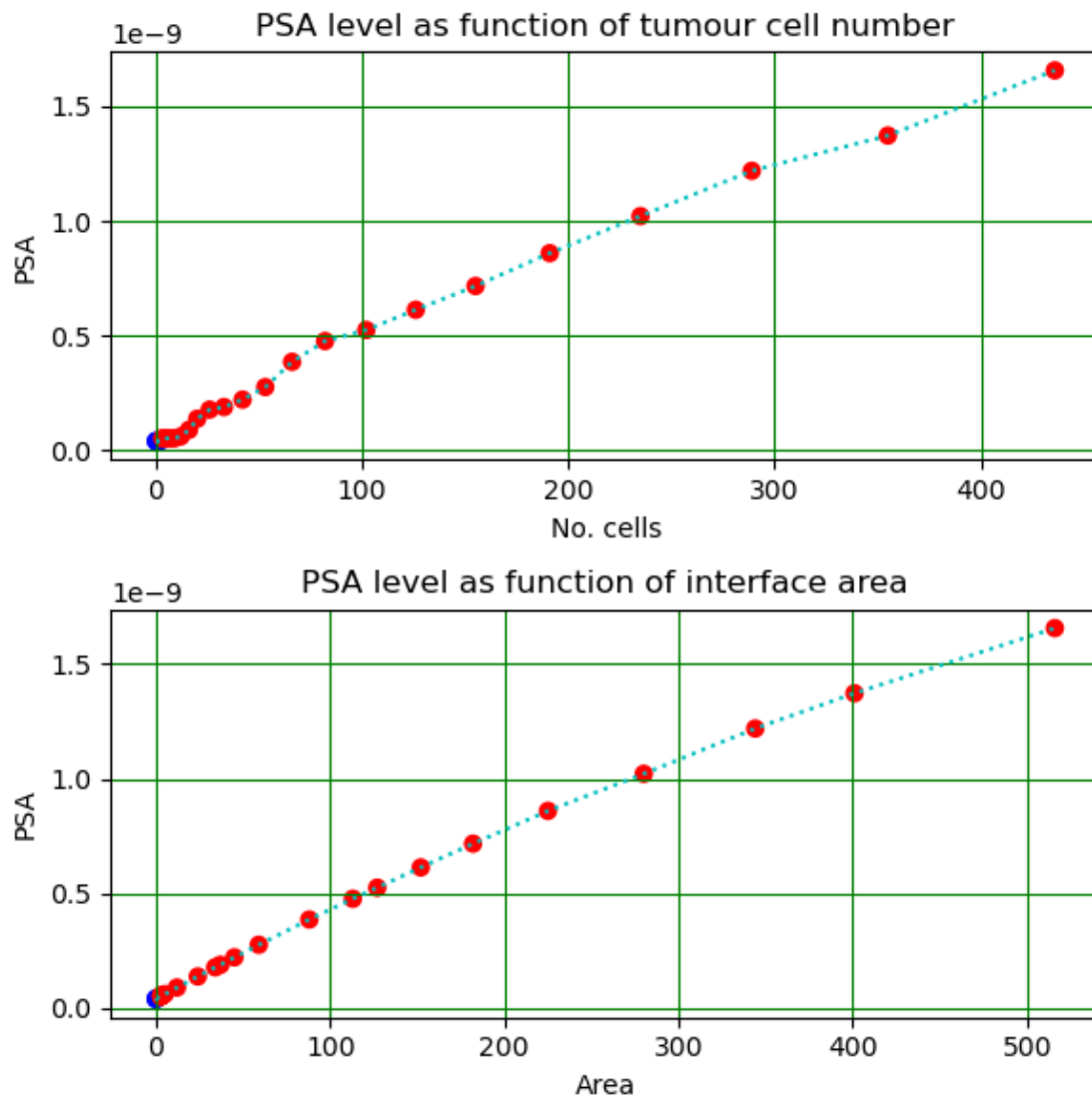


At time 24:

No. tumour cells 436, prostate cells 2102, blood cells 101097

PSA_top_level 1.656060e-09





Date and time 2026-01-10 14:41:19.422540
Time since last check is 0:03:04.483593

1.8 End of model run

Return to ToC: »

```
[17]: #
fig = plt.figure(figsize = (6, 9))
#
```

```

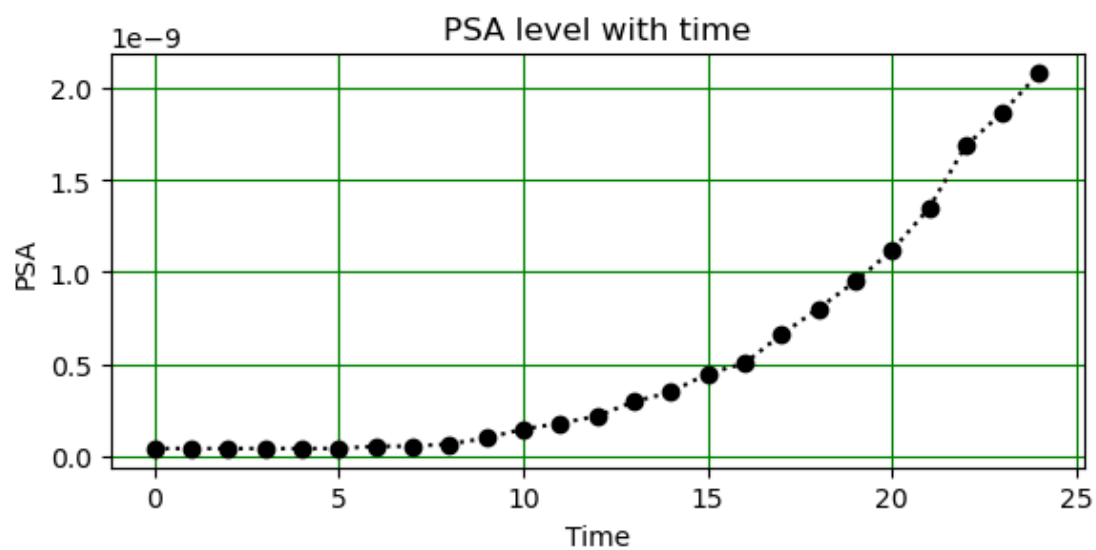
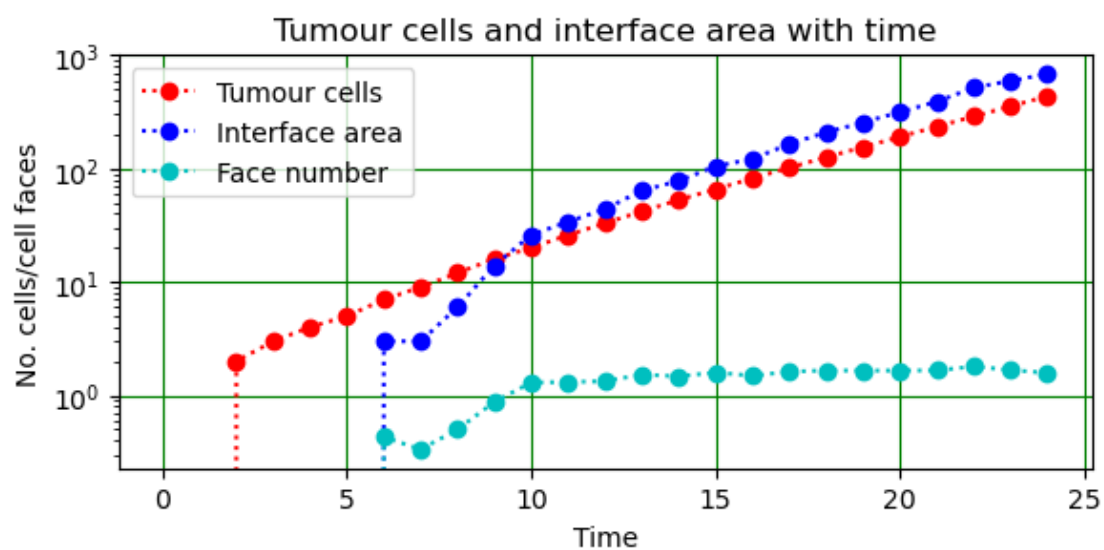
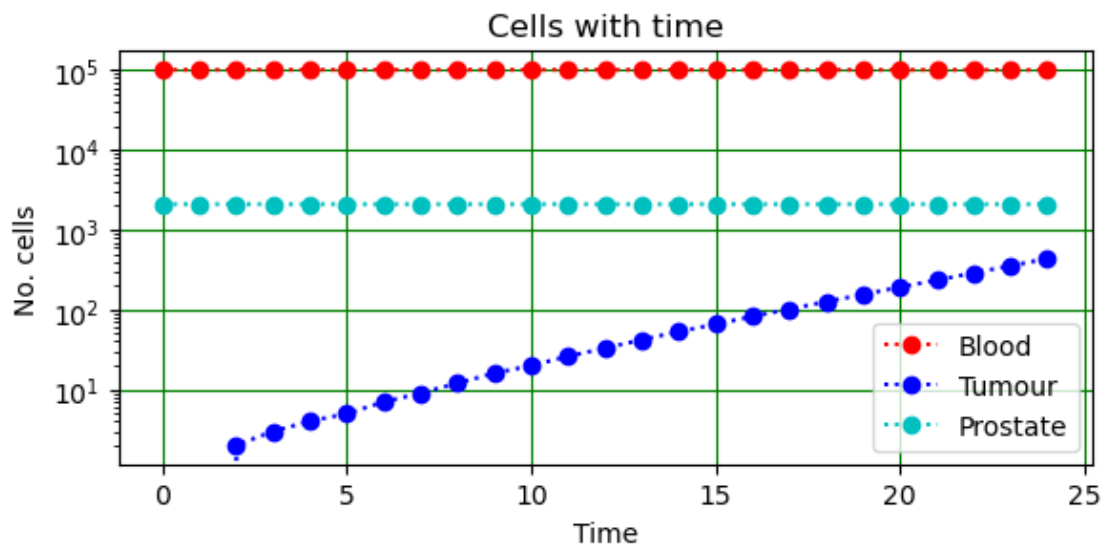
ax = fig.add_subplot(3, 1, 1)
ax.set_title("Cells with time")
ax.set_xlabel("Time")
ax.set_ylabel("No. cells")
ax.plot(times, blood_time, marker = 'o', linestyle = ':', color = 'r', label = "Blood")
ax.plot(times, tumour_time, marker = 'o', linestyle = ':', color = 'b', label = "Tumour")
ax.plot(times, prostate_time, marker = 'o', linestyle = ':', color = 'c', label = "Prostate")
ax.set_yscale('log')
ax.grid(color = 'g')
ax.legend()
#
ax = fig.add_subplot(3, 1, 2)
ax.set_title("Tumour cells and interface area with time")
ax.set_xlabel("Time")
ax.set_ylabel("No. cells/cell faces")
ax.plot(times, tumour_time, marker = 'o', linestyle = ':', color = 'r', label = "Tumour cells")
ax.plot(times, area_time, marker = 'o', linestyle = ':', color = 'b', label = "Interface area")
ax.plot(times, face_number, marker = 'o', linestyle = ':', color = 'c', label = "Face number")
ax.set_yscale('log')
ax.grid(color = 'g')
ax.legend()
#
ax = fig.add_subplot(3, 1, 3)
ax.set_title("PSA level with time")
ax.set_xlabel("Time")
ax.set_ylabel("PSA")
if double:
    ax.plot(times, PSA_top_time, marker = 'v', linestyle = '', color = 'k')
    ax.plot(times, PSA_bot_time, marker = '^', linestyle = '', color = 'k')
    ax.fill_between(times, PSA_bot_time, PSA_top_time, color = 'k', alpha = 0.3)
    if triple:
        ax.plot(times, PSA_mid_time, marker = '+', linestyle = '-', color = 'k')
else:
    ax.plot(times, PSA_top_time, marker = 'o', linestyle = ':', color = 'k')
ax.grid(color = 'g')
#
plt.tight_layout()
plt.show()
#
PSA_cells_time = tumour_time + prostate_time
#

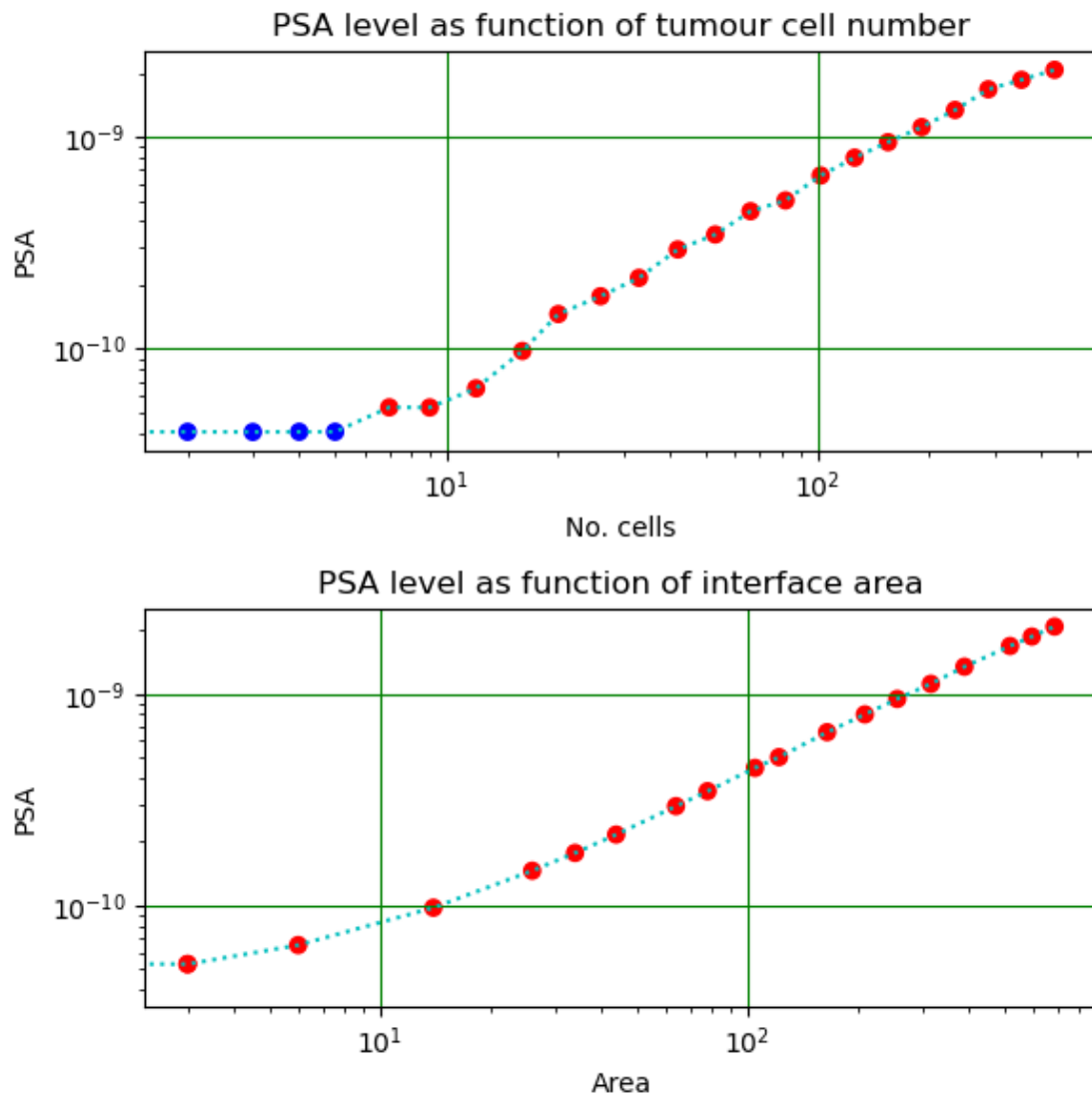
```

```

plot_log_here = True
#
fig = plt.figure(figsize = (6, 6))
#
ax = fig.add_subplot(2, 1, 1)
ax.set_title("PSA level as function of tumour cell number")
ax.set_xlabel("No. cells")
ax.set_ylabel("PSA")
if double:
    ax.scatter(tumour_time, PSA_top_time, marker = 'v', c = btcell_color)
    ax.scatter(tumour_time, PSA_bot_time, marker = '^', c = btcell_color)
    ax.fill_between(tumour_time, PSA_bot_time, PSA_top_time, color = 'c', alpha=
↵0.3)
    if triple:
        ax.scatter(tumour_time, PSA_mid_time, marker = '+', c = btcell_color)
else:
    ax.scatter(tumour_time, PSA_top_time, marker = 'o', c = btcell_color)
    ax.plot(tumour_time, PSA_top_time, marker = '', linestyle = ':', color =
↵'c')
ax.grid(color = 'g')
if plot_log_here and len(tumour_time > 0):
    ax.set_xscale('log')
    ax.set_yscale('log')
#
ax = fig.add_subplot(2, 1, 2)
ax.set_title("PSA level as function of interface area")
ax.set_xlabel("Area")
ax.set_ylabel("PSA")
if double:
    ax.scatter(area_time, PSA_top_time, marker = 'v', c = btcell_color)
    ax.scatter(area_time, PSA_bot_time, marker = '^', c = btcell_color)
    ax.fill_between(area_time, PSA_bot_time, PSA_top_time, color = 'c', alpha =
↵0.3)
    if triple:
        ax.scatter(area_time, PSA_mid_time, marker = '+', c = btcell_color)
else:
    ax.scatter(area_time, PSA_top_time, marker = 'o', c = btcell_color)
    ax.plot(area_time, PSA_top_time, marker = '', linestyle = ':', color = 'c')
ax.grid(color = 'g')
if plot_log_here:
    ax.set_xscale('log')
    ax.set_yscale('log')
#
plt.tight_layout()
plt.show()

```





1.9 Code cell template

Return to ToC: »

```
[18]: import datetime
now = datetime.datetime.now()
print("Date and time",str(now))
#
#
then = now
now = datetime.datetime.now()
```

```
print("\nDate and time",str(now))  
print("Time since last check is",str(now - then))
```

Date and time 2026-01-10 14:36:46.380883

Date and time 2026-01-10 14:36:46.381010

Time since last check is 0:00:00.000127