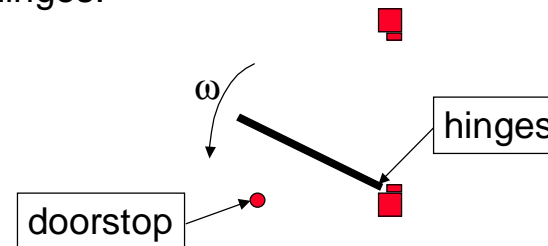


Lecture 11

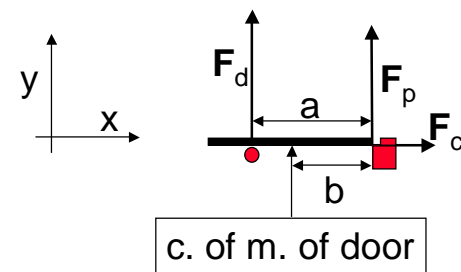
- ◆ Centre of Percussion
- ◆ Precession of the Equinox
- ◆ Stability of Spinning Objects
- ◆ Rolling Coin
- ◆ Gyrocompass

Centre of Percussion

- ◆ Example, placing door stop in position which minimises forces on hinges.



- ◆ Consider forces at moment of impact



Centre of percussion cont.

- ◆ F_d and F_p are large impact forces, F_c is smaller centripetal force. Minimise damage to hinge by making F_p as small as possible.
- ◆ Consider change of ang. mom. of door about hinges (along z axis)

$$\begin{aligned}L_f - L_i &= 0 - (-I\omega) \\ &= \int \tau dt = \int F_d a dt \\ I\omega &= a \int F_d dt \quad (1)\end{aligned}$$

- ◆ Consider change of linear momentum of door's c. of m.

$$\begin{aligned}p_f - p_i &= 0 - (-Mb\omega) \\ &= \int F_d + F_p dt \\ Mb\omega &= \int F_d dt + \int F_p dt \quad (2)\end{aligned}$$

Centre of percussion cont.

- ◆ Now substitute expression for F_d from (1) in (2) to get

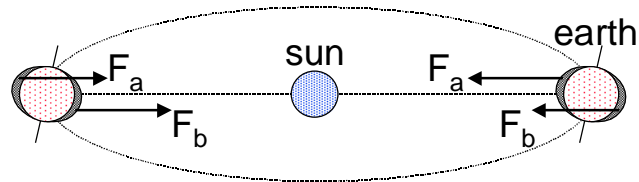
$$Mb\omega = \frac{I\omega}{a} + \int F_p dt$$

$$\int F_p dt = \left(Mb - \frac{I}{a} \right) \omega$$

- ◆ Minimise by choosing $a = \frac{I}{Mb}$
- ◆ Using $I = \frac{1}{3}Mw^2$ where $w=2b$ is width of door we see $a = \frac{4Mb^2}{3Mb} = \frac{4b}{3}$ or $\frac{2w}{3}$
- ◆ This point is centre of percussion. Another e.g. "sweet spot" on squash or tennis racket. (Ball on sweet spot, least reaction on player's hands.)

Precession of the Equinox

- ◆ Direction of earth's axis changes (slowly) w.r.t fixed stars, why?



winter $F_a < F_b$
(further from sun)
torque out of plane

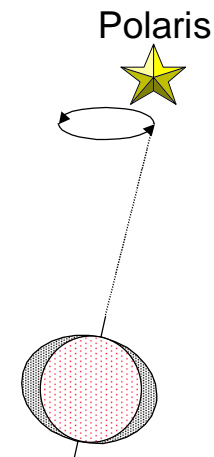
summer $F_a > F_b$
(nearer to sun)
torque out of plane

- ◆ Bulge due to earth's rotation, radius at equator 21 km larger than at poles.
- ◆ At spring and autumn equinoxes no torque, averaged over year have torque in one direction.

Precession of the equinoxes cont.

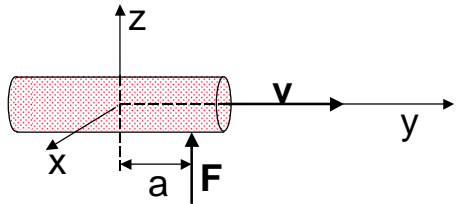
- ◆ Similar effect due to moon, torque about two times larger.
- ◆ Average torque perpendicular to spin ang. mom. and in plane of ecliptic, c.f. "Precession of Gyroscope".

*Period of precession
26000 years.
13000 years
from now polar
axis will point
47° away from
present pole
star Polaris.*



Stability of Spinning Objects

- ◆ Look at stability of moving object subject to small disturbing force



- ◆ Apply force F for time Δt . Torque about x is Fa so angular impulse is $Fa\Delta t$.

$$\Delta L_x = I_x \Delta \omega = Fa\Delta t$$

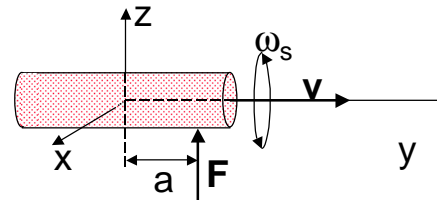
$$\Delta \omega = (\omega_x - \omega_0) = \frac{Fa\Delta t}{I_x}$$

$$\omega_x = \frac{Fa\Delta t}{I_x}$$

- ◆ Causes body to “tumble”.

Stability of spinning objects cont.

- ◆ Stabilise object by spinning about direction of motion, frequency ω_s , angular momentum L_s .



- ◆ Torque along x axis now causes precession about y axis with frequency

$$\Omega = \frac{Fa}{L_s}$$

Stability of spinning objects cont.

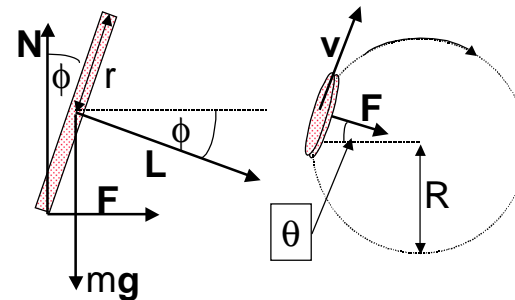
- ◆ When force removed precession stops, angular displacement is

$$\phi = \Omega \Delta t = \frac{Fa\Delta t}{L_s}$$
- ◆ Spinning object does not tumble, slightly changes orientation while force applied then stops precessing.
- ◆ Note, spin has no effect on c. of m. which in both cases acquires velocity

$$\Delta v_y = \frac{F\Delta t}{M}$$

Rolling Coin

- ◆ Why does coin roll in “circle”?



- ◆ We have: $N = mg$

$$F = \frac{Mv^2}{R}$$

- ◆ Torque about c. of m.

$$\tau = Nr \sin \phi - Fr \cos \phi$$

$$= mgr \sin \phi - \frac{Mv^2}{R} r \cos \phi \quad (1)$$

Rolling coin cont.

- ◆ Horizontal component of ang. mom.
 $L_h = L \cos \phi$

- ◆ Precesses due to torque, tends to prevent coin falling over (cf. bicycle problem)

$$\tau = \frac{dL_h}{dt} = L_h \frac{d\theta}{dt} = L_h \Omega \quad (2)$$

- ◆ What is condition for rolling in circle?
Need precession freq. same as freq. of rotation around circle!

$$\Omega = \frac{v}{R}$$

- ◆ Relate ang. mom. to speed of coin

$$L = I\omega = \frac{Mr^2}{2} \frac{v}{r} = \frac{Mrv}{2}$$

Rolling coin cont.

- ◆ Substitute for L_h and Ω in (2)

$$\tau = \frac{Mv^2 r \cos \phi}{2R}$$

- ◆ Now substitute for τ using (1)

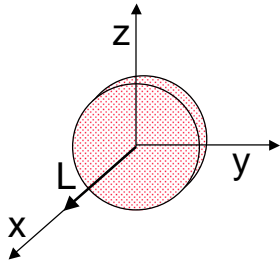
$$Mgr \sin \phi - \frac{Mv^2 r \cos \phi}{R} = \frac{Mv^2 r \cos \phi}{2R}$$

$$Mgr \sin \phi = \frac{3Mv^2 r \cos \phi}{2R}$$

$$\tan \phi = \frac{3v^2}{2gR}$$

Gyrocompass

- ◆ Consider gyroscope spinning about x axis in suspension free to rotate about y axis. Apply torque about z axis.



- ◆ Torque causes ang. mom. along z axis to increase. Happens by causing precession so component of L along z axis.
- ◆ No ang. mom. along y axis.

Gyrocompass cont.

- ◆ Precession stops when L along z axis.
- ◆ Gyrocompass is gyroscope constrained so axis can only move in horizontal plane.
- ◆ Rotation of earth causes horizontal plane to shift w.r.t. inertial plane.
- ◆ Gyroscope axis “would like” to remain stationary, but rotation of earth exerts torque through bearings causing precession.
- ◆ Torque causes gyroscope axis to line up with axis of rotation of earth.