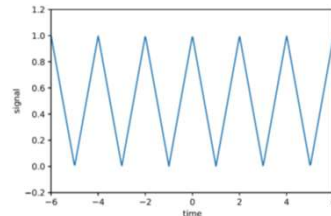


## Filters and forced oscillations – Fourier series in physics

- In this lecture we will:
  - ◆ See a practical use of Fourier series in analysing electronic circuits.
  - ◆ See how 2<sup>nd</sup> order differential equations can arise in physical situations such as the motion of masses on springs.
  - ◆ Examine the case of periodic “forcing terms” and see how to deal with them using Fourier series.
  - ◆ Do an example.

- A comprehension question for this lecture:
  - ◆ Deduce as much as you can about the coefficients in the Fourier series for the following function:



- ◆ Compare your guesses with the true values.

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## Fourier series in practical physics

- Suppose we have two electronic circuits that only let through signals in certain frequency ranges:
  - ◆  $f < f_{\text{top}}$  (a “low-pass” filter).
  - ◆  $f > f_{\text{bot}}$  (a “high-pass” filter).
- What will we see if we send a square wave signal through these circuits?
- Input:

$$f(t) = \begin{cases} -1 & \text{if } -2 \leq t < -1 \\ 1 & \text{if } -1 \leq t < 1 \\ -1 & \text{if } 1 \leq t < 2 \end{cases}$$

- Represent as a Fourier series.

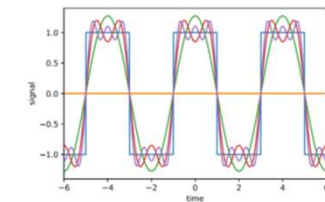
- Show that:

$$a_0 = 0$$

$$b_n = 0$$

$$a_n = \frac{2}{n\pi} \sin \frac{n\pi}{2}$$

- First few terms:

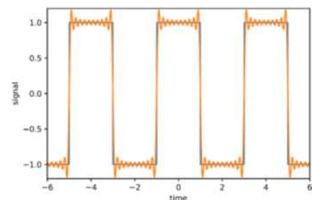


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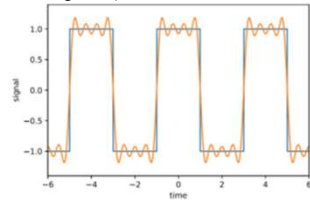
## Why use Fourier Series?

- If add up first 20 terms get reasonable representation of input:

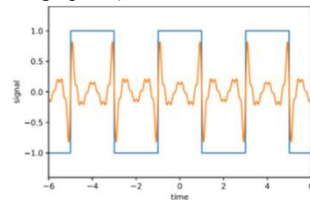


- What do we get if we pass this signal through our low- and high-pass filters?
- Find out by applying effect of circuit to sine and cosine terms that make up input, then adding them up again.

- Low-pass (cut off terms above tenth):



- High-pass (remove terms below fourth):



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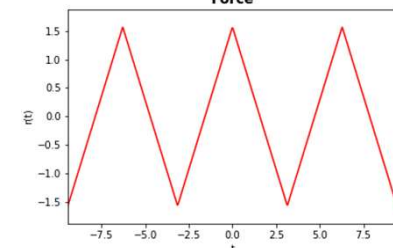
## Forced oscillations

- Consider a mass  $m$  attached to a spring with spring constant  $k$ .
- The force on the mass, at distance  $y$  from equilibrium, is  $F = -ky$ .
- Newton’s second law relates the force to the acceleration,  $F = m\ddot{y}$ .
- Hence  $m\ddot{y} = -ky$ .
- Now assume that an external force  $r(t)$  is also applied to the mass.
- Then:  $m\ddot{y} = r(t) - ky$  or  $m\ddot{y} + ky = r(t)$ .
- We have seen how to solve this if  $r(t)$  is something like  $r(t) = \cos \gamma t + \sin \gamma t$ .
- What if  $r(t)$  is a more complicated periodic function?

- Can solve by representing  $r(t)$  as a Fourier series.

- An example:  $m = 1$ ,  $k = 4$  and

$$r(t) = \begin{cases} t + \frac{\pi}{2} & \text{for } -\pi < t \leq 0 \\ -t + \frac{\pi}{2} & \text{for } 0 < t \leq \pi \end{cases}$$



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## Forced oscillations

- First compute the Fourier series for  $r(t)$ .

- Only cosine terms (even function),  $a_0$  is zero (average of  $r(t)$ ) and  $T = 2\pi$ .

$$a_n = \frac{1}{\pi} \int_{-\pi}^{\pi} r(t) \cos nt \, dt$$

$$= \frac{1}{\pi} \int_{-\pi}^0 \left(t + \frac{\pi}{2}\right) \cos nt \, dt + \frac{1}{\pi} \int_0^{\pi} \left(-t + \frac{\pi}{2}\right) \cos nt \, dt$$

$$= \frac{2}{\pi} \int_0^{\pi} \left(-t + \frac{\pi}{2}\right) \cos nt \, dt$$

$$= \frac{2}{\pi} \left( -\int_0^{\pi} t \left(\frac{\sin nt}{n}\right) + \frac{\pi}{2} \int_0^{\pi} \cos nt \, dt \right)$$

$$= \frac{2}{\pi} \left( \left[ -t \frac{\sin nt}{n} \right]_0^{\pi} + \int_0^{\pi} \frac{\sin nt}{n} \, dt + \frac{\pi}{2} \left[ \frac{\sin nt}{n} \right]_0^{\pi} \right)$$

- Hence:

$$a_n = \frac{2}{\pi} \left[ -\frac{\cos nt}{n^2} \right]_0^{\pi}$$

$$= \frac{2(1 - \cos n\pi)}{\pi n^2}$$

- Now  $1 - \cos n\pi$  is 2 if  $n$  is odd and zero if  $n$  is even, so:

$$r(t) = \frac{4}{\pi} \left( \cos t + \frac{\cos 3t}{3^2} + \dots \right)$$

- The term in  $\cos nt$  in the series for  $r(t)$  is:

$$\frac{4}{n^2 \pi} \cos nt.$$

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## Forced oscillations

- Look at the original equation for this  $\cos nt$  term:

$$\ddot{y} + 4y = \frac{4}{n^2 \pi} \cos nt.$$

- The particular integral is of the form:

$$y_p = A_n \cos nt + B_n \sin nt$$

$$\Rightarrow \dot{y}_p = -nA_n \sin nt + nB_n \cos nt$$

$$\text{and } \ddot{y}_p = -n^2 A_n \cos nt - n^2 B_n \sin nt.$$

- Equating coefficients gives:

$$A_n = \frac{4}{n^2 \pi (4 - n^2)} \text{ and } B_n = 0.$$

- Since the complete force term is the sum of  $\cos nt$  terms for  $n = 1, 3, 5, \dots$  the full particular integral  $y_p$  will be the sum of terms  $y_1, y_3, y_5, \dots$

- That is:

$$y_p = \frac{4}{\pi} \left( \frac{\cos t}{1^2(4-1^2)} + \frac{\cos 3t}{3^2(4-3^2)} + \frac{\cos 5t}{5^2(4-5^2)} \dots \right)$$

- The solution of the homogeneous equation is:  $y_c = A \cos 2t + B \sin 2t$ .

- The full solution is  $y = y_c + y_p$ :

$$y = A \cos 2t + B \sin 2t +$$

$$\frac{4}{\pi} \left( \frac{\cos t}{1^2(4-1^2)} + \frac{\cos 3t}{3^2(4-3^2)} + \frac{\cos 5t}{5^2(4-5^2)} \dots \right).$$

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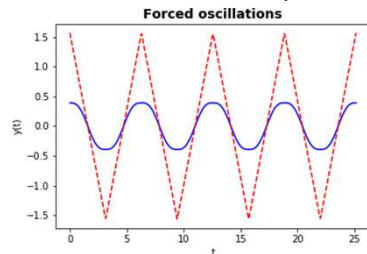
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## Forced oscillations

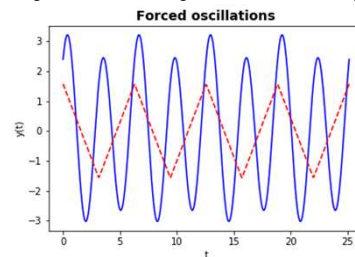
- We see the force term excites a spectrum of oscillations with amplitudes that decrease with frequency.

- There is no friction; initial conditions influence the oscillations for all  $t$ .

- If motion due to force only:



- Motion including component due to a particular initial position and velocity.



- Friction would cause component due to initial motion to die out, leaving only that due to the force.

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## Resonance

- What happens if we change the spring constant?

- If the chosen value means that the natural frequency of the system is the same as one of the frequencies in the force term, resonance occurs.

- E.g. pick  $k = 25$ .

- Then  $y_c = A \cos 5t + B \sin 5t$ .

- In the particular integral, we now have to use  $y_p = A_5 t \cos 5t + B_5 t \sin 5t$ , as  $y_c$  already contains  $\cos 5t$  and  $\sin 5t$  terms.

- We can see this frequency component ("mode") has an amplitude that grows with time, there is a "resonance".

- If there is no (or only little) friction, this mode can become large: the results can be quite interesting!

- [Tacoma narrows bridge collapse.](#)

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