First full calibration and reconstruction of a HEP detector in real time





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Detector Seminar, October 9th 2015

How operational works convert into physics: novel concepts in LHCb





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Layout

- Why operation is so important?
- The LHCb experiment
- The challenge: maximize online performance, aka having potentially the same performance online and offline
 - New resources
 - Improved reconstruction chain
 - Calibration and alignment on the online farms
- How it converts into physics:
 - The Turbo stream and the early measurements

THE goals for a particle physicist



Discovery of new physics

Precise measurements

Better understanding of how the reality/universe is made







 Physics analysis can improve (multivariate selections, complex background descriptions, new analysis techniques, ...)

But also more data are often needed/useful!



Operation



The LHCb experiment



- LHCb is the dedicated heavy flavor physics experiment at LHC
- Single arm forward spectrometer, covering a pseudorapidity range unique among the LHC detectors
- Its primary goal is to look for indirect evidence of new physics in CP-violation and rare decays of beauty and charms hadrons
- This requires:
 - 1. Excellent tracking (momentum, impact parameters and primary vertex resolution)
 - 2. Excellent decay time resolution
 - 3. Excellent particle identification

The tracking systems



Vertex Locator (VELO)



Vertex Locator (VELO):

- 42 silicon micro-strip stations with r-Phi sensors
- Surrounding interaction point
- Two retractable halves, 8 mm from beam when closed
 - Closed when is declared "stable beam"
- Possibility to inject gas (like He, Ne, Ar) for special data taking



Performance of the LHCb Vertex Locator JINST 9 (2014) 09007

LHCb Detector Performance Int.J.Mod.Phys. A30 (2015) 1530022

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LHCb Detector Performance Int.J.Mod.Phys. A30 (2015) 1530022

VELO performance in Run I



Tracker Turicensis (TT)



LHCb Detector Performance Int.J.Mod.Phys. A30 (2015) 1530022



Tracker Turicensis (TT):

- Four planes (0°,+5°,-5°,0°) of silicon microstrip sensor
- Total silicon area of 8m²
- The detector operate at 0°C.
- Upstream of the magnet
- Already sensitive to the magnetic field

Inner and Outer Trackers (IT and OT)



Inner Tracker (IT):

- Downstream of the magnet
- Three stations each with four planes of silicon micro-strip sensors around the beam pipe
- Total silicon area of 4.2m²
- The detector operate at 0°C.

Outer trackers (OT)

- Downstream of the magnet
- Three stations each with four planes of straw tubes
- Gas Mixture Ar/CO₂/O₂ (70/28.5/1.5)





Performance of the LHCb Outer Tracker

<u>JINST 9 (2014) P01002</u>

LHCb Detector Performance Int.J.Mod.Phys. A30 (2015) 1530022

Tracking performance

- Stable tracking efficiency in Runl
- Above 96% in all the momentum range for track traversing the full detector

Resonance	Mass resolution (MeV/ c^2)
J/ψ	14.3 ± 0.1
$\psi(2S)$	16.5 ± 0.4
$\Upsilon(1S)$	42.8 ± 0.1
$\Upsilon(2S)$	44.8 ± 0.1
$\Upsilon(3S)$	48.8 ± 0.2
Z^0	1727 ± 64





The PID systems





Ring Imaging CHerenkov detectors (RICH1 and RICH2)

- RICH1:
 - Upstream of the magnet
 - C₄F₁₀ radiator
 - 2<p<40 GeV/c
 - 25-300 mrad

• RICH2:

- Downstream of the magnet
- CF₁₀ radiator
- 15<p<100 GeV/c
- 15-120 mrad

Performance of the LHCb RICH detector Eur.Phys.J. C73 (2013) 2431

LHCb Detector Performance Int.J.Mod.Phys. A30 (2015) 1530022

The trigger and PID systems



The trigger and PID systems

Electromagnetic and hadronic calorimenters (ECAL and HCAL)

- Scintillator planes + absorber material planes
- Provide the Level O signature for events with hadrons above a certain ${\rm E}_{\rm T}$
- Offline PID for photons, electrons and hadrons



Muon multi-wire proportional chambers



Performance of the Muon Identification system JINST 8 (2013) P10020

Muon system

- 5 stations, each equipped with 276 multi-wire proportional chambers
 - Inner part of the first station equipped with 12 GEM detectors
- Level 0 trigger selection of tracks with high $\ensuremath{p_{\text{T}}}$
- Offline PID of muons

LHCb Detector Performance

Int.J.Mod.Phys. A30 (2015) 1530022 ¹⁸

The PID performances



Capability to distinguish particles (especially π -K) in a the momentum range 2-100 GeV/c)



Eur.Phys.J. C73 (2013) 2431

Kaon identification efficiency ~95% with a pion mis-idenfication fraction of ~10% over the full 2-100GeV/c momentum range (tight selection)



Electron identification efficiency >91% with a hadron mis-idenfication fraction of few % p>10 GeV/c (intermediate selection)

Trigger in Runl

• Level 0: 1MHz rate

- Implemented in hardware
- High p_T and E_T signature in muon and calorimeter systems
- Higher Level Trigger (HLT): 5kHz rate
 - Flexible software triggers with two stages (HLT1 and HLT2)
 - Track reconstruction and PV finding performed
 - Simplified reconstruction w.r.t. offline
 - Preliminary alignment and calibration
 - RICH PID info marginally used (notfully calibrated system)
- Processing of the data at the end of the year with the latest constants
- Only 20% deferred to disk

JINST 8 (2013) P04022

15 MHz bunch crossing rate



Idea

Novel concept in HEP: Being able to do physics directly on the HLT output

Advantages:

- No need of offline data processing (data available ~ immediately after HLT2 has processed them)
- Raw event size can be much smaller → possibility to reduce the pre-scaling of high branching ratio channels (like for charm physics)

Do much more physics with the given resources!

Trigger in Runll

- Events from lower trigger levels can be buffered on disk while performing real-time alignment and calibration
- Last trigger level uses the same reconstruction as offline
- Same alignment and calibration constants used by the trigger and the offline reconstruction
- Some analysis performed directly on the trigger output



New resources

- HLT farm nearly doubled from Run I:
 - ~27k physical cores
 - Farm nodes added for RunII are about 2x more powerful than previous nodes
- Event can be buffered after HLT1: 5PB disk space

Still a difficult challenge:

- Managing to do the full reconstruction in few hundreds ms achieving offline performance (same or better than in Runl)
- Managing to do the full alignment and calibration of the detectors in real-time
- Being able to select efficiently many signals already at trigger level

Reconstruction chain optimization



- In order to maintain full reconstruction efficiency, while keeping within a strict timing budget many improvements were needed:
 - 1. Optimization of the code (e.g. vectorization)
 - 2. Changes to the reconstruction chain and optimization of the pattern algorithm

1. Optimization of the code (e.g. vectorization):



Examples

- Identified hot spots by profiling
 - Vectorisation (track fit, magnetic field)
- Caching (material description)
- Fast approximations
- Algorithms tuning and re-implementation

=> Possible to gain order of ~30% in several algorithms

- 2. Changes to the reconstruction chain and optimization of the pattern algorithm:
- Velo tracks can be extended to the TT detector

Advantages:

- The TT detector is already in the magnetic field: possible to estimate q/p (resolution ~15%)
- Momentum estimate used to preselect tracks at an early stage
- Charge estimate allows greatly reduced search windows downstream of the magnet





New reconstruction chain:

- ~3 times faster
- Better or equivalent performance as in Run I
- Tracks with a p_T>500MeV already available at HLT1 level (in Run I p_T>1.3 GeV) without any IP requirements needed.

• Gains >50% signal efficiency for charm physics

 Enable lifetime unbiased triggers for hadronic final states (world first!)

VELO-TT performance:

- More than 97% efficient for tracks with p_T>200 MeV that have hits in at least three layers
- ~5% better performance than previous code (never used since it was too slow)



The new chain at work

- IP resolution comparable with 2012 data
- Stable between different fills
- Compatible results with 50 and 25 ns data



Tracking efficiency comparable with 2012 data



Comparable resolution to Run I for the PV reconstruction with 70% smaller fraction of fake primary vertices

Still a difficult challenge:

- Managing to do the full reconstruction in ... achieving offline performance (same or better than in Runl): DONE!
- Managing to do the full alignment and calibration of the detectors in real-time
- Being able to select efficiently many signals already at trigger level

Real-time alignment and calibration



Importance of the alignment (I)

- Physics performance relies on the spatial alignment of the detector and the accurate calibration of its subcomponents:
 - 1. Accurate alignment of the VELO essential for primary vertices discrimination, excellent impact parameter (IP) and proper time resolution



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Importance the alignment (II)

- Physics performance relies on the spatial alignment of the detector and the accurate calibration of its subcomponents:
 - 2. Better alignment of the tracking system improves the mass resolution



Importance of the calibration

- Complete calibration of the RICH detectors needed for exclusive selection using hadron particle identification criteria
 - Improve purity and mass resolution
 - PID requirements allows exclusive selection and optimization of the rate



Real-time Alignment and Calibration(I)

- General Strategy
 - Automatic evaluation at regular intervals, e.g. per fill or per run depending on the task
 - Dedicated data sample to perform alignment or calibration collected with specific trigger selection line for each task
 - Compute the new alignment or calibration constants in few minutes
 - Update the constants only if needed
 - The same new alignment and calibration constants will be used both by the trigger and the offline reconstruction

Advantages:

- Have the same performance online and offline
- More effective trigger selection
- Stability of the alignment quality, hence physics performance
- Some analysis performed directly on the trigger output

Real-time Alignment and Calibration(II)

- Technicalities:
 - Constants expected to change: updated in real-time (each fill, run, ...)
 - Constants expected to be stable: monitoring
 - Took advantage of the farm computing power



Calibration Farm tasks:

- RICH refractive index and HPD image calibration
- Calorimeter calibration
- OT-t₀ calibration

Online Farm tasks:

- VELO and tracker aligment
- Muon alignment
- RICH mirror alignment
- Calorimeter π^0 calibration


Calibration Farm

Online Farm

- Tasks are run on a single node
- Evaluation of the parameters by fitting online-monitoring histogram



Calibration Farm

- Tasks are run on a single node •
- Evaluation of the parameters by fitting monitoring histogram

Online Farm

- Parallel processing on ~1700 HLT farm nodes
- Evaluation of the parameters by iterative process
 - Analyser (multiple nodes): perform reconstruction
 - Combination of output, fits/ minimization -> extract constants

- Technicalities:
 - Constants expected to change: updated in real-time (each fill, run, ...)
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VELO, Tracker and Muon alignment: logic

- ♦ Uses an iterative procedure to minimise the residuals of a Kalman fit to a sample of reconstructed tracks
- Multiple scattering and magnetic field are taken into account and both particle masses and information from vertices are used as global constraints



VELO, Tracker and Muon alignment: at work

- Automatic alignment procedure runs at the start of each fill
 - → update of the constants only if necessary
 - VELO: is opened and closed each fill.
 - Updated each 2-3 fills
 - Tracking systems (TT, IT, OT)
 - Updated mainly after the magnet polarity
 - Muon system
 - Only as monitoring (expected to vay only after hardware interventions to the system)



VELO, Tracker and Muon alignment: Runl vs Run II

Run I

- Run offline few times per year (and updated online)
- Time needed to run offline ~1h
- Data taken with a previous version of the alignment -> not best conditions used in HLT
- New alignment updated offline for the re-processing of the data

Run II

- Run every fill and constants automatically updated if needed
- Time needed ~7 minutes
- HLT always with the most updated constants
- Offline synchronized with online parameters

- Technicalities:
 - Constants expected to change: updated in real-time (each fill, run, ...)
 - Constants expected to be stable: monitoring
 - Took advantage of the farm computing power



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RICH Mirror alignment: logic

- Cherenkov photons focused on photon-detector plane by spherical and flat mirrors
- An imaginary track reflected through the RICH mirrors should be in the center of the Cherenkov ring
- The distribution of the $\Delta\theta$ against ϕ results in a sinusoidal distribution in case of misalignment of the mirrors
- Fit the distribution to calculate alignment constants



RICH mirror alignment: at work

- Mirror pairs to align:
 - RICH1: 16
 - RICH2: 94
- 1090 alignment constants
- Re-optimization of the code and HLTselection of the high momentum tracks to be run in the online environment
- Same framework as the tracking alignment:
 - Analysers: photon reconstruction done in parallel
 - Iterator: fit of the $\Delta \theta$ distribution on a single node
- Used as monitoring (if enough ۲ statistics available potentially each fill)









RICH mirror alignment: Runl vs Run II

Run I

- Run offline few times per year
- Time needed to run offline ~several days on the GRID
- Minimal usage of RICH information at HLT level (not fully calibrated system)
- New alignment updated offline for the re-stripping of the data

Run II

- Re-optimized code
- Run as soon as enough statistics is accumulated (typically 1-2 fills)
- Time needed ~30 minutes
- RICH information can be used in HLT: fully calibrated system
- Used as monitoring

- Technicalities:
 - Constants expected to change: updated in real-time (each fill, run, ...)
 - Constants expected to be stable: monitoring
 - Took advantage of the farm computing power



Calibration Farm tasks:

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Online Farm tasks:

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- RICH mirror alignment
- Calorimeter π^0 calibration

RICH calibration: logic

- RICH automatic calibration consists of calibrating:
 - 1. RICH refractive index:
 - Depends on the gas mixture, temperature and pressure
 - Determined by fitting the difference between reconstructed and expected Cherenkov angle
 - Hybrid photon detector (HPD) images
 - Affected by the magnetic and electric fields distortions
 - Anode images cleaned and Sobel filter is used to detect the edges



RICH calibration: at work

Fully automatic procedure, evaluated run by run

- In case of a too short run, the same constants of the previous run are used
- Calibration parameters are monitored by PVSS trend plots
- Maintained stable conditions during 2015 data taking

Stability of cherenkov angle resolution



- Technicalities:
 - Constants expected to change: updated in real-time (each fill, run, ...)
 - Constants expected to be stable: monitoring
 - Took advantage of the farm computing power



Calibration Farm tasks:

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Online Farm tasks:

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- Muon alignment
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Calorimeter calibration: logic

- Important to have stable L0 rates
- It allows to account for ageing effects
- The calibration adjust directly the HV settings
- Absolute calibrations:
 - $-\pi^0$ calibration:
 - Selected photons (3x3 clusters) and fix seed (central) cell
 - Compute di-photon invariant mass
 - Find the coefficient which would move the measurement closer to the nominal $\pi^0\,\text{mass}$
 - Cs source scan:
 - Scan of the response with the source. Done each TS
- Relative calibrations:
 - Raw occupancy method:
 - Comparison of the performance of each cell with a reference
 - LED monitoring system:
 - To detect ageing of the PMTs

Calorimeter calibration: at work

- The LED corrections for ECAL and HCAL are automatically performed/updated every fill
 - ~15 minutes to have the corrections available
- Commissioning of the occupancy method ongoing: waiting for stable beam conditions (not available in Runl)
- π^0 calibration done every months: now it takes only few hours to produce the results





- Technicalities:
 - Constants expected to change: updated in real-time (each fill, run, ...)
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OT-t₀ calibration: logic

<u>JINST 9 (2014) P01002</u>

- Global time offset (t₀) related to the synchronization between the OT time and the collision time -> a shift of 0.5 ns leads to tracking inefficiency of ~0.25%
- Calculate t0 for the entire OT (real-time update)
- The offset is evaluated by using the reconstructed tracks, and comparing the drift time with the expected drift time (evaluated using the TR-relation)



OT-t0 calibration: at work

- Executed every fill, update expected every few weeks
- Automatic evaluation and update of the constants worked from day one!!!
- Added for monitoring purpose the t0-calibration per chip (4-each module).



Still a difficult challenge:

- Managing to do the full reconstruction in ... achieving offline performance (same or better than in Runl): DONE!
- Managing to do the full alignment and calibration of the detectors in real-time : DONE
- Being able to select efficiently many signals already at trigger level

Selection power at trigger level

- Same reconstruction as offline and complete alignment and PID calibration allows to apply a tighter selection on kinematics quantities
- RICH calibration allows to use hadron particle identification in selection, e.g. boost efficiency for Cabibbo suppressed decays while keeping the rate low by pre-scaling the Cabibbo favored counterpart



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Trigger performance in Run II

- Improvement of the trigger efficiency thanks to e.g.
 - Run the same offline reconstruction in HLT2
 - Having the detector fully calibrated and aligned
 - Using PID selection in the trigger



Efficiency of the HLT2 inclusive beauty trigger as a function of B p_T

Still a difficult challenge:

- Managing to do the full reconstruction in ... achieving offline performance (same or better than in Runl): DONE!
- Managing to do the full alignment and calibration of the detectors in real-time : DONE
- Being able to select efficiently many signals already at trigger level : DONE!

Ready to do physics from the HLT output!



The TURBO Stream

- Store HLT candidate information
- Remove detector raw data
- Save ~90% of space
- Idea for analysis with large yields: possible to reduce the pre-scaling of all the channels that were trigger output rate constraint -> more physics possible!
- ~24h turn-around from data taking to analysis
- Real challenge relying on the good operational performance: no 2nd chance of reprocessing to fix problems



The TURBO Stream at work: the early measurements

Used for early measurement cross-section

Results presented 1 week after their acquisition!

Example J/ψ cross-section <u>ArXiv 1509.00771</u> accepted by JHEP

- The trigger found 10⁶ J/ψ->μ⁺μ⁻ in
 3.03 ± 0.12 pb⁻¹ with J/ψ p_T<14
 GeV/c and 2<y<4.5
- No offline processing: mass resolution of ~12MeV/c² compatible with RunI data



Last year we had 4 kHz of TURBO charm, and for the same disk space you would normally then only be able to take 400 Hz, which is actually less than just the D->Kπ and D->Kππ signal rates!

SMOG system

- System to inject gas in the VELO region
 - LHCb is able to do fix target physics (unique opportunity at LHC)
 - Possibility to have a second method to measure the luminosity
 - Traditional Van der Meer scans: with LHC moving the beams with respect to each other in small steps
 - Beam Gas Imaging Method with SMOG to reconstruct beam shape at the interaction point

SMOG: System for Measuring the Overlap with Gas



Best precise measurement of the luminosity at LHC with 1.1% of uncertainty in Run I

[JINST 9 (2014) 12, P12005]

For EM delivered a luminosity measurement with 3.8% of uncertainty in few weeks

Beam gas collisions

- Exploiting the SMOG system with different noble gases: Ar, He, Ne
- Physics motivations:
 - Input to the understanding of nucleus-nucleus collisions
 - Sensitive probes of nuclear structure
 - Measurement of σ(pHe→pX). the largest uncertainty in the AMS results showing antiproton excess is due to the theoretical precision of the production σ(pHe→pX)
 [AMS-02 Coll., CERN 15.04.2015]
 - Probe quark gluon plasma (QGP)
 - Reference sample for heavy ion collisions



	√S	Date in 2015	Data sample
pNe	110.4GeV	25-26 Aug.	2 fills (~13h)
рНе	110.4GeV	8 Sept.	1 fill (~8 h)
pAr	110.4GeV	15-18 Oct.	7 fills(~29 h)

Conclusions

- LHCb is the first HEP experiment with a full calibration, alignment and reconstruction done in real-time
- Provided new calibration and alignment constants for each run or fill in few minutes
- Possible to monitor in few hours quantities that in Run I were monitored only few times in a year (like during TS)
- System fully commissioned in 2015 showing stable performance. Final tuning for stable running in 2016.
- The Turbo Stream allowed to:
 - Increase the physics reach by saving more data in less space (important for high branching ratio channels)
 - Physics analysis doable ~24h after the data taking
- First measurement of the luminosity at 13TeV with only 3.8% of uncertainty (thanks to the Beam Gas Imaging Method) in few weeks from the data taking!
- First cross-section measurements presented at summer conferences few weeks after the data taking



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The LHCb experiment

- LHCb is the dedicated heavy flavor physics experiment at LHC
- Its primary goal is to look for indirect evidence of new physics in CP-violation and rare decays of beauty and charms hadrons
- This requires:
 - 1. Excellent tracking (momentum, impact parameters and primary vertex resolution)
 - 2. Excellent decay time resolution
 - 3. Excellent particle identification



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RICH2: more complicated For a given secondary mirror several primary mirrors possible -> solve a set of simultaneous equations per half of RICH2



Trigger in Runll

- Events from lower trigger levels can be buffered on disk while performing realtime alignment and calibration
- Last trigger level uses the same reconstruction as offline
- Same alignment and calibration constants used by the trigger and the offline reconstruction
- Some analysis performed directly on the trigger output



RICH calibration: logic

- RICH automatic calibration consists of calibrating:
 - RICH refractive index:
 - Depends on the gas mixture, temperature and pressure
 - Determined by fitting the difference between reconstructed and expected Cherenkov angle
 - Hybrid photon detector (HPD) images
 - Affected by the magnetic and electric fields distortions
 - Anode images cleaned and Sobel filter is used to detect the edges

Fully automatic procedure, evaluated run by run

- In case a too short run, the same constants of the previous run are used
- Calibration parameters are monitored by PVSS trend plots

Optimization of the reconstruction chain

- In order to maintain full reconstruction efficiency, while keeping within a strict timing budget many improvements were needed:
 - Optimization of the code (e.g. vectorization)
 - Changes to the reconstruction chain and optimization of the pattern algorithm



Example

- Improved sequence forming VeloTT tracks as an intermediate stage
- Availability of a momentum estimate to pre-select tracks at an early stage
- Charge estimate allows greatly reduced search windows downstream of the magnet
 - Factor of 4 less ghost rate
 - Factor of 3 reduction in execution time
- Tracks with a p_T>500MeV already available at HLT1 level (in Run I p_T>1.3 GeV) without any IP requirements needed.

VeloTT algorithm



- Linearly extrapolate VELO track to TT
- Select hits within a search window around the extrapolated track
- Form doublets of hits in the first two layers
- Extrapolate doublets to third/fourth layers and search for compatible hits
- If no four hit candidates found, repeat in starting from last two layers
- Fit each track candidate with a χ^2 fit and estimate q/p ($\delta p/p \sim 15\%$)
- Choose best candidate track based on # layers fired and χ^2
- More than 97% efficiency for tracks with $p_T > 200 \text{MeV}$ that hit at least 3 layers
 - Not total coverage of the LHCb acceptance by the TT detector: needed to recover tracks not leaving enough hits in the TT detector.

Calorimeter and Muon systems performance

Electron identification efficiency >91% with a hadron mis-idenfication fraction of few % p>10 GeV/c (intermediate selection)







Muon efficiency >95% for almost all the p_T bins in the full momentum range

Int.J.Mod.Phys. A30 (2015) 1530022
The PID performances

Capability to distinguish particles (especially π -K) in a the momentum range 2-100 GeV/c)





Kaon identification efficiency ~95% with a pion mis-idenfication fraction of ~10% over the full 2-100GeV/c momentum range (tight selection)

Eur.Phys.J. C73 (2013) 2431

Server nodes

All servers in the EFF are dual-socket x86 servers. The overwhelming majority uses Intel processors but there are also a few AMD based systems. In the following tables some characteristics of these servers are given. All these servers are physically quad-servers, where 4 servers are installed in a single 2U chassis. They have between 1 and 2 GB of RAM per physical core.

	CPU type	Moore/s	SpecIntRate2006	number of physical cores	number of logical cores	total RAM	local harddisk space	number of units
DELL C6100	Intel x5650	650	36	12	24	24	2 TB	520
Action Solar 820 S4	Intel x5650	630	36	12	24	24	2 TB	400
ASUS RS720QA-E6- RS12	AMD 6272	680	32	23	32	32	2 TB	100
Intel S2600KP	Intel E5- 2630v3	980	56	16	32	32	4 TB	800

Gain for b-physics

 Ratio of Runll over Runl for HLT2/HLT1 efficiencies. Note that the denominator is reconstructible with p_T(B)>2 GeV, τ(B)>0.2ps

mode	$2.5~\mathrm{kHz}$
$\overline{B^0 \to K^*[K^+\pi^-]\mu^+\mu^-}$	1.64
$B^+ \to \pi^+ K^- K^+$	1.59
$B_s^0 o D_s^- [K^+ K^- \pi^-] \mu^+ u_\mu$	1.14
$B_s^0 \to \psi(1S)[\mu^+\mu^-]K^+K^-\pi^+\pi^-$	1.62
$B_{s}^{0} \rightarrow D_{s}^{-}[K^{+}K^{-}\pi^{-}]\pi^{+}$	1.46
$B^{0} \to D^{+}[K^{-}\pi^{+}\pi^{+}]D^{-}[K^{+}\pi^{-}\pi^{-}]$	1.40

Tracking efficiency from data





JINST 10 (2015) P02007

Figure 2. Illustration of the three tag-and-probe methods: (a) the VELO method, (b) the T-station method, and (c) the long method. The VELO (black rectangle), the two TT layers (short bold lines), the magnet coil, the three T stations (long bold lines), and the five muon stations (thin lines) are shown in all three subfigures. The upper solid blue line indicates the tag track, the lower line indicates the probe with red dots where hits are required and dashes where a detector is probed.

VeloTT speedup



transition from PatVeloTT to PatVeloTTHybrid: almost factor 40 speedup!

Refractive index calibration RICH1



Before alignment

After alignment



Luminosity measurement

- In LHCb two techniques used to measure the luminosity:
 - Traditional Van der Meer scans: with LHC moving the beams with respect to each other in small steps
 - Beam Gas Imaging Method with SMOG to reconstruct beam shape at the interaction point
- The combination of the two techniques allowed in RunI to achieve the **best precise measurement** of the luminosity **at LHC** with **1.1%** of uncertainty [<u>JINST 9 (2014) 12, P12005</u>]
- Only beam gas imaging method available for the EM timescale
- Delivered a luminosity measurement with 3.8% of uncertainty in few weeks (measurement 10th of June, first results presented at EPS the 22th of July)
- Further analysis to combine the two methods ongoing



Only HLT1 is used for this measurement: the new HLT split allowed to write very fast data to disk increasing the precision of the measurement (~1%)

RICH calibration: logic

- RICH automatic calibration consists of calibrating:
 - 1. RICH refractive index:
 - Depends on the gas mixture, temperature and pressure
 - Determined by fitting the difference between reconstructed and expected Cherenkov angle



Before alignment



After alignment

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RICH calibration: logic

- RICH automatic calibration consists of calibrating:
 - 2. Hybrid photon detector (HPD) images
 - Affected by the magnetic and electric fields distortions
 - Anode images cleaned and Sobel filter is used to detect the edges



Exclusive hadron selections (*PID*) requires the full calibration of the RICH detectors.

- Improve purity and mass resolution
- Higher performances of online selection, especially for tighter selection (e.g. exclusive selection of $D^0 \rightarrow K^- \pi^+$ candidates).





IDEA: trying to push the online performance to the quality of the offline one



Do much more physics with the given resources!

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